

SUPPORTING SPHERES FOR FAMILIES
OF SETS IN PRODUCT SPACES

by

HORST KRAMER

(Cluj)

Let M be a given set in the n -dimensional Euclidean space R^n . We shall denote by $\text{conv } M$ the convex hull of M , i.e. the intersection of all convex sets in R^n which contain the set M . In the following we need the notion of convexly connected sets introduced by O. HANNER and H. RADSTRÖM in [5].

Definition 1. A set M in R^n is called convexly connected, if there is no hyperplane H such that $H \cap M = \emptyset$ and M contains points in both the open halfspaces determined by H .

Remark. The notion of convexly connected sets is used in [8] also with an other meaning.

It is easy to verify that a connected set is also convexly connected and that the union of convexly connected sets having a point in common is convexly connected.

Definition 2. Let M be a set in R^n . A maximal convexly connected subset of M will be called a convexly connected component of M .

O. Hanner and H. Radström have shown that there is a unique decomposition of a set M into convexly connected components. They have also proved the following result ([5], corollary 1): If $M \subset R^n$ is compact and has almost n convexly connected components, then for each point p in $\text{conv } M$ there exist n (or fewer) points a_1, a_2, \dots, a_n of M such that p belongs to $\text{conv } \{a_1, a_2, \dots, a_n\}$.

H. KRAMER and A. B. NÉMETH have given in [6] the following two definitions:

Definition 3. There will be said that the family F of sets in a metric space E has a supporting sphere, if there is a sphere S in E having

common points with each member of the family F and the interior of S contains no point of any member of F .

Definition 4. A family F of sets in R^n is said to be independent if for any $n + 1$ pairwise distinct members K_1, K_2, \dots, K_{n+1} of F any set of points p_1, p_2, \dots, p_{n+1} , where $p_i \in K_i, i = 1, 2, \dots, n + 1$, determines a simplex of dimension n , or equivalently the vectors $p_2 - p_1, p_3 - p_1, \dots, p_{n+1} - p_1$ are linearly independent. An equivalent condition is: p_1, p_2, \dots, p_{n+1} are in general position (see [3], p. 12 definition 5).

A family F of sets is independent if and only if there is no hyperplane which intersects $n + 1$ (or more) members of F .

THEOREM 1. Let $F = \{K_i : i \in I\}$ be a family of independent compact convexly connected sets in R^n . Then

$$F_{\text{conv}} = \{\text{conv } K_i : i \in I\}$$

is a family of independent compact sets.

Proof. The sets K_i are compact by the theorem of Mazur (see for instance [7], theorem 3.2.18). Suppose now that the family F_{conv} is not independent. Then there exist $n + 1$ members of F_{conv} , say $\text{conv } K_i, i = 1, 2, \dots, n + 1$, which are not independent. Let be H a hyperplane for which $H \cap \text{conv } K_i \neq \emptyset, i = 1, 2, \dots, n + 1$. Let be $a_i \in H \cap \text{conv } K_i, i = 1, 2, \dots, n + 1$. Because K_i is convexly connected and a_i is in $\text{conv } K_i$, by the theorem of O. Hanner and H. Radström there are n points $a_1^{(i)}, a_2^{(i)}, \dots, a_n^{(i)}$ in K_i such that

$$(1) \quad a_i \in \text{conv } \{a_j^{(i)} : j = 1, 2, \dots, n\}.$$

We have also $a_i \in H$. Let us now suppose $H \cap K_i = \emptyset$. The hyperplane H determines in R^n two open halfspaces H' and H'' . By (1) and by our supposition $H \cap K_i = \emptyset$ follows then $H' \cap K_i \neq \emptyset$ and $H'' \cap K_i \neq \emptyset$.

This contradicts the property of K_i to be convexly connected. Therefore $H \cap K_i \neq \emptyset, i = 1, 2, \dots, n + 1$. This is in contradiction with the independence of the family F . That completes the proof of our Theorem.

Remark. The hypothesis that the sets K_i are convexly connected is essential. Let be $a_i, i = 1, 2, \dots, n$, n linearly independent points in R^n and let be H the hyperplane determined by these n points. Choose 2 points b_1 and b_2 on opposite sides relative to H . Consider now $K_i = \{a_i\}, i = 1, 2, \dots, n$ and $K_{n+1} = \{b_1, b_2\}$. Of course $\{K_1, K_2, \dots, K_{n+1}\}$ is a family of independent sets, but this cannot be said about the family $\{\text{conv } K_1, \dots, \text{conv } K_{n+1}\}$.

In the proof of theorem 1 it is not necessary to use the theorem of Hanner-Radström. The proof can be made also with the well-known theorem of Caratheodory on the convex hull of a compact set (see [1]).

Lemma 1. Let be K_1, K_2, \dots, K_{n+1} independent convex sets in R^n , and let be $a_i, b_i \in K_i, i = 1, 2, \dots, n + 1$. Then

$$\text{conv } \{a_1, a_2, \dots, a_{n+1}\} \cap \text{conv } \{b_1, b_2, \dots, b_{n+1}\} \neq \emptyset.$$

Proof. Let us suppose

$$\text{conv } \{a_1, a_2, \dots, a_{n+1}\} \cap \text{conv } \{b_1, b_2, \dots, b_{n+1}\} = \emptyset.$$

By the theorem on the separation of polyhedra (see [7], p. 68 theorem 2.12.9) the two simplexes $\text{conv } \{a_1, a_2, \dots, a_{n+1}\}$ and $\text{conv } \{b_1, b_2, \dots, b_{n+1}\}$ can be separated by a hyperplane H . From the convexity of K_i , from $a_i, b_i \in K_i$ and from the fact that a_i and b_i are on opposite sides relative to H , follows $H \cap K_i = \emptyset$, in contradiction with the independence of the family $\{K_1, \dots, K_{n+1}\}$. This completes the proof of the lemma.

