L'ANALYSE NUMÉRIQUE ET LA THÉORIE DE L'APPROXIMATION: Tome 19, Nº 1, 1990, pp. 1-6 2000 lyltanty and

 $|O_F| \sin \theta = d(r, t) = \max_{t \in F} \{d, u, t\}, \forall t \in [0, r]\}$ (0)

BETWEEN TWO SETS AND THEIR THE ANGLE INNER PRODUCT IN ANY BANACH SPACE

 $=\max\{d(u,b): u, \in \{0,v\}\}$

ALEXANDER ABIAN (Ames)

with $W = (\min_{x \in \mathbb{R}^n} \{u(u_x, x) : x \in \mathcal{U}\} : u_x \in [0, x]\})/r$ Abstract. Based on observation (12) concerning the definition of sin 0 in the Euclidean plane geometry, a definition of the angle between two sets and their inner product in any Banach space, or for that matter, in any metric (or even in a much more abstract) space is introduced.

Our motivation is based on the following considerations in connection with sin θ , where θ is the angle between the bounded line segment A and the line segment B (in the usual Euclidean plane) intersecting at the point 0 as shown in Fig. 1. dryn sellar to some new root and vide

(1) The line segment A is a set of points each denoted by +

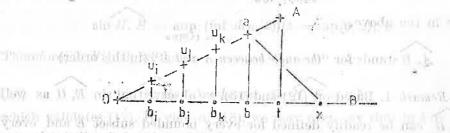
(2) The line segment B is a set of points each denoted by. (3) The line segments A and B have a nonempty intersection, namely $\{0\}$.

(4) Let d(p, q) denote the Euclidean distance of the point p from the

point q in the Euclidean plane.

5) In Fig. 1, let b be the foot of the perpendicular from the point a to the line segment B. Then the Euclidean distance d(a, B) of the point a from the line segment B (using notation in (4)) is obviously d(a, b), i.e.,

6) $d(a, B) = d(a, b) = \min\{d(a, x) : x \in B\}$



support H of the Euclidean manne wirge (or the sake of simplicity) have a manner going say for in commun. Let us call the real manner r given by (7) As Fig. 1 shows, the bounded line segment A is the closed interval

[0, r] of length r > 0. (8) In Fig. 1, for every point $u_i \in [0, r]$, let $b_i \in B$ denote the foot of the perpendicular from u_t to the line segment B. Moreover, let t denote the

sal Ord Ward and Dischola March of the Book of the Boo

foot of the perpendicular from the point r of A to the line segment B. Then clearly (using notation in (4) and (5)) we have

(9)
$$|\overline{Or}| \sin \theta = d(r, t) = \max \{d(u_i, B) : u_i \in [0, r]\}$$

= $\max \{d(u_i, b_i) : u_i \in [0, r]\}$

However, from (6) it follows that

$$d(u_i, B) = \min \{d(u_i, x) : x \in B\}$$

which by (9) implies

(10)
$$\sin \theta = (\max \{\min \{d(u_i, x) : x \in B\} : u_i \in [0, r]\})/r$$

Using a more familiar notation, (10) can be expressed as

(11)
$$\sin \theta = \max_{u \in [0,r]} (\min_{x \in B} d(u,x))/r$$

where the subscript i is droppped from u_i since it was introduced in (8) only for the convenience of indicating that b_i is the foot of the perpendicular eminating from u_i .

Clearly, (11) can be more propitiously rewritten as

(12)
$$\sin A, B = \sup_{u \in [0,r]} (\inf_{x \in B} d(u,x) / r \text{ with } r = \sup_{x \in [0,r]} d(x,0)$$

From (12), with r as in the above, we deduce

(13)
$$\widehat{A,B} = \arcsin (\sup_{u \in [0,r]} (\inf_{x \in B} d(u,x)) / r \text{ with } 0 \leqslant \widehat{A,B} \leqslant \frac{\pi}{2}$$

where in the above,

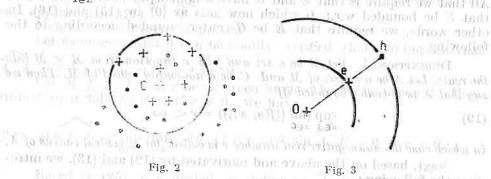
(14)
$$A$$
, B stands for "the angle between A and B " (in this order)

Remark 1. Based on (12) and (13), we observe that E, H as well as E, H can be readily defined for every bounded subset E and every subset H of the Euclidean plane which (for the sake of simplicity) have a unique point, say, 0. in common. Let us call the real number r given by All A Me I shows the bound in a control of a few could be with

(1b)
$$r = \sup_{x \in E} d(x, 0)$$
 the "central radius of E " (w.r.t.0)

As an example, let E, in Fig. 2, be the bounded set of points (each denoted by +) in the plane and H be a set of points (each denoted by.) with 0 as their unique common point. As shown in Fig. 2, every point of the set E is on or inside the circle of radius 2. Hence, the central radius of E (w.r.t.0) is 2. Thus, using notation (14), in view of (12), we have

(16)
$$\sin \widehat{E}, \widehat{H} = \sup_{u \in \widehat{E}} (\inf_{x \in H} d(u, x))/2$$
 since $r = \sup_{x \in \widehat{E}} d(x, 0) = 2$.



