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A NEW METHOD FOR THE COMPUTATION OF SQUARE ROOT, EXPONENTIAL AND LOGARITHMIC FUNCTIONS THROUGH HYPERBOLIC CORDIC

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§ 1. Introduction

Walther [1] proposed a unified algorithm for elementary functions due to coordinate transformation. In a previous paper [2], the author has discussed mainly the circular case (m = +1) and its application to complex arithmetic.

In the present paper, the author would like to discuss the hyperbolic case (m = -1), in order to give a modified alogrithm for the computation of square root, exponential and logarithmic functions.

§ 2. The principle of CORDIC in the hyperbolic case

In order to make the paper self-contained, we shall begin with the principle of CORDIC in the hyperbolic case.

Let x, y be the real numbers satisfying x > |y|. The hyperbolic coordinates (R, A) of a point P = (x, y) is defined by

$$R = (x^2 - y^2)^{1/2}$$
, $A = \operatorname{arctanh}(y/x)$; $x = R \cosh A$, $y = R \sinh A$.

It is well-known that $R^2A/2$ is the area of the domain surrounded by the x-axis, radius vector OP and the hyperbola $x^2 - y^2 = c$ passing through P (see Fig. 1).

Fig. 1

 $T(\boldsymbol{\delta}_{k}): (\boldsymbol{x}_{k}, \boldsymbol{y}_{k}) \rightarrow (\boldsymbol{x}_{k+1}, \boldsymbol{y}_{k+1}) \text{ by}$ $(1) \qquad T(\boldsymbol{\delta}_{k}): \begin{array}{l} \boldsymbol{x}_{k+1} = \boldsymbol{x}_{k} + \boldsymbol{\delta}_{k} \boldsymbol{y}_{k} \\ \boldsymbol{y}_{k+1} = \boldsymbol{y}_{k} + \boldsymbol{\delta}_{k} \boldsymbol{x}_{k} \end{array}$ which yields in the hyperbolic coordinates $R_{k+1} = R_{k} \times K_{k}, \ K_{k} = (1 - \boldsymbol{\delta}_{k}^{2})^{1/2}$

Now taking a constant $\delta_k(|\delta_k| < 1)$,

we shall apply the linear transformation

$$A_{k+1} = A_k + \alpha_k$$
, $\alpha_k = \operatorname{arctanh} \delta_k$.

We introduce a third variable z and transform is simultaneously with (1) as

 $z_{k+1} = z_k - \alpha_k$

We take a sequence δ_k , and repeat the transformation $T(\delta_1)$, $T(\delta_2)$, ..., $T(\delta_{n-1})$ with (3) starting from the values (x_1, y_1, z_1) until we arrive at (x_n, y_n, z_n) . The final values are given by

(4) $x_{n} = K(x_{1} \cosh \alpha + y_{1} \sinh \alpha)$ $y_{n} = K(x_{1} \sinh \alpha + y_{1} \cosh \alpha)$ $z_{n} = z_{1} - \alpha$

where

(5)
$$K = \prod_{k=1}^{n-1} (1 - \delta_k^2)^{1/2}, \ \alpha = \prod_{k=1}^{n-1} \operatorname{arctanh} \alpha_k.$$

In the practical application, we select one of the following two goals :

I. y or A is forced to be 0.

II. z is forced to be 0.

If the goal was reached at the steps y_n in the case I, we have

(6)
$$x_n = K(x_1^2 - y_1^2)^{1/2}, \ z_n = z_1 + \operatorname{arctanh} \frac{y_1}{x_1} = z_1 + \frac{1}{2} \log \frac{x_1 - y_1}{x_1 - y_1}.$$

Simiarly, if the goal was reached at the step z_n in the case II, we have

(7)
$$x_n = K(x_1 \cosh z_1 + y_1 \sinh z_1),$$
$$y_n = K(x_1 \sinh z_1 + y_1 \cosh z_1).$$

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(8)

Therefore, we may compute square root, exponential and logarithmic functions by the above process.

If there remains very small residues ε at the final step, it is easy to see that the relative errors in (6) or (7) are of order ε , provided that the rounding errors are negligeable. Remark that for x_n in (6), the truncation error is less than $\varepsilon^2/2x_n^2$, which is of higher order than ε .

§ 3. Practice and convergence of CORDIC

In the binary arithmetic, the transformation $T(\delta_k)$ is most easily performed, if we take $\delta_k = +2^{-k}$, where (1) is computed only by addition, subtraction and shifting without actual multiplication.

For convenience, we put

$$arepsilon_k=2^{-k}$$
, $eta_k=$

and select suitably the signature $\delta_k = + \varepsilon_k$. Precisely we take the algorithm

arctanh ε_{k}

if
$$y_k \ge 0$$
 then $\delta_k := -\varepsilon_k$ else $\delta_k := \varepsilon_k$;

in the case I, and

, if
$$z_k < 0$$
 then $\delta_k := -\varepsilon_k$ else $\delta_k := \varepsilon_k$;"

in the case II.

