

BEST UNIFORM APPROXIMATION OF SEMI-LIPSCHITZ
FUNCTIONS BY EXTENSIONS*

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Abstract. In this paper we consider the problem of best uniform approximation of a real valued semi-Lipschitz function F defined on an asymmetric metric space (X, d) , by the elements of the set $\mathcal{E}_d(F|_Y)$ of all extensions of $F|_Y$ ($Y \subset X$), preserving the smallest semi-Lipschitz constant. It is proved that, this problem has always at least a solution, if (X, d) is (d, \bar{d}) -sequentially compact, or of finite diameter.

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1. INTRODUCTION

Let X be a non-empty set. A function $d : X \times X \rightarrow [0, \infty)$ is called a *quasi-metric* on X [14] if the following conditions hold:

- 1) $d(x, y) = d(y, x) = 0$ iff $x = y$,
- 2) $d(x, z) \leq d(x, y) + d(y, z)$, for all $x, y, z \in X$.

The function $\bar{d} : X \times X \rightarrow [0, \infty)$ defined by $\bar{d}(x, y) = d(y, x)$, for all $x, y \in X$ is also a quasi-metric on X , called the *conjugate* quasi-metric of d .

A pair (X, d) where X is a non-empty set and d a quasi-metric on X , is called a quasi-metric space.

If d can take the value $+\infty$, then it is called a *quasi-distance* on X .

Each quasi-metric d on X induces a topology $\tau(d)$ which has as a basis the family of balls (*forward open balls* [5])

$$(1) \quad B^+(x, \varepsilon) := \{y \in X : d(x, y) < \varepsilon\}, \quad x \in X, \quad \varepsilon > 0.$$

This topology is called the *forward topology of X* ([5], [9]), and is denoted also by τ_+ .

Observe that the topology τ_+ is a T_0 -topology. If the condition 1) is replaced by 1') $d(x, y) = 0$ iff $x = y$, then the topology τ_+ is a T_1 -topology (see [14], [15]).

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Analogously, the quasi-metric \bar{d} induces the topology $\tau(\bar{d})$ on X , which has as a basis the family of *backward open balls* ([5])

$$(2) \quad B^-(x, \varepsilon) := \{y \in X : d(y, x) < \varepsilon\}, \quad x \in X, \quad \varepsilon > 0$$

This topology is called the *backward topology* of X ([5], [9]) and is denoted also by τ_- .

For more information about quasi-metric spaces and their applications see, for example, the papers [5], [6], [7], [9], [14] and the references quoted therein.

Let (X, d) be a quasi-metric space. A sequence $(x_k)_{k \geq 1} \subset X$ is called *d-convergent* (*forward convergent*) to $x_0 \in X$, respectively *\bar{d} -convergent* (*backward convergent*) to $x_0 \in X$ iff

$$(3) \quad \lim_{k \rightarrow \infty} d(x_0, x_k) = 0, \quad \text{respectively} \quad \lim_{k \rightarrow 0} d(x_k, x_0) = \lim_{k \rightarrow \infty} \bar{d}(x_0, x_k) = 0.$$

(see [5], Definition 2.4)

A subset K of X is called *d-compact* (*forward compact*) if every open cover of K with respect to the forward topology τ_+ has a finite subcover. We say that a subset K of X is *d-sequentially compact* (*forward-sequentially compact*) if every sequence in K has a *d-convergent* (*forward convergent*) subsequence with limit in K ([5], Definition 4.1).

The \bar{d} -compact (*backward compact*) and \bar{d} -sequentially compact (*backward-sequentially compact*) subset of X - are defined in a similar way.

Finally, a subset Y of (X, d) is called *(d, \bar{d})-sequentially compact* if every sequence $(y_n)_{n \geq 1}$ in Y has a subsequence $(y_{n_k})_{k \geq 1}$, *d-convergent* to some $u \in Y$ and \bar{d} -convergent to some $v \in Y$. By Lemma 3.1 in [5] it follows that we can take $u = v$ in the definition of *(d, \bar{d})-sequentially compactness*, if (X, d) is a T_1 quasi-metric space. A subset Y of (X, d) is called *d-bounded* (*forward bounded* in [5]) if there exist $x \in X$ and $r > 0$, such that $Y \subset B^+(x, r)$. Y is called *d-totally bounded* if for every $\varepsilon > 0$, there exists $n \in \mathbb{N}$, and the forward balls $B^+(y_1, \varepsilon), B^+(y_2, \varepsilon), \dots, B^+(y_n, \varepsilon)$, $y_i \in Y$, $i = \overline{1, n}$ such that $Y \subset \bigcup_{i=1}^n B^+(y_i, \varepsilon)$.