In general, for two bounded sets E and H in the plane the goods. Let A and B. Ale, subsets of M. with a grapeway in intersection Court

(17)
$$\sin \widehat{E}, \widehat{H} \neq \sin \widehat{H}, \widehat{E}$$
 and therefore $\widehat{E}, \widehat{H} \neq \widehat{H}, \widehat{E}$

For instance, in Fig. 3, let $E = \{0, e\}$ and $H = \{0, h\}$ with central radii respectively equal to 2 and 4. Then, according to (16), we have

$$\widehat{E}, H = \sup_{u \in \{0,e\}} (\inf_{x \in \{0,h\}} d(u,x))/2 = (\sup\{0,2\})/2,$$

$$\sin \widehat{H}, E = \sup_{u \in \{0,h\}} (\inf_{x \in \{0,e\}} d(u,x))/4 = \sup\{0,2\})/4.$$

Therefore, in Fig. 3, we have

(18)
$$\sin E, H = 1 \text{ whereas } \sin H, E = 0.5$$

which validates (17). In view of (18), we may even say that in Fig. 3

the set $\{0, e\}$ is orthogonal to the set $\{0, h\}$ man, the limit pend does of difficulties confine to be the limit for more in

the angle between the set $\{0, h\}$ and the set $\{0, e\}$ is $\pi/6$.

Remark 2. The above examples pertain to sets in the Euclidean plane where d(u, x) in (16) refers to the Euclidean distance between the points u and x of the plane.

Let us observe however, that (16) may be made meaningful in connection with points u and x of any (abstrct) set M and a function f from the Cartesian product $M \times M$ into the set of, say, real numbers. Moreover, this can be done without requiring that f satisfy any of the specific properties of a distance or a metric function. Furthermore, this can be done without requiring that E and H in (16) have a unique point in common. All that we require is that E and H have a nonempty intersection G and that E be bounded w.r.t. G which now acts as $\{0\}$ in (15) and (16). In other words, we require that E be G-center bounded according to the

DEFINITION. 1. Let M be a set and f be a function from $M \times M$ into the reals. Let A be a subset of M and C be a nonempty subset of M. Then we say that A is C-center bounded iff

(19)
$$\sup_{u \in A} \inf_{x \in C} (|f(u, x)|) = r < \infty$$

in which case the nonnegative real number r is called the C-central radius of A.

Next, based on the above and motivated by (12) and (13), we introduce the following:

DEFINITION 2. Let M be a set and f be a function from $M \times M$ into the reals. Let A and B be subsets of M with a nonempty intersection C and let A have a finite C-central radius r given by (19). Then the real number on A. H. M. S. Walthard thousand Mark & B. W. S. L. C.

A, B given below is called the angle between the set A and the set B (in this order) that amon, in Fig. 3, but K = 0, 0, and W = (9, 1, with respectively as the compact to th

(20)
$$\widehat{A}, \widehat{B} = arc \ sin \ (\sup_{u \in A} (\inf_{x \in B} (|f(u, x)|)/r) \ \text{with} \ 0 \le \widehat{A}, \widehat{B} \le \frac{\pi}{2}$$

if $r \neq 0$, and A, B = 0 if r = 0.

following:

Let us observe that if the sup appearing in (20) exists, then it is a nonnegative real number. Thus, to justify our Definition, we must prove that the sup appearing in (20) exists and its value is $\leq r$. This is shown in

THEOREM. Let M, f, A, B, C and r be as in Definition 2. Then the following sup exists and

(21)
$$0 \leq \sup_{u \in A} \left(\inf_{x \in B} (|f(u, x)|) \right) \leq r$$

Proof. For every
$$u \in A$$
, let us consider the set
$$L_u = \{|f(u, x)| : x \in B\} \text{ with } u \in A$$

Since by the hypothesis $C \subseteq B$ and C is nonempty, from (22) it follows that for every $u \in A$ it is the case that L_u is a nonempty set of nonnegative real numbers and therefore inf L_u exists. However, since $C\subseteq \bar{B},$ we have

(23)
$$0 \leq \inf L_u \leq \inf_{x \in \mathcal{C}} (|f(x, u)|) \text{ for every } u \in A$$

Next, let us consider the set $H = \{\inf L_u: \ u \in A\}$

Again, since by the hypothesis $C \subseteq A$ and C is nonempty, it follows that H is a nonempty set of real numbers. Moreover, from (19) and (23) we see that $\sup_{u \in A} H \leq \sup_{x \in C} (\inf_{x \in C} (|f(u, x)|) = r$. But $\sup_{x \in C} H$ is precisely the sup appearing in (21).