Unfortunately, the constants β_{ks} do not satisfy the convergence criterion of WALTHER [1]:

9)
$$\beta_k - \sum_{j=k+1}^{n-1} \beta_j \leq \beta_{n-1} \quad (k = 1, 2, ..., n-2).$$

In fact, β_k 's satisfy an inequality of *opposite* direction in (9). However, as mentioned in [1] and proved in [2], the inequality (9) is *true* if we add the *correction term* $-\beta_{\mu}$, $l \leq 3k + 1$ in the left hand side of (9). Therefore it is enough to add some modification in order to guarantee the convergence. Probably the simplest way is to *repeat the process once* more with the same values of ε_k and β_k at the k_i -th step $(i \geq 1)$, where

$$k_0 = 1, \ k_i = 3k_{i-1} + 1 \ (i \ge 1), \ i.e., \ k = 4, \ 13, \ 40, \ 121, \ \dots$$

For the usual accuracy less than 11 decimals, it is enough to repeat at k = 4 and 13 only. Precisely speaking, we should write

$$\varepsilon_k = \begin{cases} 2^{-k} & \text{for } 1 \leq k \leq 4 \\ 2^{-(k-1)} & \text{for } 5 \leq k \leq 14 \\ 2^{-(k-2)} & \text{for } 15 \leq k \leq 42 \end{cases}$$

and so on, but we continue use the notation (8).

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An alternate modification will be to insert $\varepsilon' = \frac{3}{4} \varepsilon_k$ and the corresponding value $\varepsilon'_k = \arctan \varepsilon'_k$ at all or necessary steps. We prefer the former one because of the simplicity.

The convergence region in the case II is

(10)
$$|z_1| \leq B = \sum_{k=1}^{\infty} \beta_k + \beta_4 + \beta_{13} + \ldots = 1.117 \ldots$$

and that in the case I is

(11)
$$|y/x_1| \leq \tanh B = 0.806 \dots$$

The values of β_k 's should be preassigned. Remark that β_k may be replaced by ε_k if ε_k^3 is negligeable, and by $\varepsilon_k + \frac{1}{3} \varepsilon_k^3$ if ε_k^5 is negligeable, so that we need rather few constants in the algorithm.

§ 4. Application to square root

It is easy to see that $x_1 = t + c$, $y_1 = t - c$ gives

$$x_n = K(x_1^2 - y_1^2)^{1/2} = (2K\sqrt{c})\sqrt{t}$$

in (6). Hence taking $\sqrt{c} = 1/2K$, we have $x_n = \sqrt{t}$ in (6). Remark that if we need no logarithmic function simultaneously, the variable z and the constants β_k 's are *unnecessary*. Further, by the remark at the end of § 2, we have only to repeat the process with repetetion at k = 4, 13, ...,*until* k = n/2, provided that accuracy of n bits is necessary. The process is as in the flow chart shown in Fig. 2.

The constants are

(12)
$$K = \prod_{k=1}^{\infty} (1 - 2^{-2k})^{1/2} \times \prod_{k=4,13,\ldots} (1 - 2^{-2k})^{1/2}, \ 1/K = 1.2074970806$$

and

 $c = 1/4K^2 = 0.36451229219...$

The convergence region is

(13) $0.1068... = e^{-2B} \leq t/c \leq e^{2B} = 9.348...$

which is surely implies the interval $\{1/4 \leq t \leq 1\}$ or $\{1/16 \leq t \leq 1\}$.

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Repeat the process for $k=1,2,\ldots, n/2$, and at k=4 and 13 repeat twice with same ϵ The assignement for x and y must be performed simultaneously

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 $x = \sqrt{t}$

 $(\epsilon = 2^{-k})$

Fig. 2

In the practical program, it will be better to determined the constant c in such a manner that the residue becomes smallest for various values of t in the interval $\{1/4 \le t \le 1\}$ or $\{1/16 \le t \le 1\}$. For TOSBAC 3400 in our Institute which has 37 bits in mantissa, the optimal value of c is 0.36451229226.

In the practice, it will be better to normalize t in $\{1/8 \le t \le 1/2\}$ in order to avoid overflow in the fix point arithmetic. For that case, there is a modified procedure. Start from k = 2 ($\varepsilon_2 = 1/4$) with c = 0.27233292991(approximately 3/4 of the previous c), and repeat twice with same ε at k = 7($= 2 \times 3 + 1$) instead of 4 and 13. The convergence region is $0.33 \Rightarrow e^{-B'} \le |t/c| \le e^{B'} \Rightarrow 3$, $B' = B - \beta_1$ which surely covers the interval $\{1/8 \le t \le 1/2\}$.

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According to the results of the numerical experiments, it seems interesting that the repetition up to the final bit (until k = 38) gives worse results than to stop at k = 20; the maximal relative error in the first case is nearly 3 times bigger than that in the leatter case.

§ 5. A new algorithm for exponential function

Since $e^{\alpha} = \sinh \alpha + \cosh \alpha$, it will be natural to try to compute e^{α} by CORDIC case II, starting from $x_1 = y_1 = 1/k$, $z_1 = \alpha$; in fact it surely gives $x_n = e^{\alpha}$, provided that $z_1 = \alpha$ lies within the convergence region (10). However, in the above discussion, we have always assumed that $x_k > |y_k|$, which does *not* imply the limiting case $x_k = y_k$. Hence we give an alternate proof to guarantee the result.

