

## TIME-ENTIRE DYNAMICAL SYSTEMS

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The aim of this paper is to prove that every dynamical system on a locally compact separable metric space is embeddable into a time-entire dynamical system.

*Definition 1.* A dynamical system is a pair  $(X, f)$ , where  $X$  is a topological space and  $f$  is a continuous function from the product space  $X \times \mathbb{R}$  into the space  $X$  satisfying the following axioms:

- (1)  $f(x, 0) = x$  for all  $x$  in  $X$   
(2)  $f(f(x, t), s) = f(x, t + s)$  for every  $x$  in  $X$  and  $t, s$  in  $\mathbb{R}$ .

*Remark 1.* We shall also use the expression:  $f$  is a dynamical system on the topological space  $X$ .

*Definition 2.* Let  $L$  be a Banach space. The dynamical system  $f$  on  $L$  is time-entire if  $f$  has an expansion in series

$$(3) \quad f(p_0, t) = p_0 + p_1 t + p_0 t^2 + \dots + p_n t^n + \dots$$

which is convergent in norm for every real number  $t$ , where  $p_n$  (for  $n = 1, 2, 3, \dots$ ) are dependant only on  $p_0$ , which may be chosen arbitrarily in  $L$ .

*Definition 3.* The dynamical system  $(X, f)$  is embeddable into the dynamical system  $(Y, g)$  if there is an homeomorphism  $F$  of  $X$  in  $Y$  so that:

$$(4) \quad F(f(x, t)) = g(F(x), t) \quad \text{for every } x \text{ in } X \text{ and } t \text{ in } \mathbb{R}.$$

*Remark 2.* In this case, if we denote by  $g' = g|_{F(X) \times \mathbb{R}}$ ,  $(X, f)$  is isomorphic with  $(F(X), g')$ , which is a subsystem of  $(Y, g)$  because  $g'(F(X), \mathbb{R}) = F(X)$ .

Using a theorem of BEBUTOV, E. A. BARBASHIN and F. A. SHOLOHOVICH have proved in [1] that a dynamical system defined on a compact metric space and having at most one critical point is embeddable into a time-entire dynamical system. Our goal is to apply a generalization of Bebutov's theorem given by us in [8] for the demonstration of the following:

**THEOREM.** *Every dynamical system defined on a locally compact separable metric space is embeddable into a time-entire dynamical system.*

*Proof.* We remind that the shift (or Bebutov) system on the topological space  $Y$  is the system  $f_0$  defined on  $C(R, Y)$  (with the compact-open topology) by  $f_0(x, t) = x_t$ , where  $x_t(s) = x(t + s)$ . In [8] we have demonstrated the following property of universality of the shift systems: every dynamical system definite on a locally compact separable metric space is embeddable into the shift system on  $1^2$ . To prove this, for a system  $f$  definite on  $X$  we have taken his prolongation  $\hat{f}$  to the one point compactification  $\hat{x}$  of  $X$  and then have embedded  $f_0$  into the shift system on  $1^2$ . After all  $f$  is embedded into a compact subsystem (that is defined on a compact space) of the shift system on  $1^2$ . Taking this into account, for the demonstration of the theorem it is enough to prove the following.

**L e m m a.** *Every compact subsystem of the shift system  $f_0$  on a Banach space  $Y$  is embeddable into a time-entire dynamical system.*

*Proof of the lemma.*  $Y$  being a Banach space, the compact-open topology on  $C(R, Y)$  is generated by the metrics:

$$(5) \quad d(x, y) = \sup_{T < 0} \min \left\{ \max_{|t| \leq T} \|x(t) - y(t)\|_Y; \frac{1}{T} \right\}$$