Hence, the Theorem is proved.

Let us observe that it can be readily verified that (20) implies that

 $\widehat{A}, \widehat{A} = 0$ for every subset A of M. Let M, f, A, B and r be as given in the above Definition 2. Then from (20) it follows that if $r \neq 0$, we have

(25)
$$\sin A$$
, $B = \sup_{u \in A} (\inf (|f(u, x)|))/r$ and $\sin A$, $B = 0$ if $r = 0$

i. The section of the purpose in the color of the relations Based on (25), as expected, we define $\cos A$, B as follows

(26)
$$\cos \widehat{A}, B = + (1 - \sin^2 \widehat{A}, B)^{1/2}$$

For a subset S of M, let as usual diam(S) stand for the "diameter of S", where attributes of rigurate of hest approximation by alcoholis

(27)
$$\operatorname{diam}(S) = \sup \{ |f(x, y)| : (x, y) \in S \times S \}$$

Finally, based on (26) and (27), we define the "inner product" $A \cdot B$ of the set A and the set B(in this order) to be the real number given by

(28)
$$A \cdot B = \operatorname{diam}(A) \cdot \operatorname{diam}(B) \cdot \cos A, B \text{ with } \operatorname{diam}(A) \cdot \operatorname{dim}(B) < \infty$$

Remark 3. In the above Definiton, A, B is defined for the case where the C-central radius r of A is bounded, i.e., $r < \infty$. The case $r = \infty$, as usual is handled as a limit of bounded cases.

Remark 4. Let us observe that in Fig. 1, the angle θ gives a measure

of the wedge between the lines (sets) A and B. Analogously, A, B as introduced by (20) may be used to give a measure of the wedge or the "gap" between two subsets A and B of an abstract space M with respect to a function f mapping $M \times M$ into the set of, say, real numbers. Similarly, the inner produce $A\cdot B$ as introduced by (28) may be used in defining the notion of the "projection" of a set A on a set B. Even if M and

f are quite untained, the concepts of A, B and $A \cdot B$ may still prove to be useful.

Clearly, the concepts A, B and $A \cdot B$ as introduced in (20) and (28), may become more useful if M shares more properties with a Euclidean space and f shares more properties with a metric function. In fact, this would be the case if A and B are subsets (with a nonempty intersection) of a Banach space M and f is the metric derived from the norm of M. See the References below.

The author thanks Dr. Tryphon T. Georgiou for a brief but helpful

discussion. THE WALL WE SEE THE WALL THE W

ring to be bounded as a 1 to which how note he fell gray the conductive land REFERENCES

T.T. Georgiou, On the computation of a gap metric. Systems and Control Letters 11(1988) 253-257.

2. G. M. Krasnoselskii, et al. Approximate solution of operator equations. Wolters-

Noordhoff Pub. Co., Gronong, 1972.

3. M. G. Krein, M. A. Krasnoselskii, Eundamental theorems concerning the extension of Hermitian operators. Uspekhi Mat. Nauk 2(3) 1974.

Received 7.XI.1989 Department of Mathematics Iowa State University Ames, Jowa 50011 Harm ASU to Be expected, we did the case of the toller of the

tion a subject to of "M. det are mond discuss" stand for the "discussion

Department of Let Man and the planetter from Man all a de-

of the et a suit the set from the erder to be the real number given by

(23) A.B. - dada (A)-dam (V)-os J. L-V- Aban Aban Man One os V

the court make of a thought to the court of the court of the case recent as a new last tention as a thrit of burnished cases.

mandal on the skip the base of the last of the free for the base of the last of the base o of the wodge between the linus treisyal and M. Auchgunsly, J. K. ady introduced by (20) may be used to give a insecure of the wedge or the

"grap" between two subsets dank is of an absense space with the proof had a the force produces a Association educe (SS) may be used in delicit.

bins W. Harry S. S. S. and A. Just a to "noit prompt out to appear off; and The array this general to be their a harris and the course the manufacture of the course the course

Clearly, the counsepts, J. R and A.- R we infroduced by (20) and (28) any become more useful if R district from properties with a Euclidean