Similar definitions are given for \bar{d} -boundedness and \bar{d} -total boundedness of a subset Y of (X, d) .

2. THE CONE OF SEMI-LIPSCHITZ FUNCTIONS

DEFINITION 1. [15] *Let Y be a non-empty subset of a quasi-metric space (X, d) . A function $f : Y \rightarrow \mathbb{R}$ is called *d-semi-Lipschitz* if there exists a number $L \geq 0$ (named a *d-semi-Lipschitz constant* for f) such that*

$$(4) \quad f(x) - f(y) \leq Ld(x, y),$$

for all $x, y \in Y$.

A function $f : Y \rightarrow \mathbb{R}$, is called *\leq_d -increasing* if $f(x) \leq f(y)$, whenever $d(x, y) = 0$.

Denote by $\mathbb{R}_{\leq d}^Y$ the set of all $\leq d$ -increasing functions on Y . This set is a cone in the linear space \mathbb{R}^Y of real valued functions defined on Y , i.e. for each $f, g \in \mathbb{R}_{\leq d}^Y$ and $\lambda \geq 0$ it follows that $f + g \in \mathbb{R}_{\leq d}^Y$ and $\lambda f \in \mathbb{R}_{\leq d}^Y$.

For a d -semi-Lipschitz function f on Y , put [14]:

$$(5) \quad \|f\|_d = \sup \left\{ \frac{(f(x)-f(y)) \vee 0}{d(x,y)} : d(x,y) > 0; x, y \in Y \right\}$$

Then $\|f\|_d$ is the smallest d -semi-Lipschitz constant of f (see also [10], [15]).

For a fixed element $\theta \in Y$ denote

$$(6) \quad d\text{-SLip}_0 Y := \{f \in \mathbb{R}_{\leq d}^Y : \|f\|_d < \infty \text{ and } f(\theta) = 0\},$$

the set of all d -semi-Lipschitz real valued functions defined on Y vanishing at the fixed element $\theta \in Y$.

Observe that if (X, d) is a T_1 quasi-metric space, then every real-valued function on X is $\leq d$ -increasing [14].

The set $d\text{-SLip}_0 Y$ is a cone (a subcone of $\mathbb{R}_{\leq d}^Y$) and the functional $\|\cdot\|_d : d\text{-SLip}_0 Y \rightarrow [0, \infty)$ defined by (5) is subadditive and positive homogeneous on $d\text{-SLip}_0 Y$. Moreover $\|f\|_d = 0$ iff $f = 0$, and consequently $\|\cdot\|_d$ is a quasi-norm (asymmetric norm) on the cone $d\text{-SLip}_0 Y$.

In [15] some properties of the “normed cone” $(d\text{-SLip}_0 Y, \|\cdot\|_d)$ are presented. Similar properties in the case of d -semi-Lipschitz functions on a quasi-metric space with values in a quasi-normed space (space with asymmetric norm) are discussed in [16], [17]. For more information concerning other properties of quasi-metric spaces, see also [7], [13].

Now, let (X, d) be a quasi-metric space and let Y be a non-empty subset of X . A real valued function f defined on Y is called τ_+ -lower semi-continuous (τ_+ -l.s.c in short) (respectively τ_- -upper semi-continuous (τ_- -u.s.c.)) at $x_0 \in Y$, if for every $\varepsilon > 0$ there exists $r > 0$ such that for every $x \in B^+(x_0, r)$ (respectively, for every $x \in B^-(x_0, r)$), $f(x) > f(x_0) - \varepsilon$ (respectively $f(x) < f(x_0) + \varepsilon$).