If $x_1 = y_1$ at the initial step, we have always $x_k = y_k$ under the transformation (1), so that the variable y is unnecessary. The transformation is replaced by $x_{k+1} = x_k(1 + \delta_k)$. Since we have put δ_k tanh α_k , we see

$$x_{k+1}' = x_k(1 + \tanh \alpha_k) = x_k \operatorname{sech} \alpha_k \exp \alpha_k = x_k(1 - \delta_k^2)^{1/2} \exp \alpha_k$$

which gives

$$x_n = x_1 \prod_{k=1}^{n-1} (1 - \delta_k^2)^{1/2} \exp((\alpha_k)) = K x_1 e^{\alpha}.$$

Indeed, we can prove that the final result (4) under CORDIC case II is true without the restriction $x_1 < |y_1|$, while in the case I, the restriction (11) is indispensable.

The actual algorithm to compute e^t for real argument t is as follows:

1°. Put
$$t \cdot \log_2 e = m + s$$
; m : integer, $-1 < s \leq 0$

2°. Put
$$z_1 = s \log_e 2$$
, $x_1 = 1/K$

where $\log_{e} 2 = 0.69314718056$ and 1/K is given in (12).

3°. Repeat the procedure

if
$$z < 0$$
 then begin $x := x(1 - \varepsilon)$; $z := z + \beta$ end

else begin
$$x := x(1 + \varepsilon)$$
; $z := z - \beta$ end;

where $\varepsilon = 2^{-k}$, $\varepsilon = \operatorname{arctanh} 2^{-k}$,

for $k = 1, 2, 3, \ldots$ with repetition at k = 4 and 13.

Remark that in the above scaling 1°, s is always negative, so that at the first step, we have always $z \leq 0$. Hence it will be better to start with

$$z_2 = s \cdot \log 2 + \operatorname{arctanh}(1/2), \ x_2 = 1/2K, \ \varepsilon = 2^{-2}, \ k = 2, 3, \ldots$$

In the computation of complex exponential function

 $\exp(x + iy) = e^x(\cos y + i \sin y),$

we combine with CORDIC in circular case for the trigonometric functions. In that case it will be better to start with $x_1 = 1/KK_+ = 0.36662806930$..., where

$$K_{+} = \sum_{k=0}^{\infty} (1 + 2^{-2k})^{1/2}$$

§ 6. Computation of logarithmic function

Logarithmic function $\log t$ will be computed by the inverse process as in the previous paragraph. However, to avoid actual division, we prefer the following algorithms:

Assume first that the argument t is sufficiently near 1 (precise bound will given later in (15)).

1°. Put

$$x_2 = 1/K_1 = \sqrt{3}/2K = 1.045723138$$
, $y = t$, $z_2 = 0$

Here $K_1 = K/(1 - 2^{-2})^{1/2}$.

2°. Repeat the following process:

, if x > y then begin $x := (1 - \varepsilon)x$; $z := z + \beta$ end

else begin $x := (1 + \varepsilon)x$; $z := z - \beta$ end;"

where $\varepsilon = 2^{-k}$, $\beta = \operatorname{arctanh}\varepsilon$,

for $k = 2, 3, \ldots$, and at k = 4 and 13 repeating twice with same ε .

The repetition is completely similar to the one in § 5 except only the branching condition is replaced by x > y instead of z < 0. The process brings x as close as y. Finally if x = y, then we have

$$x = (K_1/K_1) e^{\alpha} = t,$$

which gives $z = \alpha = \log t$.

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Here we start from k = 2, since $(1 - 2^{-1}) = 1/2$ is too small to recover later by other products. Hence the convergence region is restricted in

(15)
$$|z_{1}| \leq B - \beta_{1} = B' \rightleftharpoons 0.568..., 0.57... = e^{-B'} \leq |t| \leq e^{B'} = 1.76...$$

For other values of t, we make scaling $t = 2^m \cdot y$ (*m* being integer), and set $z_2 = m \cdot \log_e 2$ in (14) instead of 0. Here we cannot take $1/2 \leq y \leq 1$ or $1 \leq y \leq 2$, but we must choose the mantissa y in

(16)
$$3/4 \leq y \leq 3/2 \text{ or } 1/\sqrt{2} \leq y \leq \sqrt{2}.$$

But this restriction is not serious in the actual programming.

Finally remark that this algorithm is not suitable for the computation of log t when the argument t is quite close to 1. In such a case we should replace the function by log (1 + s) computed by the Taylor series

$$\log (1 + s) = s - \frac{s^3}{2} + \frac{s^3}{3} - \dots,$$

or by other approximation formulas.

Added in Proof:

After I have finished to prepare the present paper I found that the papers [3], [4] and [5] are closely connected with the method proposed here. The author would like to discuss the relations and their evaluations in a separate paper.

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