

$$(v, u - \theta) \chi = (v, u - \theta)(A \cap V) \chi = (v, 0) \chi \quad (1.2.1)$$

$$(v, u - \theta) \chi = (v - \theta, u)(A \cap (0, v)) \chi = (0, v) \chi \quad (1.2.1)$$

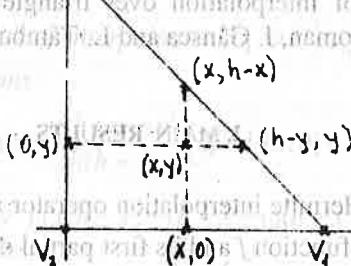
ABOUT SOME INTERPOLATION FORMULAS OVER TRIANGLES

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1. PRELIMINARIES

Beginning with the paper by Barnhill, Birkhoff and Gordon [1], the interpolation problem to boundary data on a triangle was largely studied. Considering the standard triangle $T_h = \{(x, y) \in R^2 \mid x \geq 0, y \geq 0, x + y \leq h\}$ with the vertices $V_1 = (h, 0), V_2 = (0, h), V_3 = (0, 0)$ and the opposite sides denoted by E_1, E_2, E_3 (fig. 1), in [1] there are constructed some interpolants which match a given function $f: T_h \rightarrow R$ on the sides of the triangle T_h .

Fig. 1



The ideas from [1] will be shortly presented. Let be $(x, y) \in \text{int} T_h$ and let be L_1^x, L_1^y the linear operators along the parallel to the side E_2 , respectively to the side E_1 , i.e.

$$(1.1) \quad L_1^x(f)(x, y) = Ax + B \quad L_1^y(f)(x, y) = Cy + D,$$

where the coefficients A, B, C, D are determined from the conditions

1991 AMS Subject Classification: 41-00, 41A10, 41A25.

Key words: blending interpolant, boolean sum operator.

$$(1.2.1) \quad L_1^x(f)(0,y) = f(0,y), \quad L_1^x(f)(h-y,y) = f(h-y,y)$$

$$(1.2.2) \quad L_1^y(f)(x,0) = f(x,0), \quad L_1^y(f)(x,h-x) = f(x,h-x)$$

Solving the linear algebraic systems (1.2.1), (1.2.2) the operators become:

$$(1.3.1) \quad L_1^x(f)(x,y) = \frac{h-x-y}{h-y} \cdot f(0,y) + \frac{x}{h-y} \cdot f(h-y,y)$$

$$(1.3.2) \quad L_1^y(f)(x,y) = \frac{h-x-y}{h-x} \cdot f(x,0) + \frac{y}{h-x} \cdot f(x,h-x)$$

By direct substitution the equalities (1.2.1), (1.2.2) follow for any $x, y \in [0, h]$, which prove that $L_1^x(f)$ interpolates the function f on the sides E_1 , E_3 of T_h and $L_1^y(f)$ interpolates the function f on the sides E_1 and E_3 of T_h .

The boolean sum operator $L_1^x \oplus L_1^y = L_1^x + L_1^y - L_1^x L_1^y$ (see [8]) defines the so called "blending interpolant" $(L_1^x \oplus L_1^y)(f)$. By simply computation

$$(1.4) \quad (L_1^x \oplus L_1^y)(f)(x,y) = \frac{h-x-y}{h-y} \cdot f(0,y) + \frac{h-x-y}{h-x} \cdot f(x,0) + \frac{y}{h-x} \cdot f(x,h-x) - \frac{h-x-y}{h} \cdot f(0,0) - \frac{y}{h(h-y)} \cdot f(0,h)$$

From (1.4) it is easy to see that $(L_1^x \oplus L_1^y)(f) = f$ on ∂T_h where ∂T_h is the boundary of the standard triangle T_h . Important contributions to the development of the theory of interpolation over triangle are due to the Romanian mathematicians Gh. Coman, I. Gânsca and L. Tambulea [5], [6], [7], [8].

2. MAIN RESULTS

Let H_2^y be the Hermite interpolation operator along the parallel to the side E_1 which matches the function f and its first partial derivative with respect to y at the point $(x, 0)$ and also the function f at $(x, h-x)$. Let H_2^x be the Hermite interpolation operator along the parallel to the side E_2 which matches the function f and its first partial derivative with respect to x at the point $(0, y)$ and also the function f at $(h-y, y)$.