PROPOSITION 2. *Let (X, d) be a quasi-metric space, $\theta \in X$ a fixed element, and $Y \subseteq X$ with $\theta \in Y$. Then every $f \in d\text{-SLip}_0 Y$ is τ_- -u.s.c and τ_+ -l.s.c., and every $f \in \bar{d}\text{-SLip}_0 Y$ is τ_+ -u.s.c. and τ_- -l.s.c. on Y .*

Proof. Let $f \in d\text{-SLip}_0 Y$ such that $\|f\|_d = 0$. Then $f \equiv 0$ and f is τ_- -u.s.c. and τ_+ -l.s.c at every $y \in Y$.

Now, let $\|f\|_d > 0$ and $y_0 \in Y$. The inequality

$$f(y) - f(y_0) \leq \|f\|_d d(y, y_0), \quad y \in Y$$

implies

$$f(y) \leq f(y_0) + \|f\|_d d(y, y_0), \quad y \in Y.$$

So that

$$f(y) < f(y_0) + \varepsilon,$$

for every $\varepsilon > 0$ and every $y \in B^-\left(y_0, \frac{\varepsilon}{\|f\|_d}\right)$, showing that f is τ_- -u.s.c at $y_0 \in Y$.

Similarly,

$$f(y_0) - f(y) \leq \|f\|_d \cdot d(y_0, y), \quad y \in Y,$$

implies

$$f(y) \geq f(y_0) - \|f\|_d d(y_0, y),$$

so that

$$f(y) > f(y_0) - \varepsilon,$$

for every $y \in B^+\left(y_0, \frac{\varepsilon}{\|f\|_d}\right)$, showing that f is τ_+ -l.s.c. in $y_0 \in Y$.

Similarly one prove that every $f \in \bar{d}\text{-SLip}_0 Y$ is τ_+ -u.s.c. and τ_- -l.s.c. on Y . \square

Observe that if f is in $d\text{-SLip}_0 Y$, then $-f \in \bar{d}\text{-SLip}_0 Y$, and $-f$ is τ_+ -u.s.c, and τ_- -l.s.c. on Y , i.e. if $y_0 \in Y$ then

- $\forall \varepsilon > 0, \exists r > 0$ such that $(-f)(y) < (-f)(y_0) + \varepsilon$, for all $y \in B^+(y_0, r)$, and respectively
- $\forall \varepsilon > 0, \exists r > 0$ such that $(-f)(y) > (-f)(y_0) - \varepsilon$, for all $y \in B^-(y_0, r)$.

PROPOSITION 3. *Let (X, d) be a quasi-metric space, $\theta \in X$ a fixed element, and $Y \subset X$, with $\theta \in Y$.*

- (a) *If Y is \bar{d} -sequentially compact, then each $f \in d\text{-SLip}_0 Y$ attains its maximum value on Y ;*
- (b) *If Y is d -sequentially compact, then each $f \in d\text{-SLip}_0 Y$ attains its minimum value on Y .*

Proof. (a) Let Y be \bar{d} -sequentially compact and $M := \sup f(Y)$, where $M \in \mathbb{R} \cup \{+\infty\}$. Then there exists a sequence $(y_n)_{n \geq 1}$ in Y such that $\lim_{n \rightarrow \infty} f(y_n) = M$. Because Y is \bar{d} -sequentially compact, there exists $y_0 \in Y$ and a subsequence $(y_{n_k})_{k \geq 1}$ of $(y_n)_{n \geq 1}$ such that $\lim_{n \rightarrow \infty} d(y_{n_k}, y_0) = 0$. By the τ_- -u.s.c. of f at y_0 it follows:

$$M = \lim_{k \rightarrow \infty} f(y_{n_k}) = \limsup_k f(y_{n_k}) \leq f(y_0) = M,$$

implying $M < \infty$ and $f(y_0) = M$.

(b) If $f \in d\text{-SLip}_0 Y$, it follows $-f \in \bar{d}\text{-SLip}_0 Y$, and because Y is d -sequentially compact, by (a), it follows that $-f$ attains its maximum value on Y , i.e. f attains its minimum value on Y . \square

PROPOSITION 4. *Let (X, d) be a quasi-metric space, $\theta \in X$ a fixed element, and $Y \subseteq X$ with $\theta \in Y$.*

- (a) *If Y is \bar{d} -sequentially compact, then the functional $\|\cdot\|_\infty^{\bar{d}} : d\text{-SLip}_0 Y \rightarrow [0, \infty)$ defined by*

$$(7) \quad \|f\|_\infty^{\bar{d}} = \max\{f(y) : y \in Y\}$$

is an asymmetric norm on $d\text{-SLip}_0 Y$.

