

LOCAL CONVERGENCE
OF GENERAL STEFFENSEN TYPE METHODS*

ION PĂVĂLOIU[†]

Abstract. We study the local convergence of a generalized Steffensen method. We show that this method substantially improves the convergence order of the classical Steffensen method. The convergence order of our method is greater or equal to the number of the controlled nodes used in the Lagrange-type inverse interpolation, which, in its turn, is substantial higher than the convergence orders of the Lagrange type inverse interpolation with uncontrolled nodes (since their convergence order is at most 2).

MSC 2000. 65H05.

Keywords. Nonlinear scalar equations, Steffensen type method.

1. INTRODUCTION

In this paper we study the local convergence of some general methods of Aitken-Steffensen type, which are based on inverse interpolation of Lagrange type.

Let $f : [a, b] \rightarrow \mathbb{R}$, $a, b \in \mathbb{R}$, $a < b$ be a function and x_i , $i = \overline{0, n}$, $n + 1$ distinct points in $[a, b]$, which we call interpolation nodes. Denote $y_i = f(x_i)$, $i = \overline{0, n}$, and suppose that $y_i \neq y_j$ for $i \neq j$. Assume in the beginning that $f : I \rightarrow f(I)$, $I = [a, b]$ is one-to-one, i.e., there exists $f^{-1} : f(I) \rightarrow I$. Consider the Lagrange polynomial with the interpolation nodes y_i , $i = \overline{0, n}$ and the values of f^{-1} on these nodes $x_i = f^{-1}(y_i)$, $i = \overline{0, n}$. This is the inverse interpolation polynomial, which we denote by $L(y_0, y_1, \dots, y_n; f^{-1} | y)$, and it can be represented in the Lagrange form

$$(1) \quad L(y_0, y_1, \dots, y_n; f^{-1} | y) = \sum_{i=0}^n \frac{x_i \omega(y)}{(y - y_i) \omega'(y_i)}, \quad \omega(y) = \prod_{i=0}^n (y - y_i)$$

and in the Newton form:

$$(2) \quad L(y_0, y_1, \dots, y_n; f^{-1} | y) = x_0 + [y_0, y_1; f^{-1}](y - y_0) \\ + [y_0, y_1, y_2; f^{-1}](y - y_0)(y - y_1) + \dots \\ + [y_0, y_1, \dots, y_n; f^{-1}](y - y_0)(y - y_1) \cdots (y - y_{n-1}),$$

*This work has been supported by the Romanian Academy under grant GAR 16/2004.

[†]“T. Popoviciu” Institute of Numerical Analysis, O.P. 1, C.P. 68, Cluj-Napoca, Romania,
e-mail: pavaloiu@ictp.acad.ro.

where $[y_0, \dots, y_i; f^{-1}]$, $i = \overline{1, n}$ denotes the i -th order divided difference of the function f^{-1} on the nodes y_0, \dots, y_i .

Assuming that f admits derivatives up to the order $n + 1$ on the interval $[a, b]$, then

$$(3) \quad f^{-1}(y) = L(y_0, y_1, \dots, y_n; f^{-1}|y) + \frac{[f^{-1}(\xi)]^{(n+1)}}{(n+1)!} \omega(y)$$

where ξ is a point belonging to the smallest interval containing y, y_0, \dots, y_n . Denote

$$R_n[f^{-1}; y] = \frac{[f^{-1}(\xi)]^{(n+1)}}{(n+1)!} \omega(y).$$

Consider now the equation

$$(4) \quad f(x) = 0.$$

If it has a solution $\bar{x} \in [a, b]$, then obviously

$$(5) \quad \bar{x} = f^{-1}(0).$$

An approximation of the solution \bar{x} can be obtained from (3) for $y = 0$, i.e.,

$$(6) \quad \bar{x} = L(y_0, y_1, \dots, y_n; f^{-1}|0) + R_n[f^{-1}; 0],$$

whence, by neglecting the remainder $R_n[f^{-1}; 0]$ we get

$$(7) \quad x_{n+1} = L(y_0, y_1, \dots, y_n; f^{-1}|0),$$

and the error

$$(8) \quad \bar{x} - x_{n+1} = R_n[f^{-1}; 0].$$

Denoting $M = \sup_{y \in f(I)} |[f^{-1}(y)]^{(n+1)}|$, then

$$(9) \quad |\bar{x} - x_{n+1}| \leq \frac{M}{(n+1)!} |y_0| |y_1| \cdots |y_n|.$$

