

## FIXED POINTS AND INTEGRAL INCLUSIONS

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**Abstract.** The aim of this paper is to present, as applications of some fixed point theorems, existence results for integral equations and inclusions.

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### 1. NOTATIONS AND NOTIONS

Throughout this paper, the standard notations and terminologies in non-linear analysis are used. For the convenience of the reader we recall some of them.

Let  $(X, d)$  be a metric space and  $f : X \rightarrow X$  an operator. By  $Fix f := \{x \in X \mid x = f(x)\}$  we will denote the fixed point set of the operator  $f$ .

The following concept was introduced by I.A. Rus (see [7]).

**DEFINITION 1.** Let  $(X, \rightarrow)$  be an  $L$ -space. An operator  $f : X \rightarrow X$  is, by definition, a Picard operator if:

- (i)  $Fix f = \{x^*\}$ ;
- (ii)  $f^n(x) \rightarrow x^*$ , as  $n \rightarrow \infty$ , for all  $x \in X$ .

We will also use the following symbols:

$\mathcal{P}(X) := \{Y \mid Y \subset X\}$ ,  $P(X) := \{Y \subset X \mid Y \text{ is nonempty}\}$ ,

$P_{cl}(X) := \{Y \in P(X) \mid Y \text{ is closed}\}$ ,  $P_{cv}(X) := \{Y \in P(X) \mid Y \text{ is convex}\}$  (for a normed space  $X$ ).

Let  $A$  and  $B$  be nonempty subsets of the metric space  $(X, d)$ . The gap between these sets is

$$D(A, B) = \inf\{d(a, b) \mid a \in A, b \in B\}.$$

In particular,  $D(x_0, B) = D(\{x_0\}, B)$  (where  $x_0 \in X$ ) is called the distance from the point  $x_0$  to the set  $B$ .

The Pompeiu-Hausdorff generalized distance between the nonempty closed subsets  $A$  and  $B$  of the metric space  $(X, d)$  is defined by the following formula:

$$H(A, B) := \max \left\{ \sup_{a \in A} \inf_{b \in B} d(a, b), \sup_{b \in B} \inf_{a \in A} d(a, b) \right\}.$$

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It is well-known that if  $(X, d)$  is a complete metric space, then the pair  $(P_d(X), H)$  is a (generalized) complete metric space.

The symbol  $T : X \multimap Y$  means  $T : X \rightarrow P(Y)$ , i. e.  $T$  is a multi-valued operator from  $X$  to  $Y$ . We will denote by  $Graf(T) := \{(x, y) \in X \times Y \mid y \in T(x)\}$  the graph of  $T$ . Recall that the multi-valued operator is called closed if  $Graf(T)$  is closed in  $X \times Y$ .

For  $T : X \rightarrow P(X)$  the symbol  $\text{Fix} T := \{x \in X \mid x \in T(x)\}$  denotes the fixed point set of the multi-valued operator  $T$ .

A sequence of successive approximations of  $T$  starting from  $x \in X$  is a sequence  $(x_n)_{n \in \mathbb{N}}$  of elements of  $X$  with  $x_0 = x$ ,  $x_{n+1} \in T(x_n)$ , for  $n \in \mathbb{N}$ .

## 2. THE SINGLE-VALUED CASE

Let  $\varphi : \mathbb{R}_+ \rightarrow \mathbb{R}_+$ . Then  $\varphi$  is said to be a comparison function (see [6]) if it is increasing and  $\varphi^k(t) \rightarrow 0$ , as  $k \rightarrow +\infty$ . As consequence, we also have  $\varphi(t) < t$ , for each  $t > 0$ ,  $\varphi(0) = 0$  and  $\varphi$  is continuous in 0.

In particular,  $\varphi(t) = at$ , (where  $a \in [0, 1[$ ),  $\varphi(t) = \frac{t}{1+t}$ , and  $\varphi(t) = \ln(1+t)$ ,  $t \in \mathbb{R}_+$  are examples of comparison functions.