LEMMA 2.1. *The equalities*

$$(2.2.1) \quad H_2^y(f)(x,y) = \frac{y(h-x-y)}{h-x} \cdot f^{(0,1)}(x,0) + \frac{y^2}{(h-x)^2} \cdot f(x,h-x) + \frac{(h-x-y)(h-x+y)}{(h-x)^2} \cdot f(x,0)$$

$$(2.2.2) \quad H_2^x(f)(x,y) = \frac{x(h-x-y)}{h-y} \cdot f^{(1,0)}(0,y) + \frac{x^2}{(h-y)^2} \cdot f(h-y,y) + \frac{(h-x-y)(h-x+y)}{(h-y)^2} \cdot f(0,y) \text{ hold for any } x, y \in [0, h].$$

Proof. Clearly $H_2^y(f)$ is a polynomial of degree two with respect to y and $H_2^x(f)$ is a polynomial of degree two with respect to x , i.e. $H_2^y(f)(x,y) = Ay^2 + By + C$ and $H_2^x(f)(x,y) = Dx^2 + Ex + F$ which satisfy the interpolation conditions:

$$(2.3.1) \quad H_2^y(f)(x,0) = f(x,0), \quad H_2^y(f)^{(0,1)}(x,0) = f^{(0,1)}(x,0), \\ H_2^y(f)(x,h-x) = f(x,h-x).$$

$$(2.3.2) \quad H_2^x(f)(0,y) = f(0,y), \quad H_2^x(f)^{(0,1)}(0,y) = f^{(0,1)}(0,y), \\ H_2^x(f)(h-y,y) = f(h-y,y).$$

Using these conditions one arrives to (2.2.1) and (2.2.2).

Remark 2.2. $H_2^y(f)$ interpolates the functions f and its partial derivative with respect to y on the side E_1 and also the function f on the side E_3 and $H_2^x(f)$ interpolates the function f and its partial derivative with respect to x on the side E_2 and also the function f on the side E_3 .

LEMMA 2.3. *The blending interpolants $(L_1^x \oplus H_2^y)(f)$ and $(L_1^y \oplus H_2^x)(f)$ have the following expressions:*

$$(2.4.1) \quad (L_1^x \oplus H_2^y)(f)(x,y) = \frac{y(h-x-y)}{h(h-x)} \left\{ hf^{(0,1)}(x,0) + (x-h)f^{(0,1)}(0,0) \right\} + \\ + \frac{1}{(h-x)^2} \left\{ y^2 f(x,h-x) + (h-x-y)(h-x+y)f(x,0) \right\} + \\ + \frac{h-x-y}{h-y} f(0,y) - \frac{h-x-y}{h^2(h-y)} \left\{ y^2 f(0,h) + (h^2 - y^2)f(0,0) \right\},$$

$$(2.4.2) \quad (L_1^y \oplus H_2^x)(f)(x,y) = \frac{x(h-x-y)}{h(h-y)} \left\{ hf^{(1,0)}(0,y) + (y-h)f^{(1,0)}(0,0) \right\} + \\ + \frac{1}{(h-y)^2} \left\{ x^2 f(h-y,y) + (h-x-y)(h-x+y)f(0,y) \right\} + \\ + \frac{h-x-y}{h-x} f(x,0) - \frac{h-x-y}{h^2(h-x)} \left\{ x^2 f(h,0) + (h^2 - x^2)f(0,0) \right\}.$$

Proof. First one calculates the product $(L_1^x H_2^y)(f)$ and one obtains:

$$\begin{aligned}(L_1^x H_2^y)(f)(x,y) &= \frac{h-x-y}{h-y} H_2^y(f)(0,y) + \frac{x}{h-y} H_2^y(f)(h-y,y) = \\ &= \frac{y(h-x-y)}{h} f^{(0,1)}(0,0) + \frac{y^2(h-x-y)}{h^2(h-y)} f(0,h) + \\ &\quad + \frac{(h-x-y)(h+y)}{h^2} f(0,0) + \frac{x}{h-y} f(h-y,y).\end{aligned}$$

Then, taking into account that $L_1^x \oplus L_1^y = L_1^x + L_1^y - L_1^x L_1^y$ it follows that (2.4.1) holds. In a similar way, (2.4.2) holds.