Assuming that $x_{n+1} \in [a, b]$ and denoting $y_{n+1} = f(x_{n+1})$, then we can obtain a new approximation x_{n+2} given by relation

$$(10) \quad x_{n+2} = L(y_1, y_2, \dots, y_n, y_{n+1}; f^{-1}|0),$$

where, as it can be seen, the node x_0 has been neglected and instead we consider y_{n+1} . The above procedure may continue indefinitely: assuming that we have obtained the approximations $x_k, x_{k+1}, \dots, x_{k+n} \in [a, b]$ then the next approximation is given by

$$(11) \quad x_{n+k+1} = L(y_k, y_{k+1}, \dots, y_{n+k}; f^{-1}|0), \quad k = 0, 1, \dots,$$

where $y_{k+i} = f(x_{k+i})$, $i = \overline{0, n}$. If all the iterates are contained in $[a, b]$, then the procedure may continue indefinitely.

In the same way as for (9), we get the following error bound:

$$(12) \quad |\bar{x} - x_{n+k+1}| \leq \frac{M}{(n+1)!} |y_k| |y_{k+1}| \cdots |y_{k+n}|, \quad k = 0, 1, \dots,$$

Assume that $f'(x) \neq 0, \forall x \in [a, b]$, and denote

$$m = \sup_{x \in I} |f'(x)|.$$

Obviously

$$(13) \quad |\bar{x} - x| \geq \frac{|f(x)|}{m}.$$

By (12) and (13)

$$(14) \quad |f(x_{n+k+1})| \leq \frac{mM}{(n+1)!} |f(x_k)| |f(x_{k+1})| \cdots |f(x_{k+n})|, \quad k = 0, 1, \dots$$

Multiplying relations (14) by $\left(\frac{mM}{(n+1)!}\right)^{\frac{1}{n}}$ and denoting

$$\rho_i = \left(\frac{mM}{(n+1)!}\right)^{\frac{1}{n}} |f(x_i)|, \quad i = 0, 1, \dots$$

leads to

$$(15) \quad \rho_{n+k+1} \leq \rho_k \rho_{k+1} \cdots \rho_{k+n}, \quad k = 0, 1, \dots$$

Suppose now that $\rho_i \leq d^{\alpha_i}$, with $0 < d < 1$ and $\alpha_i \in \mathbb{R}, \alpha_i > 0, i = \overline{0, n}$. Then

$$(16) \quad \rho_{n+1} \leq d^{\alpha_0 + \alpha_1 + \cdots + \alpha_n} = d^{\alpha_{n+1}},$$

where

$$(17) \quad \alpha_{n+1} = \alpha_n + \alpha_{n-1} + \cdots + \alpha_1 + \alpha_0.$$

In general, from (15) it follows

$$(18) \quad \rho_{n+k+1} \leq d^{\alpha_{n+k+1}},$$

where

$$(19) \quad \alpha_{n+k+1} = \alpha_{n+k} + \alpha_{n+k-1} + \cdots + \alpha_{k+1} + \alpha_k, \quad n = 0, 1, \dots$$

Let now $t_0 > 0$ be the unique positive solution of equation

$$(20) \quad t^{n+1} - t^n - t^{n-1} - \cdots - t - 1 = 0.$$

Assume that the values of f obey

$$(21) \quad \rho_i \leq d^{\alpha t_0^i}, \quad i = \overline{0, n},$$

for a certain constant $\alpha > 0$, i.e., $\alpha_i = \alpha t_0^i$. Then one can show by induction using (19) that

$$(22) \quad \rho_{n+k+1} \leq d^{\alpha t_0^{n+k+1}}, \quad k = 0, 1, \dots$$

In [7] it is shown that t_0 verifies $\frac{2(n+1)}{n+2} < t_0 < 2$. It is clear that the convergence order of the sequence given in (11) is less than 2.

In order to increase the convergence order of the sequence we proceed as follows. Consider the following equation, equivalent to (4):

$$(23) \quad x - g(x) = 0.$$

We shall choose the interpolation nodes in (11) using g , generalizing in this way the Steffensen method.

2. GENERAL METHODS OF STEFFENSEN TYPE

Assume in the beginning that for all $x \in [a, b]$, it follows that $g(x) \in [a, b]$.