Also, a function  $\varphi : \mathbb{R}_+ \rightarrow \mathbb{R}_+$  is said to be a strict comparison function (see [6]) if it is strictly increasing and  $\sum_{n=1}^{\infty} \varphi^n(t) < +\infty$ , for each  $t > 0$ .

The following auxiliary result is known (see Dugundji-Granas [3]).

LEMMA 2. *Let  $(X, d)$  be a complete metric space and  $f : X \rightarrow X$ . Assume:*

- i) *for each  $\varepsilon > 0$  there is  $\delta(\varepsilon) > 0$  such that if  $d(x, f(x)) < \delta$ , then  $f(B(x; \varepsilon)) \subset B(x; \varepsilon)$ ;*
- ii)  *$\lim_{n \rightarrow +\infty} d(f^{n-1}(x_0), f^n(x_0)) = 0$ , for some  $x_0 \in X$ .*

*Then the sequence  $(f^n(x_0))_{n \in \mathbb{N}}$  converges to a fixed point for  $f$ .*

We start this section with a straightforward modified version of a well-known result (J. Matkowski see [3] pp. 15 and I. A. Rus [6]).

THEOREM 3. *Let  $(X, d)$  be a complete metric space and  $f : X \rightarrow X$  such that  $d(f(x), f(y)) \leq \varphi(d(x, y))$ , for all  $x, y \in X$ , where  $\varphi : \mathbb{R}_+ \rightarrow \mathbb{R}_+$  satisfies the following assumptions:*

- i)  *$\varphi$  is increasing and upper semi-continuous;*
- ii) *the function  $\psi : \mathbb{R}_+ \rightarrow \mathbb{R}_+$ ,  $\psi(t) := t - \varphi(t)$ , is strictly increasing and  $\lim_{t \rightarrow \infty} \psi(t) = \infty$ .*

*Then:*

- a) *the operator  $f$  is Picard (denote by  $x_f^*$  the unique fixed point);*
- b) *if  $g : X \rightarrow X$  is an operator having at least a fixed point  $x_g^* \in X$  and there exists  $\eta > 0$  such that  $d(f(x), g(x)) \leq \eta$ , for each  $x \in X$ , then  $d(x_f^*, x_g^*) \leq \psi^{-1}(\eta)$ .*

*Proof.* Let  $x_0 \in X$  be arbitrary. Denote  $d_n := d(f^{n-1}(x_0), f^n(x_0))$ ,  $n \in \mathbb{N}^n$ . Then  $d_n \leq \varphi(d_{n-1}) \leq d_{n-1}$ ,  $n \in \mathbb{N}^n$ . Hence the sequence  $(d_n)_{n \in \mathbb{N}^n}$  converges to a certain element  $d \in \mathbb{R}_+$ .

Suppose  $d > 0$ . Then  $\psi(d) > \psi(0) = 0$ . So  $d > \varphi(d)$ . On the other hand, since  $d_n \leq \varphi(d_{n-1})$  and using the upper semi-continuity of  $\varphi$ , we get that  $d \leq \limsup_{n \rightarrow +\infty} \varphi(d_{n-1}) \leq \varphi(d)$ . The contradiction proves that  $d = 0$ . Hence

$\lim_{n \rightarrow +\infty} d(f^{n-1}(x_0), f^n(x_0)) = 0$ , for each  $x_0 \in X$  (This property is usually called the asymptotic regularity of  $f$ ).

Let  $\varepsilon > 0$  and define  $\delta(\varepsilon) := \varepsilon - \varphi(\varepsilon)$ . Suppose  $d(x, f(x)) < \delta$  and let  $z \in B(x; \varepsilon)$ . We have:

$d(f(z), x) \leq d(f(z), f(x)) + d(f(x), x) \leq \varphi(d(x, z)) + \delta \leq \varepsilon$ . The conclusion follows from Lemma 2.

