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MEAN-VALUE FORMULAE FOR INTEGRALS INVOLVING GENERALIZED ORTHOGONAL POLYNOMIALS

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1. It is known that if we have a sequence of orthogonal polynomials (p_m) , associated with a nonnegative measure d α on an interval (a, b) of the real line and if we consider a function $f \in C^m(a, b)$, then we can write the following mean-value formula, of N. Cioranescu [3], for integrals:

(1)
$$\int_{a}^{b} f(x) p_{m}(x) d\alpha(x) = \frac{f^{(m)}(\xi)}{m!} \int_{a}^{b} x^{m} p_{m}(x) d\alpha(x), \ a < \xi < b.$$

In this paper we give several extensions of it to some classes of nonclassical orthogonal polynomials, including the power-orthogonal polynomials corresponding to a measure of the form $\omega d\alpha$, where ω is a nonnegative polynomial having given real multiple zeros.

It is remarkable the special case of s-orthogonal polynomials $P_{m,s}$, for which

$$\int_{a}^{b} P_{m,s}^{2s+2}(x) d\alpha(x) = \text{min, when we obtain the extension}$$

(2)
$$\int_{a}^{b} f(x) P_{m,s}^{2s+1}(x) d\alpha(x) = \frac{f^{(m)}(\xi)}{m!} \int_{a}^{b} x^{m} P_{m,s}^{2s+1}(x) d\alpha(x).$$
It reduces to formula (1) when $\alpha = 0$ (1)

It reduces to formula (1) when s = 0 (the case of ordinary orthogonal polynomials).

2. We start from a "method of parameters" (see [20]) for constructing a general Gauss-Christoffel quadrature formula by using multiple preassigned nodes and multiple free nodes.

We assume that $\alpha(x)$ has infinitely many points of increase and that $d\alpha(x)$ has finite moments of all orders.

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Let a_i be fixed nodes from the interval (a, b), given with their orders of multiplicities r_i , such that we have on (a, b)

(3)
$$\omega(x) = \varepsilon \prod_{i=1}^{n} (x - a_i)^{\eta} \ge 0 \quad \text{for} \quad \varepsilon = 1 \quad \text{or} \quad \varepsilon = -1.$$

One further considers m multiple free nodes $x_1, ..., x_m$, such that $a < x_1 < x_2 < x_2 < x_3 < x_4 < x_4 < x_4 < x_5 < x$ $< ... < x_m < b$, their orders of multiplicities being, respectively, the given odd positive integers $2s_1 + 1, ..., 2s_m + 1$.

Let u be the polynomial of the free nodes

(4)
$$u(x) = \prod_{k=1}^{m} (x - x_k)^{2s_k + 1}.$$

In 1959 the second author [20] constructed and investigated a general quadrature formula, for weighted integrals Y TELL DESCRIPTION OF THE EMPTY OF THE PARTY

$$I(g) = I(g; d\alpha) = \int_{a}^{b} g(x) d\alpha(x),$$

by using preassigned multiple nodes and multiple free nodes, of the following form

(5)
$$I(g; d\alpha) = \phi(g) + R(g; d\alpha),$$
 where

where
$$\phi(f) = \sum_{i=1}^{n} \sum_{j=0}^{r_i - 1} A_{i,j} g^{(j)}(a_i) + \sum_{k=1}^{m} \sum_{h=0}^{2s_k} B_{k,h} g^{(h)}(x_k),$$

the nodes x_k being selected such that formula (5)–(6) has the highest degree of exactness, that is, to have $R(e_r; d\alpha) = 0$ for r = 0, 1, ..., D, where e_r is the monomial $e_r(x) = x^r$ and D is as large as possible.

If at (5) we have an interpolatory quadrature formula, then we have $M \leq D$,

where
$$M = \sum_{i=1}^{n} r_i + \sum_{k=1}^{m} (2s_k + 1) - 1$$
The second of the second of

is the degree of the Lagrange-Hermite interpolation polynomial associated to the and up hiple free modes. function g and the multiple nodes a_i and x_k . If we replace in (5) $g = \omega U$, where

$$U(x) = u(x)(x-x_1)...(x-x_m) = \prod_{k=1}^{m} (x-x_k)^{2s_k+2},$$

we obtain
$$R(\omega U; d\alpha) = \int_{a}^{b} \omega(x) U(x) d\alpha(x) > 0.$$
 Since the degree of ωU is $M + m + 1$

Since the degree of ωU is M+m+1, we can conclude that the highest degree of exactness of (5) must satisfy the inequality: $D \le M + m$.