(b) If Y is d -sequentially compact, then the functional $\|\cdot\|_\infty^d : d\text{-SLip}_0Y \rightarrow [0, \infty)$ defined by

$$(8) \quad \|f\|_\infty^d = \max\{-f(y) : y \in Y\}, f \in d\text{-SLip}_0Y,$$

is an asymmetric norm on $d\text{-SLip}_0Y$;

(c) If Y is (d, \bar{d}) -sequentially compact, then the functional $\|\cdot\|_\infty : d\text{-SLip}_0Y \rightarrow [0, \infty)$ defined by

$$(9) \quad \|f\|_\infty = \|f\|_\infty^d \vee \|f\|_\infty^{\bar{d}}, f \in d\text{-SLip}_0Y$$

is the uniform norm on the cone $d\text{-SLip}_0Y$.

Proof. (a) By Proposition 3 (a), the functional (7) is well defined. For every $f \in d\text{-SLip}_0Y$, we have $\|f\|_\infty^{\bar{d}} \geq f(\theta) = 0$. If $f \in d\text{-SLip}_0Y$ and $\|f\|_\infty^d > 0$ then there exists $y_0 \in Y$ such that $f(y_0) = \|f\|_\infty^d > 0$. It follows $f \neq 0$.

• Obviously,

$$\|f + g\|_\infty^{\bar{d}} \leq \|f\|_\infty^{\bar{d}} + \|g\|_\infty^{\bar{d}}$$

and

$$\|\lambda f\|_\infty^{\bar{d}} = \lambda \|f\|_\infty^{\bar{d}}$$

for all $f, g \in d\text{-SLip}_0Y$ and $\lambda \geq 0$.

(b) For every $f \in d\text{-SLip}_0Y$ it follows that $-f \in \bar{d}\text{-SLip}_0Y$, and because Y is d -sequentially compact, then $-f$ attains its maximum value on Y , and

$$\|f\|_\infty^d = \max\{-f(y) : y \in Y\}$$

is an asymmetric norm on $d\text{-SLip}_0Y$.

(c) By Proposition 3, if Y is (d, \bar{d}) -sequentially compact, then every $f \in d\text{-SLip}_0Y$, attains its maximum and minimum value on Y .

• We have

$$\begin{aligned} \|f\|_\infty &= \max\{|f(y)| : y \in Y\} = \\ &= (\max\{f(y) : y \in Y\}) \vee (\max\{-f(y) : y \in Y\}) \\ &= \|f\|_\infty^d \vee \|f\|_\infty^{\bar{d}}. \end{aligned}$$

□

3. BEST UNIFORM APPROXIMATION BY EXTENSIONS

In the following the quasi-metric space (X, d) is supposed (d, \bar{d}) -sequentially compact. Let $\theta \in X$ be a fixed element, and $Y \subseteq X$ with $\theta \in Y$. Consider also the normed cones $(d\text{-SLip}_0Y, \|\cdot\|_d)$ and $(\bar{d}\text{-SLip}_0X, \|\cdot\|_{\bar{d}})$, where $\|\cdot\|_{\bar{d}}$ is the asymmetric norm defined as in (5), where d is replaced by \bar{d} .

An extension results for semi-Lipschitz functions, analogous to Mc Shane's Extension Theorem [8] for real-valued Lipschitz functions defined on a subset of a metric space was proved in [10] (see also [12]).

PROPOSITION 5. [10] *For every $f \in d\text{-SLip}_0 Y$ there exists at least one function $F \in d\text{-SLip}_0 X$, such that*

$$(10) \quad F|_Y = f \text{ and } \|F\|_d = \|f\|_d.$$

A function F with the properties included in Proposition 5, is called an *extension*, preserving the asymmetric norm of f (or an extension preserving the smallest semi-Lipschitz constant of f).