For the second conclusion observe that

$d(x_f^*, x_g^*) \leq d(f(x_f^*), f(x_g^*)) + d(f(x_g^*), g(x_g^*)) \leq \varphi(d(x_f^*, x_g^*)) + \eta$ . Hence  $d(x_f^*, x_g^*) \leq \psi^{-1}(\eta)$ .  $\square$

As an application of the above result we can prove the following

**THEOREM 4.** *Consider the integral equation:*

$$(1) \quad x(t) = \int_a^b K(t, s, x(s))ds + g(t), \quad t \in [a, b].$$

*Suppose:*

- i)  $K : [a, b] \times [a, b] \times \mathbb{R}^n \rightarrow \mathbb{R}^n$  and  $g : [a, b] \rightarrow \mathbb{R}^n$  are continuous;
- ii) there exist a continuous function  $p : [a, b] \times [a, b] \rightarrow \mathbb{R}_+$  and an increasing function  $\varphi : \mathbb{R}_+ \rightarrow \mathbb{R}_+$  such that  $\psi : \mathbb{R}_+ \rightarrow \mathbb{R}_+$ ,  $\psi(t) := t - \varphi(t)$  is strictly increasing and  $\lim_{t \rightarrow \infty} \psi(t) = \infty$ , such that

$$\|K(t, s, u) - K(t, s, v)\| \leq p(t, s)\varphi(\|u - v\|), \quad \text{for each } t, s \in [a, b], \quad u, v \in \mathbb{R}^n.$$

$$\text{iii) } \sup_{t \in [a, b]} \int_a^b p(t, s)ds \leq 1.$$

*Then:*

- a) the integral equation (1) has an unique solution  $x^*$  in  $C([a, b], \mathbb{R}^n)$ ;
- b) if

$$(2) \quad y(t) = \int_a^b L(t, s, y(s))ds + h(t), \quad t \in [a, b]$$

is another integral equation having at least one solution  $y^* \in C([a, b], \mathbb{R}^n)$  and there are  $\eta_1, \eta_2 > 0$  such that  $\|K(t, s, u) - L(t, s, u)\| \leq \eta_1$  and  $\|g(t) - h(t)\| \leq \eta_2$ , for each  $t, s \in [a, b]$  and  $u \in C([a, b], \mathbb{R}^n)$ , then  $\|x^* - y^*\| \leq \psi^{-1}(\eta_1 \cdot (b - a) + \eta_2)$ .

*Proof.* Define  $A : C([a, b], \mathbb{R}^n) \rightarrow C([a, b], \mathbb{R}^n)$ , by the formula

$$Ax(t) := \int_a^b K(t, s, x(s))ds + g(t), \quad t \in [a, b].$$

Observe that  $\|Ax(t) - Ay(t)\| \leq \int_a^b \| [K(t, s, x(s)) - K(t, s, y(s))] \| ds \leq \int_a^b p(t, s) \varphi(\|x(s) - y(s)\|) ds \leq \varphi(\|x - y\|_C) \int_a^b p(t, s) ds$ . Thus

$$\|Ax - Ay\|_C \leq \varphi(\|x - y\|_C), \text{ for each } x, y \in C([a, b], \mathbb{R}^n)$$

(here  $\|\cdot\|_C$  stands for the sup-norm in  $C([a, b], \mathbb{R}^n)$ ). The first conclusion follows from Theorem 3.

For the second conclusion, consider  $B : C([a, b], \mathbb{R}^n) \rightarrow C([a, b], \mathbb{R}^n)$ , given by the formula

$$Bx(t) := \int_a^b L(t, s, x(s)) ds + h(t), \quad t \in [a, b].$$

Then  $\|Ax(t) - Bx(t)\| \leq \int_a^b \|K(t, s, x(s)) - L(t, s, x(s))\| ds + \|g(t) - h(t)\| \leq \eta_1 \cdot (b - a) + \eta_2$ , for each  $t \in [a, b]$ . Hence  $\|Ax - Bx\|_C \leq \eta_1 \cdot (b - a) + \eta_2$ .