In order to construct such a quadrature formula, we have used a method of additional arbitrary nodes γ_j (j = 1, 2, ..., m), such that a_i, x_k and γ_j are distinct points from (a, b). Let $v(x) = (x - \gamma_1) \dots (x - \gamma_m)$.

The corresponding Lagrange-Hermite interpolation formula is of the form

where we have
$$g(x) = (L_H g)(x) + (rg)(x),$$

(8)
$$(L_H g)(x) = (L_H g) \left(x; \frac{a_i}{r_i}; \frac{x_k}{2s_k + 1}; \gamma_j \right)$$

(9) $(rg)(x) = \omega(x) u(x) v(x) \begin{bmatrix} a_i & x_k \\ r_i & 2s_k + 1 \end{bmatrix}, \gamma_j; x; g$

the brackets used in the remainder representing the symbol for divided differences. It is easily verified that we have (see [21])

(
$$L_H g$$
) (x) = $v(x)$ ($L_H g_1$) $\begin{pmatrix} a_i & x_k \\ x_i & \vdots \\ r_i & 2s_k + 1 \end{pmatrix} + \omega(x) u(x) (Lg_2) (x; \gamma_j),$

where $g_1 = f(x)$ and $f(x)$

where $g_1 = f / v$, $g_2 = f / (\omega u)$.

By integrating the preceding interpolation formula, we obtain a quadrature formula of the form

(10)
$$I(g; d\alpha) = \phi(g) + \Omega(g) + R(g; d\alpha),$$

where

where
$$\Omega(g) = \sum_{j=1}^{m} D_{j}g(\gamma_{j}), \quad R(g; d\alpha) = I(rg; d\alpha).$$
Because the divided difference which grows in the

Because the divided difference which occurs in the remainder is of order M+m+1, it follows that the quadrature formula (10) has the degree of exactness D = M + m. To such the processing of the stable processing the

Now we seek to determine the nodes x_k , having respectively the given orders of multiplicities $2s_k + 1$, such that $D_1 = ... = D_m = 0$. Because

$$D_{j} = \int_{a}^{b} \frac{\omega(x) u(x) v_{j}(x)}{\omega(\gamma_{j}) u(\gamma_{j}) v_{j}(\gamma_{j})} d\alpha(x), \quad v_{j}(x) = \frac{v(x)}{x - \gamma_{j}},$$

it follows that we should have the should have

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$$I(\omega uv_j; d\alpha) = 0 \quad (j = 1, 2, ..., m).$$

Taking into account that γ_i are arbitrary, it follows that $D_i = 0$ if and only if the polynomial u is orthogonal on (a, b), with respect to the distribution $\omega d\alpha$, to all polynomials of degree at most m-1.

Consequently, we arrive at the following system of m equations in madditional modes γ_{ij} (j = i, 2, ..., m), such that m

unknowns $x_1, ..., x_m$:

unknowns
$$x_1, ..., x_m$$
:
$$\int_a^b \omega(x) u(x) x^k d\alpha(x) = 0 \text{ ($k = 0, 1, ..., m-1$)}.$$

The solution of the system (12) identifies with the solution of the following extremal problem:

(13)
$$I(U; d\alpha) = \int_{a}^{b} \omega(x) (x - x_1)^{2s_1 + 2} \dots (x - x_m)^{2s_m + 2} d\alpha(x) = \min.$$

The nodes x_k , with given odd orders of multiplicities, which are determined by (12) or by (13), will be called Gaussian nodes, corresponding to the measure $\omega(x) d\sigma(x)$.

3. Given the sequence of nonnegative integers $\sigma = (s_1, ..., s_m)$ and the measure $\omega d\alpha$, the relations (12) permit us to define a sequence of polynomials

(14)
$$P_{k,\sigma}(x) = (x - x_{1,\sigma}) \dots (x - x_{k,\sigma}), \quad a < x_{1,\sigma} < \dots < x_{k,\sigma} < b$$

such that

$$\int_a^b \omega(x) P_{k,\sigma}(x) Q_{m,\sigma}(x) d\alpha(x) = 0 \quad (0 \le k \le m-1),$$
 where

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where

(15)
$$Q_{m,\sigma}(x) = \prod_{j=1}^{m} (x - x_{j,\sigma})^{2s_j + 1}.$$

The polynomials $P_{k,\sigma}$ represent a sequence of σ -orthogonal polynomials, corresponding to the measure $\omega d\alpha$ and the interval (a, b).