Lemma 2. Let be $C_i, i = 1, 2, \dots, n + 1$ independent compact convexly connected sets in R^n . If $a_i, b_i \in \text{conv } C_i, i = 1, 2, \dots, n + 1$ then: $\text{conv } \{a_1, a_2, \dots, a_{n+1}\} \cap \text{conv } \{b_1, b_2, \dots, b_{n+1}\} \neq \emptyset$.

By theorem 1 follows the independence of the sets $\text{conv } C_i, i = 1, 2, \dots, n + 1$. Then lemma 2 follows immediately from lemma 1.

The following theorem was proved in [6] by H. KRAMER and A. B. NÉMETH:

THEOREM 2. Let be K_1, K_2, \dots, K_{n+1} independent convex and compact sets in R^n . Then this family admits one and only one supporting sphere.

Let now E_1, E_2 be two metric spaces with the distances d_1, d_2 on E_1 respectively E_2 . In $E_1 \times E_2$ can be defined two distances d' and d'' in the following way: For any pair of points $x = (x_1, x_2), y = (y_1, y_2)$ let:

$$d'(x, y) = d_1(x_1, y_1) + d_2(x_2, y_2)$$

and

$$d''(x, y) = ((d_1(x_1, y_1))^2 + (d_2(x_2, y_2))^2)^{1/2}.$$

Denote by E' respectively E'' the corresponding metric spaces.

THEOREM 3. Let $F_1 = \{A_i : i \in I\}$ and $F_2 = \{B_j : j \in J\}$ be families of compact sets in the metric space E_1 respectively E_2 . The family of compact sets $F_{12} = \{A_i \times B_j : i \in I, j \in J\}$ in E' (respectively E'') has a supporting sphere if and only if the family F_1 has a supporting sphere in E_1 and the family F_2 has a supporting sphere in E_2 .

Proof. We shall prove our theorem only in the case when F_{12} is considered as a family of compact sets in E'' . The other case may be treated in the same way. The compactness of the members of F_{12} in E'' (respectively in E') follows from ([2] p. 72, theorem 3.20.16).

Necessity. Suppose that F_{12} has a supporting sphere in E'' , i.e. there is a point (a_1, a_2) in $E_1 \times E_2$ such that

$$d''((a_1, a_2), A_i \times B_j) = d''((a_1, a_2), A_k \times B_h)$$

for each $i, k \in I$ and $j, h \in J$. We have then in particular

$$(2) \quad d''((a_1, a_2), A_i \times B_j) = d''((a_1, a_2), A_k \times B_j)$$

for a fixed j in J and for all i, k in I . As

$$\begin{aligned} d''((a_1, a_2), A_i \times B_j) &= \min \{d''((a_1, a_2), (x_1, x_2)) : (x_1, x_2) \in A_i \times B_j\} \\ &= \min \{(d_1^2(a_1, x_1) + d_2^2(a_2, x_2))^{1/2} : (x_1, x_2) \in A_i \times B_j\} = \\ &= ((\min \{d_1(a_1, x_1) : x_1 \in A_i\})^2 + (\min \{d_2(a_2, x_2) : x_2 \in B_j\})^2)^{1/2} = \\ &= (d_1^2(a_1, A_i) + d_2^2(a_2, B_j))^{1/2}. \end{aligned}$$

We can then write (2) under the form :

$$d_1^2(a_1, A_i) + d_2^2(a_2, B_j) = d_1^2(a_1, A_k) + d_2^2(a_2, B_j).$$

Hence $d_1(a_1, A_i) = d_1(a_1, A_k)$ for all i, k in I , i.e. the family F_1 has a supporting sphere with the center a_1 . The same reasoning can be applied to show the existence of a supporting sphere for the family F_2 with the center a_2 .

Sufficiency. Suppose that F_i has a supporting sphere in E_i with the center a_i , $i = 1, 2$. Then we have

$$d_1(a_1, A_i) = d_1(a_1, A_k) \quad \text{for all } i, k \text{ in } I$$

and

$$d_2(a_2, B_j) = d_2(a_2, B_h) \quad \text{for all } j, h \text{ in } J.$$

Hence $d''((a_1, a_2), A_i \times B_j) = d''((a_1, a_2), A_k \times B_h)$ for all i, k in I and j, h in J , i.e. the family F_{12} has a supporting sphere in E'' .

THEOREM 4. Let $F_m = \{C_1, C_2, \dots, C_{m+1}\}$ be a family of independent compact convexly connected sets in R^m and $F_n = \{D_1, D_2, \dots, D_{n+1}\}$ a family of independent compact and convexly connected sets in R^n . Then the family

$$F = \{\text{conv } C_i \times \text{conv } D_j : i = 1, 2, \dots, m+1; j = 1, 2, \dots, n+1\}$$

has one and only one supporting sphere in R^{m+n} .

Proof. By theorem 1 follows the independence in the space R^m of the family $F_{m, \text{conv}} = \{\text{conv } C_i : i = 1, 2, \dots, m+1\}$ and the independence in the space R^n of the family $F_{n, \text{conv}} = \{\text{conv } D_j : j = 1, \dots, n+1\}$. By theorem 2 $F_{m, \text{conv}}$ has a unique supporting sphere in R^m and $F_{n, \text{conv}}$ has a unique supporting sphere in R^n . The existence and the unicity of a supporting sphere for the family F follows then from theorem 4.

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*Institutul de calcul din Cluj
al Academiei Republicii Socialiste România*