

NUMERICAL INTEGRATION BY MEANS OF GAUSS-  
LEGENDRE FORMULA

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**1. Introduction.** The aim of this paper is to construct an algorithm written in FORTRAN — IV for the composite Gauss-Legendre quadrature formula. This FORTRAN algorithm consists of a commended subprogram which furnishes us the Gauss rule of integration constructed at the roots of the Legendre polynomial of the degree  $N$ ,  $N$  being arbitrary.

If  $N$  is a fixed natural number let us denote by  $x_i$ ,  $i = 1, 2, \dots, N$ ,  $-1 < x_N < \dots < x_2 < x_1 < +1$ , the roots of the Legendre polynomial  $P_N$  which may be defined by the recursion relation

$$P_0(x) = 1, \quad P_1(x) = x$$

$$P_j(x) = \frac{2j-1}{j} x P_{j-1}(x) - \frac{j-1}{j} P_{j-2}(x), \quad j = 2, 3, \dots, N.$$

For an integrable function  $f: [a, b] \rightarrow \mathbf{R}$  the Gauss-Legendre formula may be written as

$$(1) \quad \int_a^b f(x) dx = \frac{b-a}{2} \sum_{k=1}^N c_k f\left(\frac{a+b}{2} + \frac{b-a}{2} x_k\right) + R(f)$$

where  $c_1, \dots, c_N$  are the Christoffel weights defined as

$$c_k = \frac{2}{(1-x_k^2)[P'_N(x_k)]^2}$$

and  $R(f) = R(f; [a, b], N)$  is the remainder. It is known that if  $f$  belongs to the space  $C^{(2N)}[a, b]$  then there exists at least a point  $\theta \in [a, b]$ , such that (see [3], [5]).

$$(2) \quad R(f) = \frac{(b-a)^{2N+1}}{2N+1} \binom{2N}{N}^{-2} \frac{f^{(2N)}(\theta)}{(2N)!}.$$

The simplest composite formula is generated by repeated application of the quadrature formula (1) at each subinterval  $[a_i, a_{i+1}]$ ,  $a_i = a + \frac{i-1}{L}(b-a)$ ,  $i = 1, 2, \dots, L$ . Let us denote

$$H = \frac{b-a}{2L}, \quad h_i = a + (2i-1)H, \quad M = \begin{bmatrix} N \\ 1 \end{bmatrix},$$

$$T_{ik}(f) = f(h_i + Hx_k) + f(h_i - Hx_k).$$

In terms of  $L$ , the number of applications of the formula (1), and  $a$  and  $b$ , the integration limits, the composite formula is

$$(3) \quad \int_a^b f(x) dx = H \left[ c(N) \sum_{i=1}^L f(h_i) + \sum_{k=1}^M c_k \sum_{i=1}^L T_{ik}(f) \right] + R_{N,L}(f)$$

where

$$c(N) = \begin{cases} 0 & \text{if } N = 2M \\ \frac{2^{2N-1}}{N^2} \binom{2M}{M}^{-2} & \text{if } N = 2M + 1 \end{cases}$$

**2. The remainder**  $R_{N,L}$ . If  $f \in C^{(2N)}[a, b]$  then from (1) - (2) it follows that there are the points  $\theta_1, \dots, \theta_L$ ,  $\theta_i \in [a_i, a_{i+1}]$ , such that

$$R_{N,L}(f) = \frac{(2H)^{2N+1}}{2N+1} \binom{2N}{N}^{-2} \frac{1}{(2N)!} \sum_{i=1}^L f^{(2N)}(\theta_i).$$