Let $u_0 \in [a, b]$ be an initial approximation of the solution \bar{x} of equation (14). We shall use the following notations:

$$(24) \quad x_0 = u_0, \quad x_1 = g(x_0), \quad x_2 = g(x_1), \dots, \quad x_n = g(x_{n-1}),$$

which, by (7) lead to a new approximation for \bar{x}

$$(25) \quad u_1 = L(y_0, y_1, \dots, y_n; f^{-1}|0),$$

where $y_i = f(x_i)$, $i = \overline{0, n}$, x_i being given by (24).

From (9) we get:

$$(26) \quad |\bar{x} - u_1| \leq \frac{M}{(n+1)!} |f(x_0)| |f(x_1)| \cdots |f(x_n)|,$$

whence, by (13) we get

$$(27) \quad |\bar{x} - u_1| \leq \frac{Mm^{n+1}}{(n+1)!} |\bar{x} - x_0| |\bar{x} - x_1| \cdots |\bar{x} - x_n|.$$

Assume that g obeys the Lipschitz condition on $[a, b]$, i.e. there exists $l > 0$ such that

$$|g(x) - g(y)| \leq l|x - y|, \quad \forall x, y \in [a, b].$$

Under this hypothesis, taking into account (24), we are lead to

$$(28) \quad |\bar{x} - u_1| \leq \frac{M \cdot m^{n+1} \cdot l^{\frac{n(n+1)}{2}}}{(n+1)!} |\bar{x} - u_0|^{n+1}.$$

Let now u_1 be the next approximation for \bar{x} ; then, analogously to (24), we consider in (7) the following values to f^{-1} at the interpolation nodes:

$$(29) \quad x_0 = u_1, \quad x_1 = g(x_0) \dots, \quad x_n = g(x_{n-1}).$$

In the same way as above, we obtain the next approximation u_2 for \bar{x} , which satisfies

$$|\bar{x} - u_2| \leq \frac{M \cdot m^{n+1} \cdot l^{\frac{n(n+1)}{2}}}{(n+1)!} |\bar{x} - u_1|^{n+1}.$$

In general, if u_k is an approximation of \bar{x} and we set

$$x_0 = u_k, \quad x_1 = g(x_0), \dots, \quad x_n = g(x_{n-1}),$$

then by (7) we obtain the next approximation u_{k+1} , which satisfies

$$(30) \quad |\bar{x} - u_{k+1}| \leq \frac{M \cdot m^{n+1} \cdot l^{\frac{n(n+1)}{2}}}{(n+1)!} |\bar{x} - u_k|^{n+1}, \quad k = 0, 1, \dots$$

Denoting $\delta_k = ml^{\frac{n+1}{2}} \left(\frac{Mm}{(n+1)!} \right)^{\frac{1}{n}} |\bar{x} - u_k|$, then from the above relation we deduce

$$\delta_{k+1} \leq \delta_k^{n+1}, \quad k = 0, 1, \dots,$$

which leads to the conclusion that for $n \geq 1$, method (11) converges super-linearly. Moreover, if x_0 is chosen such that $\delta_0 < 1$ then $\lim_{k \rightarrow \infty} \delta_k = 0$ and therefore $\lim_{k \rightarrow \infty} u_k = \bar{x}$.

The error at each step is bounded by:

$$(31) \quad |\bar{x} - u_k| \leq m^{-1} t^{-\frac{n+1}{2}} \left(\frac{Mm}{(n+1)!} \right)^{-\frac{1}{n}} \delta_0^{(n+1)^k}, \quad k = 1, 2, \dots$$

In the following we analyze two particular cases.

- (1) Case $n = 1$. In this case (11) leads to the well known Steffensen method.

Indeed, by (2) we get

$$(32) \quad L[y_0, y_1 f^{-1}|y] = x_0 + [y_0, y_1; f^{-1}](y - y_0),$$

hence, taking into account the equality

$$[y_0, y_1; f^{-1}] = \frac{1}{[x_0, x_1; f]},$$

for $y = 0$ we obtain the approximation

$$(33) \quad x_2 = x_0 - \frac{f(x_0)}{[x_0, x_1; f]},$$

i.e., the first step in the chord method.

Obviously, (9) may continue by

$$(34) \quad x_k = x_{k-2} - \frac{f(x_{k-2})}{[x_{k-2}, x_{k-1}; f]}, \quad k = 2, 3, \dots$$

Denoting in (33) $x_0 = u_0$ and $x_1 = g(u_0)$, we get

$$u_1 = u_0 - \frac{f(u_0)}{[u_0, g(u_0); f]}$$

and in general

$$(35) \quad u_k = u_{k-1} - \frac{f(u_{k-1})}{[u_{k-1}, g(u_{k-1}); f]},$$

which is precisely the Steffensen method.