Then from the second conclusion of Theorem 3 we conclude  $\|x^* - y^*\|_C \leq \psi^{-1}(\eta_1 \cdot (b - a) + \eta_2)$ .  $\square$

EXAMPLE 1. If  $g \in C[a, b]$ , then the integral equation

$$x(t) = \int_a^b s \cdot \frac{x(s)}{1 + x(s)} ds + g(t), \text{ for each } t \in [a, b]$$

has a unique solution in  $C[a, b]$ . The conclusion follows by an application of Theorem 4 with  $\varphi(t) = \frac{t}{1+t}$ .

EXAMPLE 2. If  $g \in C[a, b]$ , then the integral equation

$$x(t) = \int_a^b \ln(1 + x(s)) ds + g(t), \text{ for each } t \in [a, b]$$

has a unique solution in  $C[a, b]$ . The conclusion follows by an application of Theorem 4 with  $\varphi(t) = \ln(1 + t)$ .

### 3. THE MULTI-VALUED CASE

The following result is known in the literature as Wegrzyk's theorem (see [10]).

THEOREM 5. *Let  $(X, d)$  be a complete metric space and  $T : X \rightarrow P_{cl}(X)$  be such that  $H(T(x), T(y)) \leq \varphi(d(x, y))$ , for each  $x, y \in X$ . Assume that  $\varphi : \mathbb{R}_+ \rightarrow \mathbb{R}_+$  is a strict comparison function. Then  $\text{Fix} T$  is nonempty and for any  $x_0 \in X$  there exists a sequence of successive approximations of  $T$  starting from  $x_0$  which converges to a fixed point of  $T$ .*

As an application, let us consider the following integral inclusion:

$$(3) \quad x(t) \in \int_a^b K(t, s, x(s)) ds + g(t), \quad t \in [a, b].$$

THEOREM 6. *Let  $K : [a, b] \times [a, b] \times \mathbb{R}^n \rightarrow P_{cl, cv}(\mathbb{R}^n)$  and  $g : [a, b] \rightarrow \mathbb{R}^n$  such that:*

- (a) *there exists an integrable function  $M : [a, b] \rightarrow \mathbb{R}_+$  such that for each  $t \in [a, b]$  and  $u \in \mathbb{R}^n$  we have  $K(t, s, u) \subset M(s)B(0; 1)$ , a.e.  $s \in [a, b]$ ;*  
 (b) *for each  $u \in \mathbb{R}^n$   $K(\cdot, \cdot, u) : [a, b] \times [a, b] \rightarrow P_{cl, cv}(\mathbb{R}^n)$  is jointly measurable;*  
 (c) *for each  $(s, u) \in [a, b] \times \mathbb{R}^n$   $K(\cdot, s, u) : [a, b] \rightarrow P_{cl, cv}(\mathbb{R}^n)$  is lower semi-continuous;*  
 (d) *there is a strict comparison function  $\varphi : \mathbb{R}_+ \rightarrow \mathbb{R}_+$  such that for each  $(t, s) \in [a, b] \times [a, b]$  and each  $u, v \in \mathbb{R}^n$  we have that*

$$H(K(t, s, u), K(t, s, v)) \leq p(t, s) \cdot \varphi(\|u - v\|)$$

where  $p : [a, b] \times [a, b] \rightarrow \mathbb{R}_+$  is a continuous function and

$$\sup_{t \in [a, b]} \int_a^b p(t, s) ds \leq 1;$$

- (e)  *$g$  is continuous.*

Then there exists at least one solution for the integral inclusion (3).

*Proof.* Define the multi-valued operator  $T : C([a, b], \mathbb{R}^n) \rightarrow \mathcal{P}(C([a, b], \mathbb{R}^n))$  by

$$T(x) := \left\{ v \in C([a, b], \mathbb{R}^n) \mid v(t) \in \int_a^b K(t, s, x(s)) ds + g(t), t \in [a, b] \right\}.$$

The proof follows the following steps.