Let  $X$  be a compact, invariant (that is  $f_0(x, t) \in X$  for every  $x$  in  $X$  and  $t$  in  $R$ ) subset of  $C(R, Y)$  and denote the restriction of  $f_0$  to  $X \times R$  again by  $f_0$ . All functions from  $X$  are bounded because,  $X$  being compact, there is a constant  $m > 0$  so that for every  $x \in X: d(0, x) \leq m$ , therefore  $\|x(t)\|_Y = \|x_t(0)\|_Y \leq d(0, x_t) \leq m$ . We shall use a transformation like Fourier's used in [1] but for functions from  $C(R, Y)$ . For this we need to use complex numbers so that we replace  $Y$  (if it is real) by the complex Banach space  $Y_c$  obtained from  $Y$  by the extension of the field of scalars ([7], pp. 5-6). Let the set of continuous functions  $\varphi: R \rightarrow Y_c$  for which

the Riemann integral  $\int_{-\infty}^{\infty} \|\varphi(t)\|_{Y_c}^2 e^{-t^2} dt$  is finite. If we define in the natural

way the addition and the multiplication by complex numbers, while the norm we define by:

$$(6) \quad \|\varphi\| = \left[ \int_{-\infty}^{\infty} \|\varphi(t)\|_{Y_c}^2 e^{-t^2} dt \right]^{1/2}$$

we get a Banach space that we denote by  $N$ . To obtain a map  $\Phi$  from  $X$

in  $N$  we put for a  $x \in X$ :

$$(7) \quad (\Phi(x))(t) = \int_{-\infty}^{\infty} x(s) e^{-s^2} e^{ist} ds.$$

We have

$$(8) \quad \|(\Phi(x))(t)\|_{Y_c} \leq \int_{-\infty}^{\infty} \|x(s)\|_{Y_c} e^{-s^2} ds \leq m \int_{-\infty}^{\infty} e^{-s^2} ds = m\sqrt{\pi}$$

so that  $\Phi(x) \in N$ , that is  $\Phi$  is well defined. To prove that  $\Phi$  is continuous, we consider a sequence  $\{x_n\}$  which tends to  $x$  in  $X$  and an  $\varepsilon > 0$ . We

may choose an  $\eta > \frac{2\pi}{\varepsilon}$  so that  $\int_{\eta}^{\infty} e^{-s^2} ds < \frac{\varepsilon}{8m\sqrt[3]{\pi}}$ . Because  $x_n \rightarrow x$  there is

a natural  $n_0$  so that for every  $n > n_0: d(x_n, x) < \frac{1}{\eta}$ , that is for  $|t| \leq \eta$ :

$\|x_n(t) - x(t)\|_{Y_c} < \frac{1}{\eta}$ . For such a  $n$ :

$$(9) \quad \left\| \int_{-\infty}^{\infty} [x_n(s) - x(s)] e^{-s^2} e^{ist} ds \right\|_{Y_c} \leq \int_{-\infty}^{\infty} \|x_n(s) - x(s)\|_{Y_c} e^{-s^2} ds \leq \\ \leq \frac{1}{\eta} \int_{-\eta}^{\eta} e^{-s^2} ds + 2 \cdot 2m \int_{\eta}^{\infty} e^{-s^2} ds \leq \frac{\varepsilon}{2\sqrt[3]{\pi^3}} + 4m \cdot \frac{\varepsilon}{8m\sqrt[3]{\pi}} = \frac{\varepsilon}{\sqrt[3]{\pi}}$$

hence

$$(10) \quad \|\Phi(x_n) - \Phi(x)\|_N \leq \varepsilon.$$

Assume now that for an  $x \in X$ :

$$(11) \quad \int_{-\infty}^{\infty} x(s) e^{ist} ds = 0.$$

Then for every  $\lambda, t$  in  $R$ :

$$(12) \quad \int_{-\infty}^{\infty} x(s + \lambda) e^{ist} ds = 0.$$

Fix  $a < b$  and put:

$$(13) \quad \varphi(s) = \int_a^b x(s + \lambda) d\lambda$$

We have

$$(14) \quad \int_a^b \int_{-\infty}^{\infty} x(s + \lambda) e^{ist} ds \cdot d\lambda = 0$$

or applying Fubini's theorem [6]:

$$(15) \quad \int_{-\infty}^{\infty} \varphi(s) e^{ist} ds = 0 \text{ for every } t \text{ in } R.$$