In this case, the elements of the sequence $(\delta_k)_{k \geq 0}$ have the form

$$\delta_k = \frac{lm^2 M}{2} |\bar{x} - u_k|, \quad k = 0, 1, \dots, \quad M = \sup_{y \in f(I)} \left| (f^{-1}(y))'' \right|$$

and obey

$$\delta_{k+1} \leq \delta_k^2, \quad k = 0, 1, \dots$$

If $\delta_0 < 1$, then obviously

$$\lim_{k \rightarrow \infty} \delta_k = 0$$

and hence $\lim x_k = \bar{x}$, with the error

$$|x_k - \bar{x}| \leq \frac{2}{lm^2 M} \delta_0^{2^k}, \quad k = 1, 2, \dots,$$

whence (35) converges quadratically.

2. Case $n = 2$

It can be easily seen that the second order divided difference $[y_0, y_1, y_2; f^{-1}]$ can be expressed as

$$(36) \quad [y_0, y_1, y_2; f^{-1}] = \frac{-[x_0, x_1, x_2; f]}{[x_0, x_1; f][x_0, x; f][x_1, x_2; f]}.$$

By (2) we get

$$L [y_0, y_1, y_2; f^{-1} | y] = x_0 + [y_0, y_1; f^{-1}] (y - y_0) \\ + [y_0, y_1, y_2; f^{-1}] (y - y_0) (y - y_1).$$

Setting $y = 0$ and taking into account (36) and the corresponding formula for the first order divided difference, we are lead to

$$(37) \quad x_3 = x_0 - \frac{f(x_0)}{[x_0, x_1; f]} - \frac{[x_0, x_1, x_2; f] f(x_0) f(x_1)}{[x_0, x_1; f][x_1, x_2; f][x_1, x_2; f]},$$

i.e., to a method correcting the chord method.

In general, a method of type (37) has the form

$$(38) \quad x_{n+3} = x_n - \frac{f(x_n)}{[x_n, x_{n+1}; f]} - \frac{[x_n, x_{n+1}, x_{n+2}; f]}{[x_n, x_{n+1}; f][x_{n+1}, x_{n+2}; f][x_n, x_{n+2}; f]},$$

$n = 0, 1, \dots$ If in (37) we control the interpolation nodes as

$$x_0 = u_0, \quad x_1 = g(x_0), \quad x_2 = g(x_1) = g(g(x_0))$$

we obtain

$$u_1 = u_0 - \frac{f(u_0)}{[u_0, g(u_0); f]} - \frac{[u_0, g(u_0), g(g(u_0)); f] f(u_0) f(g(u_0))}{[u_0, g(u_0); f][u_0, g(g(u_0)); f][g(u_0), g(g(u_0)); f]}.$$

In general, if u_k is an approximation to \bar{x} , then u_{k+1} is given by

$$(39) \quad u_{k+1} = u_k - \frac{f(u_k)}{[u_k, g(u_k); f]} - \frac{[u_k, g(u_k), g(g(u_k)); f] f(u_k) f(g(u_k))}{[u_k, g(u_k); f][u_k, g(g(u_k)); f][g(u_k), g(g(u_k)); f]}.$$

Denoting $M = \sup_{y \in f(I)} |[f^{-1}(y)]'''|$, then the error satisfies at each iteration step:

$$(40) \quad |u_k - \bar{x}| \leq \frac{\sqrt{6}}{ml^{3/2}\sqrt{mM}} \delta_0^{3^k},$$

where

$$\delta_0 = \frac{ml^{3/2}\sqrt{Mm}}{\sqrt{6}} |\bar{x} - u_0|.$$

Assuming $\delta_0 < 1$, then $\lim_{k \rightarrow \infty} u_k = \bar{x}$, with the convergence order at least 3.

