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ON THE APPROXIMATIVE SOLVING OF THE INTEGRAL

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A large number of technical and scientific problems requires the solving of the nonlinear integral equations, but the finding of the exact solutions is generally a hard problem. In the latest time several papers and lectures are devoted to the theory and application of the method of the approximative solving of these equations. In Balázs's paper [2], the method ([3], [4]) of chords is applied for the equation

(1)
$$x(s) = \int_{0}^{1} K[s, t, x(t)] dt,$$

where $K \in C([0, 1] \times [0, 1] \times R)$. As divided difference of the operator $P: C[0, 1] \to C[0, 1]$

$$P(x) = x(s) - \int_0^1 K[s, t, x(t)]dt,$$

the mapping $[x_i, x_j; P] \in \mathfrak{L}(C[0, 1], C[0, 1])$

$$[x_i, x_j; P]h = h(s) - \int_0^1 [x_i, x_j, K]_{(t)}h(t)dt$$

is considered, where

$$[x_i, x_j; K]_{(i)} = \frac{K(s, t, x_i(t)) - K(s, t, x_j(t))}{x_i(t) - x_j(t)}$$

We can se obtain a divided difference of the second order

$$[x_i, x_j, x_k; P]hk = -\int_0^1 \frac{[x_i, x_j; K]_{(t)} - [x_j, x_k; K]_{(t)}}{x_i(t) - x_k(t)} h(t)k(t)dt.$$

Using the rezults of the paper [2] we give a theorem of existence of the solution for the equation.

(2)
$$x(s) = \int_{0}^{1} K_{1}[s, t, x(s), x(t)]dt$$

where $K_1 \in C([0, 1] \times [0, 1] \times \mathbb{R}^2)$. We have

$$P_1(x) = x(s) - \int_0^1 K_1[s, t, x(s), x(t)]dt,$$

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$$[x_{i}, x_{j}; P_{1}]h = h(s) - \int_{0}^{1} \{[x_{i}, x_{j}; K_{1}]_{(s)}h(s) + [x_{i}, x_{j}; K_{1}]_{(t)}h(t)\}dt,$$

$$[x_i, x_j, K_1]_{(s)} = \frac{K_1[s, t, x_i(s), x_i(t)] - K_1[s, t, x_j(s), x_i(t)]}{x_i(s) - x_j(s)},$$

$$[x_i, x_j; K_1]_{(t)} = \frac{K_1[s, t, x_j(s), x_i(t)] - K_1[s, t, x_j(s), x_j(t)]}{x_i(t) - x_j(t)},$$

We observe that the divided difference of the second order of the P_1 , is formed with the divided differences of second order of the function K_1 . We consider the integral equation

$$h(s)f(s) - \int_{0}^{1} [x_{i}, x_{j}; K_{1}]_{(t)}h(t)dt = y_{1}(s)$$

Now we can apply the theorem of [2]; and we can give the

THEOREM If for the equation (2) there exist the functions x_{-1} , $x_0 \in$ $\in C[0, 1]$ so that the following conditions are satisfied:

(i) for the kernel $[x_i, x_j; K_1]_{(t)}$ there exists the rezolvent kernel R(s, t)

$$\int_{0}^{1} |R(s, t)| dt \leqslant A \qquad (0 \leqslant s \leqslant 1);$$

(ii) $||x_0 - x_{-1}|| \le \eta_{-1}$, $||[x_0, x_{-1}; P_1]^{-1}P_1(x_0)|| \le \eta_0$;

(iii)
$$|[u, v, w; K_1]| \leq M$$
, $(s, t) \in [0, 1] \times [0, 1]$

for every u, v, w of the sphere S defined by the $||x - x_0|| \le 2\eta_{-1}$;

(iv)
$$h_0 = (A + 1)(\eta_0 + \eta_{-1})M \leq \frac{1}{4}$$
,

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Then the equation (2) has a solation x^* in S being the limit of the sequence given by

$$x_{n+1} = x_n - [x_n, x_{n-1}; P_1]^{-1}P_1(x_n).$$

The rapidity of the convergence being given by the

$$||x_n - x^*|| \le \frac{1}{2^s n^{-1}} \cdot q^{s_{n-1}} (4h_0)^{s_n} \eta_0$$

where 0 < q < 1, and s_n is the partial sum of the Fibonacci's series with $u_1 = u_2 = 1$.

This result can be applied to the Chandrasekar equation which arises in radiative transfer ([1] pp. 277).

- [1] Anselone, P. M., ed., Nonlinear Integral Equations, University of Wisconsin Press. Madison, 1964.
- [2] Balázs, M., Asupra aplicării metodei coardei la rezolvarea ecuațiilor integrale neliniare (Rumanian), Stud. și Cerc. Mat., 6, tom 23, 841-844 (1971).
- [3] Balázs, M., Goldner, G., Observații asupra diferențelor divizate și asupra metodei coardei (Rumanian), Revista de Anal. Numer. și Teor. Aprox., Volumul 3, Fascicula 1,
- [4] Sergeev, A. S., O metode hord (Russian), Sibirs. Mat. J. tom II. 2, 282-289 (1961).

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