It may be deduced from (15) as in [4] (p. 398) that  $\varphi(s) \equiv 0$ . But  $a$  and  $b$  being arbitrary it follows that  $x = 0$  because if we suppose  $x(t_0) \neq 0$  for a  $t_0 \in R$ , by the continuity of  $x$ , for  $r = \|x(t_0)\|$  there is a  $\delta > 0$  so that

$$\|x(t) - x(t_0)\| \leq \frac{r}{2} \text{ for every } t \in (t_0 - \delta, t_0 + \delta). \text{ Then } \frac{1}{2\delta} \int_{t_0 - \delta}^{t_0 + \delta} x(t) dt \in$$

$$\in S\left(x(t_0), \frac{r}{2}\right) \text{ so that } \int_{t_0 - \delta}^{t_0 + \delta} x(t) dt \neq 0, \text{ which is impossible. After all } \Phi(x) = 0$$

implies  $x = 0$ , hence  $\Phi$  is an injection.  $X$  being a compact space and  $\Phi$  a continuous injection it follows that  $\Phi$  is a homeomorphism from  $X$  on  $\Phi(X) \subset N$ .

We define  $f: \Phi(X) \times R \rightarrow \Phi(X)$  by:

$$(16) \quad f[\Phi(x), t] = \Phi[f_0(x, t)].$$

It is easy to prove that  $f$  is a dynamical system on  $\Phi(X)$ , isomorphic (by (16)) with the shift system on  $X$ . Let us prove that  $f$  is time-entire, that is the function

$$(17) \quad g(s, t) = F[\Phi(x), t](s)$$

is entire with respect to  $t$ . But

$$(18) \quad g(s, t) = \int_{-\infty}^{\infty} x(t + u) e^{-u^2} e^{ius} du = \int_{-\infty}^{\infty} x(u) e^{-(u-t)^2} e^{i(u-t)s} du.$$

The function  $x(u) e^{-(u-t)^2} e^{i(u-t)s}$  being analytic with respect to  $t$  for every  $u$ , continuous with respect to  $u$  for every  $t$ , and bounded, it follows that  $g$  is analytical with respect to  $t$  (for the ordinary case this property is proved in [5] pp. 295–296; for functions with values in a Banach space it is necessary to verify a lot of other theorems; the starting one is Cauchy's integral formula which is true in this case [3]). That is:

$$(19) \quad g(s, t) = \sum_{k=0}^{\infty} \varphi_k(s) t^k.$$

It must be shown that  $\varphi_k \in N$  and that the series converges in the norm of  $N$ . Firstly  $\varphi_0 = \Phi(x) \in N$ . Then  $\varphi_1(s) = g'_t(s, 0)$ , that is

$$(20) \quad \varphi_1(s) = \int_{-\infty}^{\infty} x(u) e^{-u^2} e^{ius} (2u - is) du$$

and so

$$(21) \quad \|\varphi_1(s)\|_{Y_c} \leq m \left[ 2 \int_{-\infty}^{\infty} |u| e^{-u^2} du + |s| \int_{-\infty}^{\infty} e^{-u^2} du \right] = m(2 + \sqrt{\pi} \cdot |s|).$$

Generally

$$(22) \quad \varphi_n(s) = \sum_{k=0}^n p_k(s) \int_{-\infty}^{\infty} x(u) e^{-u^2} e^{ius} u^k du$$

that is

$$(23) \quad \|\varphi_n(s)\| \leq 2m \sum_{k=0}^n |p_k(|s|)| \int_0^{\infty} u^k e^{-u^2} du = 2m P_n(|s|)$$

because

$$(24) \quad \int_0^{\infty} u^k e^{-u^2} du = \begin{cases} \frac{p!}{2} & \text{if } k = 2p + 1 \\ \frac{\sqrt{\pi}}{2^{p+1}} (2p - 1)!! & \text{if } k = 2p \end{cases}$$

where by  $p_k$  and  $P_n$  we have denoted polynomials and by  $|p_k|$  the polynomial obtained from  $p_k$  taking all the coefficients in absolute value. After all,  $\varphi_n$  belongs to  $N$  for every natural  $n$ . The proof of the convergence of the series (19) is the same as that of [1] (by formal changes).

*Remark 3.* Using the generalization of Vinograd's theorem given by D. H. CARLSON in [2] it follows a similar result for local dynamical systems. The lemma may be applied also to systems for which an embedding theorem in a compact subsystem of the shift system is proved.

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