Suppose in the following that the function g given by (23) has derivatives up to the p -th order, $p \in \mathbb{N}$, $p \geq 2$, on $[a, b]$ and its derivatives satisfy

$$(41) \quad g^{(i)}(\bar{x}) = 0, \quad i = \overline{1, p-1}, \quad g^{(p)}(\bar{x}) \neq 0.$$

In this case, if the derivative of p -th order in continuous on $[a, b]$ and

$$L = \sup_{x \in [a, b]} |g^{(p)}(x)|,$$

then for all $x \in [a, b]$ one has

$$(42) \quad |g(\bar{x}) - g(x)| \leq \frac{L}{p!} |\bar{x} - x|^p.$$

Using the above relation (27) we get

$$(43) \quad |\bar{x} - u_1| \leq \frac{Mm^{n+1}}{(n+1)!} \left(\frac{p!}{L}\right)^{\frac{n+1}{p-1}} \theta_0^{\frac{p^{n+1}-1}{p-1}},$$

where $\theta_0 = \left(\frac{L}{p!}\right)^{\frac{1}{p-1}} |\bar{x} - u_0|$.

We make the following notations:

$$\begin{aligned} q &= \frac{p^{n+1}-1}{p-1}; \\ K &= \frac{Mm^{n+1}}{(n+1)!} \left(\frac{p!}{L}\right)^{\frac{n+1}{p-1}}; \\ \varepsilon_0 &= K^{\frac{1}{q-1}} \theta_0; \\ \varepsilon_1 &= K^{\frac{1}{q-1}} |\bar{x} - u_1|. \end{aligned}$$

By (43), we are lead to

$$\varepsilon_1 \leq \varepsilon_0^q.$$

We obtain the sequence of approximation $(u_s)_{s \geq 0}$ for which, if denoting

$$(44) \quad \varepsilon_s = K^{\frac{1}{q-1}} |\bar{x} - u_s|, \quad s = 1, 2, \dots,$$

we get

$$(45) \quad \varepsilon_s \leq \varepsilon_0^{q^s}, \quad s = 1, 2, \dots$$

Obviously, in this case too, if $\varepsilon_0 < 1$, then by (44) and (45) it follows $\lim_{s \rightarrow \infty} u_s = \bar{x}$ and the convergence order is q .

REFERENCES

- [1] BALÁZS, M., *A bilateral approximating method for finding the real roots of real equations*, Rev. Anal. Numér. Théor. Approx., **21**, no. 2, pp. 111–117, 1992. [📄](#)
- [2] BRENT, R., WINOGRAD, S. and WALFE, PH., *Optimal iterative processes for root-finding*, Numer. Math., **20**, no. 5, pp. 327–341, 1973.
- [3] COMAN, C., *Some practical approximation methods for nonlinear equations*, Mathematica – Rev. Anal. Numér. Théor. Approx., **11**, nos. 1–2, pp. 41–48, 1982. [📄](#)
- [4] CASSULLI, V. and TRIGIANTE, D., *The convergence order for iterative multipoint procedures*, Calcolo, **13**, no. 1, pp. 25–44, 1977.
- [5] IANCU, C., PĂVĂLOIU, I. and ȘERB, I., *Méthodes itératives optimales de type Steffensen obtenues par interpolation inverse*, Faculty of Mathematics, “Babeş-Bolyai” University, Seminar on Functional analysis and Numerical Methods, Preprint no. **1**, pp. 81–88, 1983.
- [6] KACEWICZ, B., *An integral-interpolation iterative method for the solution of scalar equations*, Numer. Math., **26**, no. 4, pp. 355–365, 1976.
- [7] OSTROWSKI, A., *Solution of Equations in Euclidian and Banach Spaces*, Academic Press, New York and London, 1973.

-
- [8] PĂVĂLOIU, I., *La résolution des equations par interpolation*, *Mathematica*, **23(46)**, no. 1, pp. 61–72, 1981.
- [9] PĂVĂLOIU, I. and ȘERB, I., *Sur des méthodes de type interpolatoire à vitesse de convergence optimale*, *Rev. Anal. Numér. Théor. Approx.*, **12**, no. 1, pp. 83–88, 1983. [✉](#)
- [10] PĂVĂLOIU, I., *Optimal efficiency index for iterative methods of interpolatory type*, *Computer Science Journal of Moldova*, **5**, no. 1 (13), pp. 20–43, 1997.
- [11] TRAUB, J. F., *Iterative Methods for the Solution of Equations*, Prentice-Hall, Inc. Englewood Cliffs, N.J., 1964.
- [12] TUROWICZ, A. B., *Sur les dérivées d'ordre supérieur d'une fonction inverse*, *Ann. Polon. Math.*, **8**, pp. 265–269, 1960.

Received by the editors: January 21, 2004.