Using the inequalities

$$\frac{4^n}{\sqrt{\pi n + a}} < \binom{2n}{n} < \frac{4^n}{\sqrt{\pi n + b}}, \quad a = \frac{8}{9}, \quad b = \frac{\pi}{4}, \quad n > 2,$$

one proves the following

**Lemma 1.** a) If  $f \in C^{(2N)}[a, b]$  then there exists  $\theta$ ,  $\theta \in [a, b]$ , such that

$$(4) \quad R_{N,L}(f) = \frac{(2H)^{2N+1}}{2N+1} \binom{2N}{N}^{-2} \cdot L \cdot \frac{f^{(2N)}(\theta)}{(2N)!};$$

b) For  $f \in C^{(2N)}[a, b]$  we have

$$|R_{N,L}(f)| < \frac{2\pi}{(2N)!} \left(\frac{H}{2}\right)^{2N+1} \|f^{(2N)}\|, \quad N > 2,$$

where  $\|\cdot\|$  denotes the uniform norm.

In the following we find the remainder  $R_{N,L}$  on the space of continuous functions. The following notation is used:

$$e_k(t) = t^k, \quad k = 0, 1, \dots,$$

$$Q_{n,x}(t) = |t-x|_+^n = \begin{cases} (t-x)^n & \text{if } t \geq x \\ 0 & \text{if } t < x, \end{cases}$$

$[z_1, z_2, \dots, z_n; f]$  - denotes the divided difference at the knots

$$z_i, \quad i = 1, 2, \dots, n.$$

Let us consider a bound linear functional  $R: C[a, b] \rightarrow \mathbf{R}$ . If for each  $h \in C^{(n+1)}[a, b]$  there exists a point  $\theta = \theta(h) \in [a, b]$  for which

$$R(h) = \frac{h^{(n+1)}(\theta)}{(n+1)!} R(e_{n+1}), \quad R(e_{n+1}) \neq 0,$$

then we say that  $R$  has a simple form on the space  $C^{(n+1)}[a, b]$ . The functional  $R$  has a simple form on  $C[a, b]$  if for each  $f \in C[a, b]$  there is a system  $\theta_1, \dots, \theta_{n+2}$  of distinct points from  $[a, b]$  such that

$$R(f) = R(e_{n+1}) \cdot [\theta_1, \theta_2, \dots, \theta_{n+2}; f].$$

**THEOREM 2.** If  $R: C[a, b] \rightarrow \mathbf{R}$  is a bounded linear functional which has a simple form on the subspace  $C^{(n+1)}[a, b]$  then  $R$  has a simple form on the whole space  $C[a, b]$ .

*Proof.* If  $R$  verifies the prescribed hypothesis then

$$(5) \quad R(e_k) = 0 \quad \text{for } k = 0, 1, \dots, n.$$

According to Peano (see [1], theorem 3.7.1) the equalities (5) imply that

$$(6) \quad R(h) = \int_a^b h^{(n+1)}(x) K(x) dx, \quad h \in C^{(n+1)}[a, b],$$

where

$$K(x) = \frac{1}{n!} R_i(|t-x|_+^n) = \frac{1}{n!} R(Q_{n,x}).$$

The continuity of  $K$  on  $[a, b]$  implies that the function

$$h_0(x) = \int_a^x \int_a^{x_1} \dots \int_a^{x_n} [K(x_{n+1}) - |K(x_{n+1})|] dx_1 dx_2 \dots dx_{n+1}, \quad x \in [a, b],$$

verifies

$$h_0 \in C^{(n+1)}[a, b], \quad h_0^{(n+1)}(x) = K(x) - |K(x)|.$$

Without loss of generality, say  $R(e_{n+1}) > 0$ . From the behaviour of the functional  $R$  on the space  $C^{(n+1)}[a, b]$  it follows that there is a point  $\theta$  on  $[a, b]$  such that

$$R(h_0) = [K(\theta) - |K(\theta)|] \frac{R(e_{n+1})}{(n+1)!} \leq 0.$$

On the other hand, from (6)

$$R(h_0) = \int_a^b [K^2(x) - K(x)|K(x)|] dx = \frac{1}{2} \int_a^b (K(x) - |K(x)|)^2 dx \geq 0.$$

Therefore  $R(h_0) = 0$ , i.e.