Denote the set of all extensions of f preserving asymmetric norm, by

$$(11) \quad \mathcal{E}_d(f) = \{F \in d\text{-SLip}_0 X : F|_Y = f \text{ and } \|F\|_d = \|f\|_d\}$$

The set $\mathcal{E}_d(f)$ is convex in $d\text{-SLip}_0 X$, the functions

$$(12) \quad F_d(f)(x) = \inf \{f(y) + \|f\|_d d(x, y) : y \in Y\}, \quad x \in X,$$

and

$$(13) \quad G_d(f)(x) = \sup \{f(y) - \|f\|_d \cdot d(y, x) : y \in Y\}, \quad x \in X,$$

are extremal elements of $\mathcal{E}_d(f)$, and

$$(14) \quad G_d(f)(x) \leq F(x) \leq F_d(f)(x),$$

for all $F \in \mathcal{E}_d(f)$ (see [10], [11]).

Now let \mathbb{R}^X be the linear space of all real valued functions defined on (X, d) . One considers the quasi-distance ([15], p.67)

$$D_d : \mathbb{R}^X \times \mathbb{R}^X \rightarrow [0, \infty)$$

defined by

$$(15) \quad D_d(f, g) = \sup \{(f(x) - g(x)) \vee 0 : x \in X\}.$$

Obviously, $d\text{-SLip}_0 X \subset \mathbb{R}_{\leq d}^X \subset \mathbb{R}^X$, and the quasi-distance D_d may be restricted to $d\text{-SLip}_0 X$.

The quasi-distance D_d generates the topology $\tau(D_d)$, named the topology of quasi-uniform convergence. In [15] (Corollary 4, p.67), it is proved that the unit ball U_0 of $d\text{-SLip}_0 X$ is compact with respect to the topology of quasi-uniform convergence $\tau(D_d)$, (and $\tau(\overline{D}_d)$ too, where $\overline{D}_d(f, g) = D_d(g, f)$, $f, g \in d\text{-SLip}_0 X$).

We have

PROPOSITION 6. *For every $f \in d\text{-SLip}_0 Y$, the set $\mathcal{E}_d(f)$ is compact with respect to the topology $\tau(D_d)$, (and $\tau(\overline{D}_d)$, too).*

Proof. Because $F_d(f)$ defined in (12) and $G_d(f)$ defined in (13) are in $\mathcal{E}_d(f)$, and they satisfy the inequalities (14), it follows

$$D_d(F, F_d(f)) = 0, \text{ and } \overline{D}_d(F, G_d(f)) = D_d(G_d(f), F) = 0$$

for every $F \in \mathcal{E}_d(f)$. It follows that $\mathcal{E}_d(f)$ is D_d -totally bounded (and \overline{D}_d -totally bounded too).

Let $(F_n)_{n \geq 1}$ be a sequence in $\mathcal{E}_d(f)$. Because $F_n(x) \leq F_d(f)(x)$, for all $x \in X$, it follows that $D_d(F_n, F_d(f)) = 0$, $n = 1, 2, \dots$, i.e. $(F_n)_{n \geq 1}$ is D_d -convergent to $F_d(f)$. It follows that $\mathcal{E}_d(f)$ is D_d -sequentially compact. By Proposition 4.6 in [5], because $\mathcal{E}_d(f)$ is totally D_d -bounded and D_d -sequentially compact it follows that the set $\mathcal{E}_d(f)$ is D_d -compact (i.e. compact with respect to the topology $\tau(D_d)$).

Because $G_d(f)(x) \leq F(x)$, for all $x \in X$ and every $F \in \mathcal{E}_d(f)$, it follows that $D_d(G_d(f), F) = \overline{D}_d(F, G_d(f)) = 0$. Consequently, $\mathcal{E}_d(f)$ is \overline{D}_d -compact too. (i.e. with respect to the topology $\tau(\overline{D}_d)$). \square

Obviously, for every $F \in d\text{-SLip}_0 X$, $F|_Y \in d\text{-SLip}_0 Y$ and the set $\mathcal{E}_d(F|_Y)$ is a (D_d, \overline{D}_d) -compact subset of $d\text{-SLip}_0 X$, by Proposition 6.

