## ON THE LEIBNIZ FORMULA FOR DIVIDED DIFFERENCES

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#### Abstract

We give an identity for the Hermite-Lagrange interpolating polynomial and a short proof of Leibniz-type formula for divided differences in case of coalescing knots.


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## 1. INTRODUCTION

Let $x_{0}, \ldots, x_{n}$, be distinct points and $f$ be a function defined on the set $\left\{x_{0}, \ldots, x_{n}\right\}$. In most books on Numerical Analysis divided differences for distinct points are defined recursively:

$$
\begin{gathered}
{\left[x_{0}\right] f=f\left(x_{0}\right), \ldots} \\
{\left[x_{0}, \ldots, x_{n}\right] f=\frac{\left[x_{1}, \ldots, x_{n}\right] f-\left[x_{0}, \ldots, x_{n-1}\right] f}{x_{n}-x_{0}}}
\end{gathered}
$$

Divided differences might fairly be ascribed to Newton [9]. A. M. Ampère [1] called these quantities "les fonctions interpolaires" (see also [11, page 1]).

In a personal message, Erik Meijering [8] let us know that the term "divided difference" was used first in 1842 by Augustus de Morgan in Chapter XVIII, "On Interpolation and Summation", of his book [5, p. 550] (see also [16]).

Newton's formula for interpolation by a polynomial was given by Isaac Newton as Lemma 5 of Book III of his Principia Mathematica of 1687 [9] but it was known to him before since he mentioned it in a letter to the German scientist Henry Oldenburg dated October 24, 1676.

Newton proved that the polynomial

$$
P_{n}(X)=f\left(x_{0}\right)+\left(X-x_{0}\right)\left[x_{0}, x_{1}\right] f+\cdots+\left(X-x_{0}\right) \ldots\left(X-x_{n-1}\right)\left[x_{0}, \ldots, x_{n}\right] f
$$

is the unique polynomial of degree at most $n$ such that

$$
P_{n}\left(x_{i}\right)=f\left(x_{i}\right), \quad i=0, \ldots, n
$$

[^0]In 1795, J. L. Lagrang ${ }^{\|}$obtained the following form of Newton's interpolating polynomial:

$$
P_{n}(x)=\sum_{i=0}^{n} f\left(x_{i}\right) \frac{\ell(x)}{\left(x-x_{i}\right) \ell^{\prime}\left(x_{i}\right)},
$$

where $\ell(x)=\left(x-x_{0}\right)\left(x-x_{1}\right) \ldots\left(x-x_{n}\right)$.
The polynomial $P_{n}$ of degree at most $n$ such that

$$
P_{n}\left(x_{i}\right)=f\left(x_{i}\right), \quad i=0, \ldots, n,
$$

is nowadays generally called the Lagrange interpolation polynomial, of the function $f$ with respect to $x_{0}, \ldots, x_{n}$, and is denoted by $L\left[x_{0}, \ldots, x_{n}\right] f$.

However, in 2002, Erik Meijering [8] discovered that early from the year 1779, Edward Waring [15] obtained "the Lagrange Formula".

Let $m, n \in \mathbb{N}$, and $\alpha_{0}, \ldots, \alpha_{n} \in \mathbb{N}^{*}$ such that

$$
\alpha_{0}+\cdots+\alpha_{n}=m+1 .
$$

Consider the numbers $y_{i j}, i=0, \ldots, n ; j=0, \ldots, \alpha_{i}-1$, and the distinct points $x_{0}, \ldots, x_{n}$.

In 1878 Charles Hermite $[7]^{2}$ proved that there exists a unique polynomial $H_{m}$ of degree at most $m$, called the Hermite-Lagrange interpolating polynomial, such that

$$
H_{m}^{(j)}\left(x_{i}\right)=y_{i j},
$$

for $i=0, \ldots, n ; j=0, \ldots, \alpha_{i}-1$.
Suppose that the function $f:[a, b] \rightarrow \mathbb{R}$ possesses the derivatives $f^{\left(\alpha_{i}-1\right)}\left(x_{i}\right)$, $i=0, \ldots, n$. We denote the Hermite-Lagrange interpolating polynomial $H_{m}$, satisfying

$$
\begin{equation*}
H_{m}^{(j)}\left(x_{i}\right)=f^{(j)}\left(x_{i}\right), \tag{1.1}
\end{equation*}
$$