$$\int_a^b [K(x) - |K(x)|]^2 dx = 0$$

or  $K(x) = |K(x)|$ ,  $x \in [a, b]$ . In conclusion,  $K$  is non-negative on  $[a, b]$ . Therefore, the bounded linear functional  $R: C[a, b] \rightarrow \mathbf{R}$  has the properties

$$\text{i) } R(e_k) = 0 \text{ for } k = 0, 1, \dots, n, \quad R(e_{n+1}) > 0,$$

$$\text{ii) } R(Q_{n,x}) \geq 0 \text{ for } x \in [a, b].$$

An earlier result by T. POPOVICIU ([7], theorem 12) asserts that in this case  $R$  has a simple form on the space  $C[a, b]$ . This completes the proof (see also [4]).

The equality (4) enables us to assert that  $R_{N,L}: C[a, b] \rightarrow \mathbf{R}$  which is a bounded linear functional ([3]), has a simple form on the subspace  $C^{(2N)}[a, b]$ . From the above theorem we conclude with the following:

**THEOREM 3.** *If  $f: [a, b] \rightarrow \mathbf{R}$  is continuous on  $[a, b]$  then there is a system  $\theta_1, \theta_2, \dots, \theta_{2N+1}$  of distinct points from  $[a, b]$  such that*

$$R_{N,L}(f) = L \cdot \frac{(2H)^{2N+1}}{2BN+1} \left(\frac{2N}{N}\right)^{-2} \cdot [\theta_1, \theta_2, \dots, \theta_{2N+1}; f].$$

### 3. The roots of the Legendre polynomial

$$I_j = \left( \cos \frac{j\pi}{N+1}, \cos \frac{4j-1}{4N+2} \pi \right).$$

If  $x_i$ ,  $-1 < x_N < \dots < x_2 < x_1 < +1$ , are the roots of the Legendre polynomial  $P_N$ , then it is known that (see [9])

$$x_j \in I_j, \quad x_{N+1-j} = -x_j, \quad j = 1, 2, \dots, M.$$

Moreover  $I_j \cap I_i = \emptyset$ ,  $i \neq j$ . In order to find the roots  $x_1, \dots, x_M$  we have used the so-called „square-root iteration method” ([6]), namely

$$x_j^{(0)} = \cos \frac{4j-1}{4N+1} \pi, \quad x_j^{(0)} \in I_j, \quad 1 \leq j \leq M,$$

$$x_j^{(k)} = F(x_j^{(k-1)}), \quad k = 1, 2, \dots,$$

where

$$F(x) = x - \frac{P_N(x)}{P_N'(x) \sqrt{1 - \frac{P_N(x)P_N''(x)}{P_N'(x)^2}}}.$$

An iteration  $x_j^{(k_0)}$  was considered as a „good approximation” of the root  $x_j$  if one of the following inequalities

$$|x_j^{(k_0)} - x_j^{(k_0-1)}| \leq 10^{-16}, \quad |P_N(x_j^{(k_0)})| \leq 10^{-20}, \quad k_0 \geq 10.$$

was verified. This iteration method was tested for  $N = 2,200,1$ . We note that the first inequality was satisfied for  $k_0 = 3$ . On the other hand, for all values of  $N$

$$|P_N(x_j^{(3)})| \leq 10^{-15}, \quad j = 1, 2, \dots, M.$$

By means of these approximative values of the roots there are determined the corresponding Christoffel weights  $c_j$ . Let us denote

$$S_N(k) = \frac{1 - (-1)^{k+1}}{k+1} - \sum_{j=1}^N (x_j)^k \cdot c_j = R(e^k; [-1, +1], N).$$