THEOREM 2.1. The operators $L_1^x \oplus H_2^y$ and $L_1^y \oplus H_2^x$

$$(2.5.1) \quad (L_1^x \oplus H_2^y)(f) = f \text{ on } \partial T_h, \quad (L_1^x \oplus H_2^y)^{(0,1)}(f) = f^{(0,1)} \text{ on } E_1,$$

$$(2.5.2) \quad (L_1^y \oplus H_2^x)(f) = f \text{ on } \partial T_h, \quad (L_1^y \oplus H_2^x)^{(1,0)}(f) = f^{(1,0)} \text{ on } E_2.$$

Proof. By direct substitution one obtains

$$\begin{aligned}(L_1^x \oplus H_2^y)(f)(x,0) &= \frac{1}{(h-x)^2} (h-x)^2 f(x,0) + \frac{h-x}{x} f(0,0) - \\ &\quad - \frac{h-x}{h^3} h^2 f(0,0) = f(x,0)\end{aligned}$$

which proves that $(L_1^x \oplus H_2^y)(f) = f$ on E_2 . In a similar way one proves that $(L_1^x \oplus H_2^y)(f) = f$ on E_1 and on E_3 . Next, one compute the first partial derivative with respect to y at $(x, 0)$ and one obtains:

$$\begin{aligned}(L_1^x \oplus H_2^y)^{(0,1)}(f)(x,y) &= \frac{h-x-2y}{h(h-x)} \left\{ hf^{(0,1)}(x,0) + (x-h)f^{(0,1)}(0,0) \right\} + \\ &\quad + \frac{2y}{(h-x)^2} \left\{ f(x, h-x) - f(x, 0) \right\} + \frac{x}{(h-y)^2} f^{(0,1)}(0,y) + \\ &\quad + \frac{x}{h^2(h-y)^2} \left\{ y^2 f(0,h) + (h^2 - y^2) f(0,0) \right\} - \\ &\quad - \frac{h-x-y}{h^2(h-y)} \left\{ 2y f(0,h) - 2y \cdot f(0,0) \right\}\end{aligned}$$

$$\begin{aligned}\text{So, with } y=0, \quad (L_1^x \oplus H_2^y)^{(0,1)}(f)(x,0) &= f^{(0,1)}(x,0) + \frac{x-h}{h} f^{(0,1)}(0,0) - \\ &\quad - \frac{x}{h^2} f(0,0) + \frac{h-x}{h} f^{(0,1)}(0,0) + \frac{x}{h^2} f(0,0) = f^{(0,1)}(x,0)\end{aligned}$$

In a similar way, one obtains (2.5.2).

Remark 2.4. The multiplicity of the knots $(x, 0)$, $(x, h-x)$ and respectively $(0, y)$, $(h-y, y)$ can be inverted.

Remark 2.5. Considering the boolean sum operator $(H_2^x \oplus H_2^y)$ one obtains the blending function interpolant $(H_2^x \oplus H_2^y)(f)$. This function interpolates f on ∂T_h and its partial derivatives $f^{(0,1)}$ and $f^{(1,0)}$ on E_1 and respectively on E_2 .

Remark 2.6. The interpolation procedures which were presented above have many applications in computer aided geometry (see [7], [8]).

Using the boolean sum operators we can consider now the following approximation formulas:

$$f = (L_1^x \oplus H_2^y)(f) + R_{12}^{xy} f, \quad f = (L_1^y \oplus H_2^x)(f) + R_{12}^{yx} f,$$

where R_{12}^{xy} and R_{12}^{yx} are the corresponding remainder terms.

THEOREM 2.2. If $f \in B_{12}(0, 0)$ then the remainder term R_{12}^{xy} is:

$$\begin{aligned}R_{12}^{xy}(f)(x,y) &= \int_0^h K_{30}(x,y,s) f^{(3,0)}(s,0) ds + \int_0^h K_{21}(x,y,s) f^{(2,1)}(s,0) ds + \\ &\quad + \int_0^h K_{03}(x,y,t) f^{(0,3)}(0,t) dt + \int_0^h \int_0^h K_{12}(x,y,s,t) f^{(1,2)}(s,t) ds dt\end{aligned}$$

where

$$K_{30}(x,y,s) = \frac{(x-s)_+^2}{2}, \quad K_{21}(x,y,s) = y \cdot (x-s)_+,$$

$$K_{03}(x,y,t) = \frac{y^2}{(h-x)^2} \cdot \frac{(h-x-t)_+^2}{2} + \frac{h-x-y}{h-y} \cdot \frac{(y-t)_+^2}{2} - \frac{y^2(h-x-y)(h-t)^2}{2h^2(h-y)}$$

$$K_{12}(x,y,s,t) = \frac{y}{h-x} (x-s)_+^0 \left[h-x-y + \frac{y}{h-x} \cdot (h-x-t)_+ \right].$$