1.  $T(x) \in P_{cl}(C([a, b], \mathbb{R}^n))$ .

From (e) and Theorem 2 in Rybiński [9] we have that for each  $x \in C([a, b], \mathbb{R}^n)$  there exists  $k(t, s) \in K(t, s, x(s))$ , for all  $(t, s) \in [a, b]$ , such that  $k(t, s)$  is integrable with respect to  $s$  and continuous with respect to  $t$ . Then

$$v(t) := \int_a^b k(t, s) ds + g(t),$$

has the property  $v \in T(x)$ . Moreover, from (a) and (b), via Theorem 8.6.4. in Aubin and Frankowska [1], we get that  $T(x)$  is a closed set, for each  $x \in C([a, b], \mathbb{R}^n)$ .

2.  $H(T(x_1), T(x_2)) \leq \varphi(\|x_1 - x_2\|)$ , for each  $x_1, x_2 \in C([a, b], \mathbb{R}^n)$ .

Let  $x_1, x_2 \in C([a, b], \mathbb{R}^n)$  and  $v_1 \in T(x_1)$ . Then

$$v_1(t) \in \int_a^t K(t, s, x_1(s)) ds + g(t), \quad t \in [a, b].$$

It follows that

$$v_1(t) = \int_a^b k_1(t, s) ds + g(t),$$

$t \in [a, b]$ , where  $k_1(t, s) \in K(t, s, x_1(s))$ ,  $(t, s) \in [a, b] \times [a, b]$ .

From (d) we have  $H(K(t, s, x_1(s)), K(t, s, x_2(s))) \leq p(t, s)\varphi(\|x_1(s) - x_2(s)\|) \leq p(t, s)\varphi(\|x_1 - x_2\|)$ , so there exists  $w \in K(t, s, x_2(s))$  such that  $\|k_1(t, s) - w\| \leq p(t, s)\varphi(\|x_1 - x_2\|)$ ,  $t, s \in [a, b]$ .

Let us define  $U : [a, b] \times [a, b] \rightarrow \mathcal{P}(\mathbb{R}^n)$ , by  $U(t, s) = \{w \mid \|k_1(t, s) - w\| \leq p(t, s)\varphi(\|x_1 - x_2\|)\}$ . Since the multi-valued operator  $V(t, s) := U(t, s) \cap K(t, s, x_2(s))$  is jointly measurable and lower semi-continuous in  $t$  there exists  $k_2(t, s)$  a selection for  $V$ , jointly measurable (and hence integrable in  $s$ ) and continuous in  $t$ . So,  $k_2(t, s) \in K(t, s, x_2(s))$  and  $\|k_1(t, s) - k_2(t, s)\| \leq p(t, s)\varphi(\|x_1 - x_2\|)$ , for each  $t, s \in [a, b]$ .

Consider  $v_2(t) = \int_a^b k_2(t, s)ds + g(t)$ ,  $t \in [a, b]$ . We have:

$$\begin{aligned} \|v_1(t) - v_2(t)\| &\leq \int_a^b \|k_1(t, s) - k_2(t, s)\|ds \leq \int_a^b p(t, s)\varphi(\|x_1 - x_2\|)ds \\ &\leq \varphi(\|x_1 - x_2\|). \end{aligned}$$

A similar relation can be obtained by interchanging the roles of  $x_1$  and  $x_2$ . So the second step follows.

The conclusion follows from Theorem 5.  $\square$

EXAMPLE 3. If  $g \in C[a, b]$ , and  $K(s, u) := [\frac{u}{2(1+u)}, \frac{u}{1+u}]$  then the integral inclusion

$$x(t) \in \int_a^b K(s, x(s))ds + g(t), \text{ for each } t \in [a, b]$$

has at least one unique solution in  $C[a, b]$ . The conclusion follows by an application of Theorem 6 with  $\varphi(t) = \frac{t}{1+t}$ .

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