Taking into account that the quadrature formula (1) is exact for all polynomials of the degree  $\leq 2N - 1$ , in order to test the accuracy of the iterative method, we have asked if the values  $S_N(2k)$ ,  $k = 0, N - 1$ , are zero; note that  $S_N(2k - 1) = 0$  for  $1 \leq k \leq N$ . Using this precision criterion it was observed that

$$|S_N(2k)| \leq 10^{-14}, \quad k = 0, 1, \dots, N - 1.$$

### 4. FORTRAN implementation.

Let us denote

$$I(f) = \int_a^b f(x) dx$$

$$G(N, L, f) = H \cdot \left[ c(N) \sum_{i=1}^L f(h_i) + \sum_{k=1}^M c_k \sum_{i=1}^L T_{ik}(f) \right].$$

The composite quadrature formula (3) furnishes us the approximation

$$I(f) \approx G(N, L, f).$$

In order to evaluate  $I(f)$  we have constructed a subroutine

GAUSSI (F, A, B, N, L, EPS, X, W, R, ITER, KOD)

where the input parameters are:

FON = the function  $f$  which must be integrated  
 A, B = the integration limits  $a, b$   
 N = degree of the Legendre polynomial  
 L = the (initial) number of applications of the Gauss-Legendre quadrature formula  
 EPS = a tolerance value  
 ITER = the maximum number of iterative cycles permitted, i.e.,  
 $L$  (final)  $\leq$  ITER

The output parameters are:

R = the final approximative value for  $I(f)$   
 X = a vector of dimension  $1 + \left\lfloor \frac{N}{2} \right\rfloor$  which contains the non-negative roots  $X(1) > X(2) > \dots > X(N1)$  of the Legendre polynomial; Note that  $N1 = \lfloor N/2 \rfloor$  if  $N$  is even and  $N1 = 1 + \lfloor N/2 \rfloor$  for  $N$  odd.  
 W = an array of dimension  $1 + \lfloor N/2 \rfloor$  which includes the Christoffel numbers  $W(I) = c_i$  corresponding to  $X(I)$   
 KOD = an error code,  $KOD \in \{0, 1\}$ .

The program was compiled and executed on a FELIX C-256 computer using double precision arithmetic. The principal steps of this FORTRAN algorithm are:

- 1) Test if  $N > 3$ . If this is false then  $N := 4$ ;
- 2) Check for  $0 < EPS < 10^{-7}$ . If these inequalities are not satisfied, then  $EPS := 10^{-8}$ ;
- 3) Compute an initial approximation RINIT for  $I(f)$ . More precisely  $RINIT := G(3, 1, f)$ ;
- 4) Compute the (approximative) roots  $X(1), X(2), \dots, X(N1)$  of the Legendre polynomial as well as the corresponding Christoffel weights  $W(1), W(2), \dots, W(N1)$ ;
- 5) Calculate the approximation R of the integral  $I(f)$ . This means that  $R := G(N, L, f)$ ;
- 6) Test of accuracy: more precisely check for  
 (7)  $|R - RINIT| \leq EPS \min(1, |R|)$ .  
 If (7) is verified then  $KOD = 0$  and RETURN.
- 7) Iteration of the integration method: when the accuracy criterion (7) is not satisfied then test if  $2L < ITER$ : if this is true then  $L := 2L$ ,  $RINIT := R$  and a new approximation R is constructed, i.e.,  $R := G(2L, N, f)$ . This iteration proceeds until the accuracy test (7) is passed or until  $L$ , the number of iterations, exceeds ITER. If  $2L \geq ITER$  and (7) is not verified then  $KOD = 1$  and RETURN. Note that  $L$  may be destroyed during computation; in the following we shall denote by LFINAL the final value of  $L$ .