Now, we consider the following optimization problem:

For $F \in d\text{-SLip}_0 X$, find $G_0 \in \mathcal{E}_d(F|_Y)$ such that

$$(16) \quad D_d(F, G_0) = \inf\{D_d(F, G) : G \in \mathcal{E}_d(F|_Y)\}.$$

This problem (of best approximation) has always at least one solution, because $\mathcal{E}_d(F|_Y)$ is D_d -compact. Analogously, the problem of existence of an element $\overline{G}_0 \in \mathcal{E}_d(F|_Y)$ such that

$$(17) \quad \overline{D}_d(F, \overline{G}_0) = \inf\{\overline{D}_d(F, G) : G \in \mathcal{E}_d(F|_Y)\},$$

is also assured, because $\mathcal{E}_d(F|_Y)$ is \overline{D}_d -compact too.

Now, because (X, d) is supposed (d, \overline{d}) -sequentially compact, every $F \in d\text{-SLip}_0 X$ is bounded, and the uniform norm

$$(18) \quad \|F\|_\infty = \max\{F(x) : x \in X\} \vee \max\{-F(x) : x \in X\}$$

is well defined, by Proposition 4, (c).

Moreover, for every $G \in \mathcal{E}_d(F|_Y)$, we have

$$(19) \quad \|F - G\|_\infty = D_d(F, G) \vee \overline{D}_d(F, G).$$

Now, we consider the following *problem of uniform best approximation*:

For $F \in d\text{-SLip}_0 X$, find $G_0 \in \mathcal{E}_d(F|_Y)$, such that

$$(20) \quad \|F - G_0\|_\infty = \inf\{\|F - G\|_\infty : G \in \mathcal{E}_d(F|_Y)\}.$$

PROPOSITION 7. *Let (X, d) be a (d, \overline{d}) -sequentially compact quasi-metric space, $\theta \in X$ a fixed element, and $Y \subset X$ with $\theta \in Y$. Then for every $F \in d\text{-SLip}_0 X$, there exists at least one element $G_0 \in \mathcal{E}_d(F|_Y)$, such that*

$$\|F - G_0\|_\infty = \inf\{\|F - G\|_\infty : G \in \mathcal{E}_d(F|_Y)\}.$$

Proof. For every $G \in \mathcal{E}_d(F|_Y)$, using the equality (18), one obtains

$$\begin{aligned} \inf\{\|F - G\|_\infty : G \in \mathcal{E}_d(F|_Y)\} &= \\ &= \inf\{D_d(F, G) \vee D_d(G, F) : G \in \mathcal{E}_d(F|_Y)\} \end{aligned}$$

Because $\mathcal{E}_d(F|_Y)$ is (D_d, \overline{D}_d) -compact, the conclusion of Proposition follows. \square

Any solution $G_0 \in \mathcal{E}_d(F|_Y)$ of problem (20) is called an element of best uniform approximation of F by elements of $\mathcal{E}_d(F|_Y)$.

Using (19), one obtains:

If F is such that

$$F(x) \geq F_d(F|_Y)(x), x \in X,$$

then $G_0 = F_d(F|_Y)$ is the unique solution of (20), where $F_d(F|_Y)$ is defined as in (12);

If F is such that

$$F(x) \leq G_d(F|_Y)(x), x \in X,$$

then $G_0 = G_d(F|_Y)$ is the unique solution of (20), where $G_d(F|_Y)$ is defined as in (13);

Finally, if $F \in \mathcal{E}_d(F|_Y)$ i.e. $\|F\|_d = \|F|_Y\|_d$, then $G_0 = F$.

In the following we consider another situation where a uniform best approximation problem by extensions may be posed and solved.

This is the case when the quasi-metric space (X, d) is of finite diameter, i.e. such that $\sup\{d(x, y) : x, y \in X\} = \text{diam}X < \infty$.

For $\theta \in (X, d)$ denote $cl_{\tau(d)}\{\theta\} = \{x \in X : d(\theta, x) = 0\}$ and $cl_{\tau(\overline{d})}\{\theta\} = \{x \in X : d(x, \theta) = 0\}$ (see [15], p.68). Let also $cl\{\theta\} = cl_{\tau(d)}\{\theta\} \cup cl_{\tau(\overline{d})}\{\theta\}$.