Such a new type of orthogonality was considered in many papers: [24], [2], [17], [5], [7], [8] and [15]. In [10] it was given a stable procedure for the numerical now we mak to determine construction of the σ -orthogonal polynomials.

4. Once the nodes $x_k = x_{k,\sigma}$ are determined, we can see that formula (10) reduces to the form (5)-(6). In [20] there was proved that the coefficients of formula (10) do not depend on the nodes γ_j . Since the remainder $R(g; d\alpha)$

should also be independent of these parameters, let us make $\gamma_j \rightarrow x_j \ (j=1,2,...,m)$ in the remainder given at (9), (10) and (11). We obtain

(16)
$$R(g; d\alpha) = \int_{a}^{b} \omega(x) U(x) D_{n}(g; x) d\alpha(x),$$

where

(17)
$$D_{1}(g;x) = \left[x; \frac{a_{i}}{r_{i}}; \frac{x_{k}}{2x_{k}+2}; g(t)\right].$$

Because $\omega(x) U(x) \ge 0$ on (a, b), we can apply the mean-value theorem of the integral calculus and we get

$$R(g; d\alpha) = D_1(g; \eta) \int_a^b \omega(x) U(x) d\alpha(x), \quad \eta \in (a, b).$$

Assuming that $f \in C^{N+1}(a,b)$, where N = M + m, we can use the meanvalue theorem of divided differences and we find

$$R(g; d\alpha) = \frac{g^{(N+1)}(\xi)}{(N+1)!} \int_a^b \omega(x) U(x) d\alpha(x).$$

5. The quadrature rule (10), containing the parameters $\gamma_1, \dots, \gamma_m$, can be used for obtaining generalizations of the mean-value formula (1) of N. Cioranescu. Indeed, if we replace $g = \omega f u$, we obtain

$$I(\omega f u; d\alpha) = \int_{a}^{b} \omega(x) u(x) v(x) \Omega(\omega f u; x) d\alpha(x),$$

$$\Omega(\omega f u; x) = \left[x; \frac{a_i}{r_i}; \frac{x_k}{2s_k + 1}; \gamma_1, \dots, \gamma_m; \omega(t) f(t) u(t)\right].$$

But, according to an "absorption formula" from the theory of divided differences, we can write orthogenal polynomials

$$\Omega(\omega f u; x) = [x, \gamma_1, \dots, \gamma_n; f(t)].$$

Hence we have
$$I(\omega f u; d\alpha) = \int_{a}^{b} \omega(x) u(x) v(x) [x, \gamma_1, ..., \gamma_m; f(t)] d\alpha(x).$$

Because the second side of this equality must also be independent of the parameters $\gamma_1, ..., \gamma_m$, we shall consider the limiting case $\gamma_k \to x_k$.

Consequently, we obtain the following formula

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$$\int_{a}^{b} \omega(x) f(x) Q_{m,\sigma}(x) d\alpha(x) =$$

$$= \int_{a}^{b} \omega(x) P_{m,\sigma}(x) Q_{m,\sigma}(x) [x, x_1, ..., x_m; f(t)] d\alpha(x),$$

where we have used the notations (14) and (15) and for shortness: $x_{k,\sigma} = x_k$.