Proof. Taking into account that $R_{12}^{xy} f = f$, $(\forall) f \in P_2^2$, the proof follows by the Sard kernel theorem in triangles [1], with

$$K_{30}(x,y,s) = (L_1^x \oplus H_2^y) \left[\frac{(x-s)_+^2}{2} \right], \quad K_{21}(x,y,s) = (L_1^x \oplus H_2^y)[(x-s)_+ \cdot y],$$

$$K_{03}(x,y,t) = (L_1^y \oplus H_2^x) \left[\frac{(y-t)_+^2}{2} \right],$$

$$K_{12}(x,y,s,t) = (L_1^y \oplus H_2^x)[(x-s)_+^0 \cdot (y-t)_+].$$

THEOREM 2.3. If $f \in B_2(0, 0)$ then the remainder term R_{12}^{xy} has the expression:

$$R_{12}^{xy}(f)(x, y) = \int_0^h K_{30}(x, y, s)f^{(3,0)}(s, 0)ds + \int_0^h K_{12}(x, y, s)f^{(1,2)}(s, 0)ds + \\ + \int_0^h \int_0^h K_{03}(x, y, t)f^{(0,3)}(0, t)dt + \int_0^h \int_0^h K_{21}(x, y, s, t)f^{(2,1)}(s, t)ds dt$$

where

$$K_{30}(x, y, s) = \frac{(y-s)_+^2}{2}, \quad K_{12}(x, y, s) = x \cdot (y-s)_+,$$

$$K_{03}(x, y, t) = \frac{x^2}{(h-y)^2} \cdot \frac{(h-y-s)_+^2}{2} + \frac{h-x-y}{h-x} \cdot \frac{(x-s)_+^2}{2} - \frac{x^2(h-x-y)(h-s)^2}{2h^2(h-x)}$$

$$K_{21}(x, y, s, t) = \frac{x}{h-y} (y-t)_+^0 \left[h-x-y + \frac{x}{h-y} \cdot (h-y-s)_+ \right].$$

Proof. Taking into account that $R_{12}^{xy} f = f$, $(\forall) f \in P_2^2$, the proof follows by the Sard kernel theorem in triangles [1], with

$$K_{30}(x, y, s) = (L_1^x \oplus H_2^y) \left[\frac{(x-s)_+^2}{2} \right], \quad K_{12}(x, y, t) = (L_1^x \oplus H_2^y) [(y-t)_+ \cdot x],$$

$$K_{03}(x, y, t) = (L_1^x \oplus H_2^y) \left[\frac{(y-t)_+^2}{2} \right],$$

$$K_{21}(x, y, s, t) = (L_1^x \oplus H_2^y) [(x-s)_+ \cdot (y-t)_+^0].$$

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Received December 10, 1997

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The Clément method introduced by Clement [11], and which we shall describe in the following section, is a known method for solving large linear systems. When it is used by a Delréen method, the pointwise estimate of the error passes through refinement applying three negative steps.

The first result was given by Driscoll and Flaherty in [12], for finite elements. It is review the source, setting $\Omega \subset \mathbb{R}^2$, $D \subset \Omega^n$, the local approximation of different Newton's [13] methods already made under the following simplified assumptions:

- (C1) there exists $y^* \in D$ such that $\delta(y^*) = 0$
- (C2) the function δ is differentiable in a neighborhood of y^* and the derivative δ' is continuous at y^*
- (C3) the function $\delta'(y^*)$ is non-negative, $\delta''(y^*) > 0$.

We shall denote hereafter by $\{\cdot\}_k$ an array having length k in \mathbb{R}^n or in dual space $H^1(\Omega)$. The symbol $\{\cdot\}_k$ stands for the k -th column vector and $\{\cdot\}_k$ denotes the transpose $\{\cdot\}_k$. For definitions and properties concerning the matrix operations we refer to [14, ch. 9] and chapter [18].

Theorem 1. [12] Let $L \in \mathbb{R}^{n \times n}$ be a symmetric and positive definite matrix, $D \subset \mathbb{R}^n$ and assume that for some $\rho \in \mathbb{R}$ we have $\rho I \leq L \leq \rho^{-1}I$ and $\rho^{-1}L$ satisfies (C1) and (C2). Then there is a sequence of semi regular meshes τ_k such that δ_k from (1) is well defined and D the quadrature rule given by

What summarizes the Delréen algorithm is the following:
1.1. A triangular domain Ω is partitioned into n subtriangles.