The program listing is the following:

```

SUBROUTINE GAUSSI (F,A,B,N,L,EPS,X,W,R,ITER,KOD)
=====
C
C   PURPOSE:
C       THE APPROXIMATIVE INTEGRATION OF A FUNCTION
C       F ON AN INTERVAL (A,B)
C
C   METHOD:
C       GAUSS-LEGENDRE QUADRATURE FORMULA
C
C   USAGE:
C       CALL GAUSSI (F,A,B,N,L,EPS,X,W,R,ITER,KOD)
C
C   DESCRIPTION OF PARAMETERS:
C       F       — THE FUNCTION WHICH IS INTEGRATED
C       A,B     — ENDPOINTS OF THE INTERVAL OF INTE-
C               GRATION
C       N       — THE DEGREE OF THE LEGENDRE POLY-
C               NOMIAL
C       L       — NUMBER OF EQUIDISTANT SUBINTERVALS
C               FROM (A,B)
C       EPS    — A TOLERANCE VALUE
C       X       — VECTOR OF DIMENSION 1+N/2 WHICH CON-
C               TAINS THE NON-NEGATIVE ROOTS OF THE
C               LEGENDRE POLYNOMIAL
C       W       — AN ARRAY OF DIMENSION 1+N/2 WHICH
C               INCLUDES THE CHRISTOFFEL NUMBERS
C       R       — THE APPROXIMATIVE VALUE OF THE
C               INTEGRAL
C       ITER   — THE MAXIMUM NUMBER OF ITERATIVE
C               CYCLES PERMITTED
C       KOD    — AN ERROR CODE : KOD = 0 MEANS THAT
C               A CERTAIN ACCURACY TEST IS VERIFIED.
C               OTHERWISE, KOD = 1.
C
C   INPUT PARAMETERS : F,A,B,N,L,EPS,ITER
C   OUTPUT PARAMETERS : X,W,R,KOD
C
C   REMARKS :
C   (1) L IS DESTROYED DURING COMPUTATION
C   (2) A DECLARATION EXTERNAL F MUST BE USED
C       BEFORE CALL GAUSSI (F, A, B, N, L, EPS, X, W, R,
C       ITER, KOD)

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```

IMPLICIT DOUBLE PRECISION (A-H,O-Z)
DIMENSION X(1), W(1)
C      = = = TEST ON N = = =
1     N = 4
C      = = = TEST ON EPS = = =
8     EPX=EPS - .1D-6
      IF(EPX*EPX) 2,9,9
9     EPS = .1D-7
C      = += THE INITIAL VALUE OF R, NAMELY RINIT, IS
      CONSTRUCTED = +=
2     H1 = (B-A)*0.5
      P = (A+B)*0.5
      ROOT=H1*0.774596669241483
      P1 = P + ROOT
      P2 = P - ROOT
      RINIT = (F(P1)+F(P2))*0.5555555555555556
      RINIT = RINIT + 0.8888888888888889*F(P)
C      = += INITIAL VALUES = +=
      M = N/2
      TN=DFLOAT(N)
      AN = 1./TN
      CSI = 1./(4.*TN + 1.)
      DEV = (1. + TN)*TN
C      = += START OF THE ITERATION METHOD WHICH
      FURNISHES US
C      THE ROOTS X(1),...,X(M) AND THE WEIGHTS W(1),...,
      W(M) = +=
      DO 100 K = 1,M
        TED = (4.*DFLOAT(K)-1.)*CSI
        V = TED*3.1415926535897932
        X(K) = DCOS(V)
        NTER = 0
300    P2 = X(K)
        P1 = 1.
C      = = COMPUTE P3, THE VALUE OF THE LEGENDRE
C      POLYNOMIAL, PN(X) AT X(K) = =
      DO 70 IT = 2,N
        ZI = 1./DFLOAT(IT)
        P3 = (2.-ZI)*X(K)*P2 - (1.-ZI)*P1
        P1 = P2
        P2 = P3
70    CONTINUE
C      = = CALCULATE THE SUCCESIVE APPROXIMATION OF
C      THE ROOT X(K) = =
      U = 1. - X(K)*X(K)
      U1 = P3*X(K) - P1