$i=0, \ldots, n ; j=0, \ldots, \alpha_{i}-1$, by:

$$
H_{m}[\underbrace{x_{0}, \ldots, x_{0}}_{\alpha_{0} \text { times }}, \ldots, \underbrace{x_{n}, \ldots, x_{n}}_{\alpha_{n} \text { times }}] f, \quad \text { or } \quad H_{m}\left[\begin{array}{cccc}
x_{0} & x_{1} & \ldots & x_{n} \\
\alpha_{0} & \alpha_{1} & \ldots & \alpha_{n}
\end{array}\right] f \text {. }
$$

2. AN IDENTITY FOR THE HERMITE-LAGRANGE POLYNOMIALS

Rename the knots $(\underbrace{x_{0}, \ldots, x_{0}}_{\alpha_{0} \text { times }}, \ldots, \underbrace{x_{n}, \ldots, x_{n}}_{\alpha_{n} \text { times }})$ to $\left(t_{0}, \ldots, t_{m}\right)$.
Theorem 2.1. The following formula

$$
\begin{align*}
& H_{m}\left[t_{0}, \ldots, t_{m}\right]\left(\left(X-t_{0}\right) \ldots\left(X-t_{i}\right) f\right)  \tag{2.1}\\
= & \left(X-t_{0}\right) \ldots\left(X-t_{i}\right) H_{m}\left[t_{i+1}, \ldots, t_{m}\right] f,
\end{align*}
$$

[^1]is satisfied for $i=0,1, \ldots, m-1$.
Proof. Use the notations:
\[

$$
\begin{aligned}
P & =H_{m}\left[\begin{array}{llll}
x_{0} & x_{1} & \ldots & x_{n} \\
\alpha_{0} & \alpha_{1} & \ldots & \alpha_{n}
\end{array}\right]\left(\left(X-x_{0}\right) f\right) \\
Q & =\left(X-x_{0}\right) H_{m}\left[\begin{array}{cccc}
x_{0} & x_{1} & \ldots & x_{n} \\
\alpha_{0}-1 & \alpha_{1} & \ldots & \alpha_{n}
\end{array}\right] f .
\end{aligned}
$$
\]

It is sufficient to prove that $P=Q$.
For $i=0$, we have:

$$
Q^{(j)}\left(x_{0}\right)=\left.j\left(\frac{\mathrm{~d}}{\mathrm{~d} x}\right)^{j-1}\left(H_{m}\left[\begin{array}{cccc}
x_{0} & x_{1} & \ldots & x_{n} \\
\alpha_{0}-1 & \alpha_{1} & \ldots & \alpha_{n}
\end{array}\right] f\right)\right|_{x=x_{0}}
$$

$\left(1 \leq j \leq \alpha_{0}-1\right)$ hence

$$
\begin{aligned}
Q^{(j)}\left(x_{0}\right) & =\left\{\begin{array}{cc}
0, & j=0 \\
j f^{(j-1)}\left(x_{0}\right), & 1 \leq j \leq \alpha_{0}-1
\end{array}\right. \\
& =\left.\left(\frac{\mathrm{d}}{\mathrm{~d} x}\right)^{j}\left(\left(x-x_{0}\right) f(x)\right)\right|_{x=x_{0}} \\
& =P^{(j)}\left(x_{0}\right) \quad\left(0 \leq j \leq \alpha_{0}-1\right) .
\end{aligned}
$$

For $1 \leq i \leq n$, we obtain:

$$
\begin{aligned}
Q^{(j)}\left(x_{i}\right)= & \left.\left(x_{i}-x_{0}\right)\left(\frac{\mathrm{d}}{\mathrm{~d} x}\right)^{j}\left(H_{m}\left[\begin{array}{cccc}
x_{0} & x_{1} & \ldots & x_{n} \\
\alpha_{0}-1 & \alpha_{1} & \ldots & \alpha_{n}
\end{array}\right] f\right)\right|_{x=x_{i}} \\
& +\left.j\left(\frac{\mathrm{~d}}{\mathrm{~d} x}\right)^{j-1}\left(H_{m}\left[\begin{array}{cccc}
x_{0} & x_{1} & \ldots & x_{n} \\
\alpha_{0}-1 & \alpha_{1} & \ldots & \alpha_{n}
\end{array}\right] f\right)\right|_{x=x_{i}} \\
= & \left.\left(\frac{\mathrm{d}}{\mathrm{~d} x}\right)^{j}\left(\left(x-x_{0}\right) f(x)\right)\right|_{x=x_{i}} \\
= & P^{(j)}\left(x_{i}\right) \quad\left(0 \leq j \leq \alpha_{i}-1\right) .
\end{aligned}
$$

The degrees of the polynomials $P$ and $Q$ are at most $m$, and $Q^{(j)}\left(x_{i}\right)=$ $P^{(j)}\left(x_{i}\right), 0 \leq i \leq n, 0 \leq j \leq \alpha_{i}-1$. Hence $P=Q$, and the proof is completed.