Applying the mean-value formula to the integral from the second side of this equality, we get

(18)
$$\int_{a}^{b} \omega(x) f(x) Q_{m,\sigma}(x) d\alpha(x) =$$

$$= [\eta, x_{1}, ..., x_{m}; f(t)] \int_{a}^{b} \omega(x) P_{m,\sigma}(x) Q_{m,\sigma}(x) d\alpha(x).$$

Since $P_{m,\sigma}(x) Q_{m,\sigma}(x) = Q_{m,\sigma}(x^m + ...)$, if we use the orthogonality relations we may conclude that we have the following important mean-value formula

(19)
$$\int_{a}^{b} \omega(x) f(x) Q_{m,\sigma}(x) d\alpha(x) =$$

$$= [\eta, x_{1}, \dots, x_{m}; f(t)] \int_{a}^{b} \omega(x) x^{m} Q_{m,\sigma}(x) d\alpha(x).$$

If $f \in C^m(a,b)$ and we have no preassigned nodes, by applying the meanvalue formula to the divided difference involved, we get the following mean-value formula for the integrals, corresponding to the power-orthogonal polynomials:

(20)
$$\int_{a}^{b} f(x) Q_{m,\sigma}(x) d\alpha(x) = \frac{f^{(m)}(\xi)}{m!} \int_{a}^{b} x^{m} Q_{m,\sigma}(x) d\alpha(x), \quad a < \xi < b.$$

When $s_1 = ... = s_m = 0$ we are in the case of standard orthogonal polynomials and we arrive at the formula (1) of N. Cioranescu [3], while if $s_1 = ... = s_m = s$ we obtain the extension (2) of it, corresponding to the s-orthogonal polynomials $P_{m,s}$, in the sense of Turán, Ghizzetti, Ossicini, Rosati, Gori, Gautschi, Milovanović and their collaborators: [24], [6], [8], [5], [9], [10], [4], [14].

6. Now we want to find a formula which is similar to (19), by using the theory of T. Popoviciu [19] on functionals of simple form, having a certain degree of exactness. We consider the linear functional F defined by

If we take into account the equality (18), we can write $F(e_i) = 0$ $(j=0,1,\ldots,m-1),\ F(e_m)>0.$ It follows that the functional F has the degree of exactness m-1

Let us denote by $\varphi_m(x;t)$ the spline function

$$\varphi_m(x;t) = \left(\frac{x - t + |x - t|}{2}\right)^{m-1},$$

which has a continuous derivative of order m-2, and is non-concave of order m-3.

Since $F(\phi_m) \ge 0$ on (a, b), by using a theorem of Popoviciu [19] we can conclude that there exist m+1 distinct points $t_1, ..., t_{m+1}$ in (a, b)such that

$$F(f) = F(e_m)[t_1, ..., t_{m+1}; f(t)].$$

According to (18) we have well a surface of the sur

$$F(e_m) = \int_a^b \omega(x) P_{m,\sigma}(x) Q_{m,\sigma}(x) d\alpha(x).$$

Consequently, we obtain the representation

$$\int_{a}^{b} \omega(x) f(x) Q_{m,\sigma}(x) d\alpha(x) =$$

$$= [t_1, ..., t_{m+1}; f(t)] \int_a^b \omega(x) P_{m,\sigma}(x) Q_{m,\sigma}(x) d\alpha(x).$$

Formula (18) has on it the advantage that the m nodes involved are known to be the zeros of the power orthogonal polynomial $P_{m,\sigma}(x)$.

7. In the case when we have no preassigned nodes, $s_k = s (k = 1, ..., m)$ and $d\alpha(x) = w(x) dx$, we can write: $Q_{m,\sigma}(x) = P_{m,s}^{2s+1}(x)$, where $P_{m,s}(x) =$ $=(x-x_1)\dots(x-x_m)$ represents the s-orthogonal polynomial with respect to the weight function w on the interval (a, b). Approximation 3 (1974), 79-84.

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Investigations on the s-orthogonal polynomials, minimizing the integral

 $\int_{0}^{b} w(x) P_{m,s}^{2s+2}(x) dx$, have been done by many mathematicians: D. Jackson [12],

P. Turán [24], T. Popoviciu [17], L. Chakalov [2], A. Ghizzetti and A. Ossicini ([5], [6] and [7]), L. Gori [8], W. Gautschi [4], G. V. Milovanović [14], and others. In 1930 S. Bernstein [1] proved that, if (a, b) = (-1, 1) and $w(x) = (1 - x^2)^{-1/2}$, the extremal polynomial is just the Chebyshev polynomial of the first kind, for any nonnegative integer s.

There are other cases of weight functions (see [16] and [9]) for which the corresponding s-orthogonal polynomials are independent of the values of s.

Finally, we want to mention that, by using the mean-value formulae established in this paper, it will be important to investigate the generalized Fourier expansions of a function f in s or σ -orthogonal polynomials.

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