```

```

      Q = U*AN/UI
      GW = P3*Q
      DE = U + 2.*X(K)*GW + GW*GW*DEV
      DER = DABS(U)/DE
      EPSI = GW*DSQRT(DER)
      IF(DABS(P3) - .1D-19) 100,100,5
5     IF(DABS(EPSI) - .1D-17) 100,100,6
6     IF(NTER-10) 7,7,100
7     NTER = NTER + 1
      X(K) = X(K) + EPSI
      GO TO 300
100    W(K) = 2.*Q*Q/U
C      = = CALCULATE THE APPROXIMATION R OF THE
      INTEGRAL, = = IF(2*M - N) 3,4,3
3     AM = 1.
      DO 50 I=1,M
        TIX = 2.*DFLOAT(I) - 1.
50    AM = AM*(1. + 1./TIX)
      NM = M + 1
      W(NM) = AM*AM*AN*AN
      X(NM) = 0
      GO TO 44
4     NM = M
44    H = H1/DFLOAT(L)
      R = 0
      DO 444 K = 1,NM
        ZW = H*X(K)
        S = 0
        DO 80 I = 1,L
          ZI = 2.*DFLOAT(I) - 1.
          SI = A + ZI*H
          S = S + F(SI + ZW) + F(SI - ZW)
80    R = R + W(K)*S
444    R = R*H
      RABS = DABS(R)
      IF(RABS - 1.) 90,90,91
90    DEZ = DABS(R-RINIT) - EPS*RABS
      GO TO 92
91    DEZ = DABS(R-RINIT) - EPS
C      = = TEST ON ACCURACY = =
92    IF(DEZ) 93,93,94
92    L = 2*L
      IF(L-ITER) 95,96,96
95    RINIT = R
C      = = ITERATION OF THE INTEGRATION METHOD = =
      GO TO 44
93    KOD = 0

```

```

96      GO TO 99
      KOD = 1
      L = L/2
99      IF(N-NM) 401,500,401
C      = = FINDING THE TRUE WEIGHT W(M+1) = =
401     W(NM) = 2. * W(NM)
500     RETURN
      END

```

**5. Numerical examples.** The above algorithm was programmed and examples were computed for several functions. The computations were done in double precision.

5.1.  $f(x) = x + \pi \cdot \sin(\pi x)$ ,  $a = 0$ ,  $b = 1$ ,  $N = 10$ ,  $L = 128$ ,  
ITER=1000, EPS = .1D-14.

Results:  $R = .2500000000000000E+01$ , LFINAL=512, KOD=1  
 $I(f) = .2500000000000000E+01$ .

5.2.  $f(x) = 1 + e^x$ ,  $a = 0$ ,  $b = 1$ ,  $N = 4$ ,  $L = 40$ , ITER=500,  
EPS = .1D-5.

Results:  $R = .271828182845905E+01$ , LFINAL=160, KOD=0  
 $I(f) = .2718281828459045...E+01 = e$ .

5.3.  $f(x) = 1/(1+x)$ ,  $a = 1$ ,  $b = 0$ ,  $N = 5$ ,  $L = 20$ , ITER=500,  
EPS = .1D-7.

Results:  $R = -.693147180559945E+00$ , LFINAL=160, KOD=0  
 $I(f) = -.6931471805599453...E+00 = -\log_2$ .

5.4.  $f(x) = 6\sqrt{2\pi} (\sin x)^{3/2}$ ,  $a = 0$ ,  $b = \pi/2$ , ITER=4000, EPS=  
= .1D-7.

Results: 1) With  $N = 4$ ,  $L = 200$   
 $R = .131450472058757E+02$ , LFINAL=400, KOD=0;  
2) With  $N = 5$ ,  $L = 400$   
 $R = .131450472063418E+02$ , LFINAL=400, KOD=0;  
3) If  $N = 44$ ,  $L = 200$ , then  
 $R = .131450472065968E+02$ , LFINAL=200, KOD=0;  
4) For  $N = 100$ ,  $L = 100$  one finds  
 $R = .131450472065969E+02$ , LFINAL=100, KOD=0;  
 $I(f) = .131450472065969...E+02 = \left[\Gamma\left(\frac{1}{4}\right)\right]^2$ .