Identifying the coefficients of $X^{m}$ in Eq. (2.1) we reobtain the following reduction formula for the divided difference in the case of multiple knots
(2.2) $\left[t_{0}, \ldots t_{m}\right]\left(\left(X-t_{0}\right) \ldots\left(X-t_{i}\right) f\right)=\left[t_{i+1}, \ldots, t_{m}\right] f, \quad i=0, \ldots, m-1$.

## 3. THE LEIBNIZ-TYPE FORMULA FOR DIVIDED DIFFERENCES

Let $f$ and $g$ be functions defined on an interval containing the points $t_{0}, \ldots, t_{n}$ not necessarily distinct. The following Leibniz-type formula for divided differences is satisfied

$$
\begin{equation*}
\left[t_{0}, \ldots, t_{m}\right](f g)=\sum_{k=0}^{m}\left[t_{0}, \ldots, t_{k}\right] f\left[t_{k}, \ldots, t_{n}\right] g . \tag{3.1}
\end{equation*}
$$

Formula (3.1) is generally credited to Steffensen, because of his paper [14. However our earlist reference for Eq. (3.1) is that of Tiberiu Popoviciu [12, p. 12, Eq. (18)]. In 1940 Tiberiu Popoviciu [13, p. 65] protested: "Je me suis décidé de revenir sur ces questions en remarquant l'apparition de quelques travaux où mes résultats ne sont pas cités; voir, par exemple, 14] ("I decided to come back upon these problems, because I have noticed some works, e.g., [14, in which results from my dissertation [12 are not quoted").

On the occasion of Tiberiu Popoviciu's $50^{t h}$ birthday, Academician Miron Nicolescu, G. Pic, D. V. Ionescu, E. Gergely, L. Németi, L. Bal and F. Radó published an overview of Popoviciu's mathematical activity [10]. In this paper the authors reiterated the priority of Tiberiu Popoviciu in what concerns the Leibniz formula for divided differences.

In a recent paper [4, de Boor wrote: "My first reference for the Leibniz formula is [12], though Steffensen later devotes an entire paper, [14], to it and this has become the standard reference for it despite the fact that Popoviciu, in response, wrote his own overview of divided differences, [13], trying, in vain, to correct the record".

A new proof of Leibniz's formula is obtained by Tiberiu Popoviciu as an application of his Fundamental Formula for Divided Differences [13, p. 70].

In the case of distinct knots, an interesting proof of (3.1) is given by de Boor [2, p. 5]. De Boor's idea is used by DeVore and Lorentz [6, p. 121] to prove (3.1) in the case of coalescing points, but assuming that the derivatives of $f$ and $g$, required for the divided difference $\left[t_{0}, \ldots, t_{m}\right]$, are continuous at the corresponding points. A generalization of formula (3.1) is given by de Boor in [3].

## 4. THE PROOF

We give a proof of the Leibniz-type formula (3.1) in the case of coalescing points. Using the Newton form of the interpolating polynomial (1.1) and the reduction formula (2.2) we have:

$$
\begin{aligned}
{\left[t_{0}, \ldots, t_{m}\right](f g) } & =\left[t_{0}, \ldots, t_{m}\right]\left(H\left[t_{0}, \ldots, t_{m}\right](f) g\right) \\
& =\left[t_{0}, \ldots, t_{m}\right]_{t}\left(\sum_{k=0}^{m}\left(t-t_{0}\right) \ldots\left(t-t_{k-1}\right)\left[t_{0}, \ldots, t_{k}\right](f) g(t)\right)
\end{aligned}
$$

$$
\begin{aligned}
& =\sum_{k=0}^{m}\left[t_{0}, \ldots, t_{k}\right] f\left[t_{0}, \ldots, t_{m}\right]_{t}\left(\left(t-t_{0}\right) \ldots\left(t-t_{k-1}\right) g(t)\right) \\
& =\sum_{k=0}^{m}\left[t_{0}, \ldots, t_{k}\right] f\left[t_{k}, \ldots, t_{m}\right] g
\end{aligned}
$$

and the proof is completed.

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[^1]:    ${ }^{1}$ cf. J. L. Lagrange, "Leçons élémentaires sur les mathématiques données a l'École Normale", in Oeuvres de Lagrange, J.-A. Serret (ed.), vol. 7, Gauthier-Villars, Paris, 1877, pp. 183-287. Lecture notes first published in 1795.
    ${ }^{2}$ Also in Oeuvres de Charles Hermite, vol. III, Gauthier-Villars, Paris, 1912, pp. 432-443.