5.5.  $f(x) = x \cdot \arctg x$ ,  $a = 1$ ,  $b = 0$ ,  $N = 15$ ,  $L = 10$ , ITER=50,  
EPS = .1D-8.

Results:  $R = -.285398163397448E+00$ , LFINAL=40, KOD=0  
 $I(f) = -.285398163397448...E+00 = 0.5 - \arctg(1)$ .

5.6.  $f(x) = x \cdot \log_e x$ ,  $a = 1$ ,  $b = 2$ , ITER=300, EPS = .1D-7.

Results: 1) With  $N = 200$ ,  $L = 20$ , we obtain  
 $R = .636294361119892E+00$ , LFINAL=20, KOD=0;  
2) If  $N = 150$ ,  $L = 256$ , then  
 $R = .636294361119892E+00$ , LFINAL=256, KOD=0,  
 $I(f) = .63629436111989061884...E+00$ .

5.7.  $f(x) = (0.5x + \sqrt{1 + 0.25x^2})^{13} \cdot P_{10}(x)$ ,  $a = -1$ ,  $b = 1$ , ITER =  
= 4000, EPS = .1D-8. Note that in the following we  
denote by  $P_n$  the  $n$ -th Legendre polynomial.

Results: 1) For  $N = 90$ ,  $L = 80$  one finds  
 $R = .1188281590606595E-01$ , LFINAL=80, KOD=0;  
2) If  $L = 400$  and  $N = 5$ , respectively  $N = 6$ , then  
LFINAL = 800, KOD = 0 and  
 $R = .118281590606931E-01$ , resp.,  
 $R = .118281590606417E-01$   
 $I(f) = .118281590606678...E-01 = 65\sqrt{5}/12288$ .

5.8.  $f(x) = (1 - x - \log_e x)/((1 - x) \cdot \log x)$ ,  $a = 0$ ,  $b = 1$ , ITER =  
= 4000,  $L = 1400$ .

Results: 1) With  $N = 10$ , EPS = .1D-9 one obtains  
 $R = .577215655361789E+00$ , LFINAL=2800, KOD=1;  
2) For  $N = 50$ , EPS = .1D-8 the computer furnishes  
 $R = .577215664180130E+00$ , LFINAL=2800, KOD=1  
 $I(f) = .57721566490153286...E+00 = \gamma = \text{Euler's}$   
constant.

5.9.  $f(x) = \log_e 2 + \frac{x}{(\sin x + \cos x) \sin x}$ ,  $a = 0$ ,  $b = \pi/4$ , ITER = 400,  
EPS = .1D-9,  $N = 10$ ,  $L = 1200$ .

Results:  $R = .915965594177221E+00$ , LFINAL=2400, KOD=0  
 $I(f) = .915965594177219015...E+00 = G = \text{Cata-}$   
lan's constant.

5.10.  $f(x) = 9728 \cdot P_9(x)(1.25 - x)^{-0.5}$ ,  $a = -1$ ,  $b = 1$ , ITER = 4000,  
EPS = .1D-8.

Results: 1) If  $N = 8$ ,  $L = 1000$ , then  
 $R = .2000000000000189E+01$ , KOD=0, LFINAL=  
= 2000;  
2) For  $N = 9$ ,  $L = 1000$ , one finds  
 $R = .2000000000000120E+01$ , KOD=0, LFINAL=  
= 2000,  
 $I(f) = .2000000000000000E+01$ .

Taking into account that the knots at which the integrand is evaluated are chosen in a way that depends on the nature of the function  $f$ , we note that this program named GAUSS1 furnishes us an adaptive iterative scheme for automatic integration. An important property of the above subroutine is the fact that the integration abscissas  $X(I)$ , as well as the values of the corresponding weights  $W(I)$ , are output parameters. Comparison of the calculated roots  $X(I)$  and weights  $W(I)$  with those listed in [2]-[3], [8], shows that our algorithm yields results accurate to 14 figures or more.

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