The following proposition holds:

PROPOSITION 8. *Let (X, d) be a quasi-metric space of finite diameter, and $\theta \in X$ a fixed element. Then every $f \in d\text{-SLip}_0X$ is bounded on $X \setminus cl\{\theta\}$.*

Proof. Let f be in $d\text{-SLip}_0X$. By definition, we have $f(\theta) = 0$, and for $x \in cl_{\tau(\overline{d})}\{\theta\} = \{x \in X : d(x, \theta) = 0\}$ -it follows $f(x) \leq 0$, because $d(x, \theta) = 0$ implies $f(x) \leq f(\theta) = 0$.

Analogously, for $x \in cl_{\tau(d)}\{\theta\} = \{x \in X : d(\theta, x) = 0\}$ it follows $0 = f(\theta) \leq f(x)$.

For every $x \in X \setminus cl_{\tau(\overline{d})}\{\theta\}$, we have

$$f(x) - f(\theta) \leq \|f\|_d d(x, \theta) \leq \|f\|_d \text{diam}X,$$

and consequently $f(x) \leq \|f\|_d \text{diam}X < \infty$.

It follows, $f(x) \leq \|f\|_d \text{diam}X < \infty$ for all $x \in X \setminus cl_{\tau(\overline{d})}\{\theta\}$.

For every $x \in X \setminus cl_{\tau(d)}\{\theta\}$ it follows

$$f(\theta) - f(x) \leq \|f\|_d d(\theta, x) \leq \|f\|_d \text{diam}X.$$

Then $f(x) \geq -\|f\|_d \text{diam}X > -\infty$, for all $x \in X \setminus cl_{\tau(d)}\{\theta\}$. Consequently $-\|f\|_d \text{diam}X \leq f(x) \leq \|f\|_d \text{diam}X$, $x \in X \setminus cl\{\theta\}$. \square

Now, let (X, d) be a quasi-metric space of finite diameter, $\theta \in X$ a fixed element, and $Y \subset X$ with $\theta \in Y$. Then, for every $F \in d\text{-SLip}_0 X$, it follows $F|_Y \in d\text{-SLip}_0 Y$, and the set

$$\mathcal{E}_d(F|_Y) = \{G \in d\text{-SLip}_0 X : G|_Y = F|_Y, \|G\|_d = \|F|_Y\|_d\}$$

is non empty.

This set is also (D_d, \overline{D}_d) -compact and the following proposition holds:

PROPOSITION 9. *Let (X, d) be a quasi-metric space of finite diameter, $\theta \in X$ a fixed element, and $Y \subset X$ with $\theta \in Y$. Then for every $F \in d\text{-SLip}_0 X$, there exists at least one element $G_0 \in \mathcal{E}_d(F|_Y)$ such that*

$$\|(F - G_0)|_{X \setminus d\{\theta\}}\|_\infty = \inf\{\|(F - G)|_{X \setminus d\{\theta\}}\|_\infty : G \in \mathcal{E}_d(F|_Y)\}.$$

The proof is immediate.

EXAMPLE 10. Let $X = [-10, 10]$ and the quasi-metric $d : X \times X \rightarrow [0, \infty)$ defined by

$$d(x, y) = \begin{cases} y - x & \text{if } x \leq y, \\ 2(x - y) & \text{if } x > y. \end{cases}$$

Consider $\theta = 0$ and $Y = \{-1, 0, 1\}$. Then the function $f : Y \rightarrow \mathbb{R}$

$$f(y) = \begin{cases} -1, & y = -1, \\ 0, & y = 0, \\ 3, & y = 1, \end{cases}$$

is in $d\text{-SLip}_0 Y$ and $\|f\|_d = 3$.

The functions

$$\begin{aligned} F_d(f)(x) &= \inf_{y \in Y} \{f(y) + 3d(x, y)\} \\ &= \begin{cases} -4 - 3x, & x \in [-10, -1], \\ 6x + 5, & x \in \left(-1, \frac{-5}{9}\right], \\ -3x, & x \in \left(\frac{-5}{9}, 0\right], \\ 6x, & x \in \left(0, \frac{2}{3}\right], \\ 6 - 3x, & x \in \left(\frac{2}{3}, 1\right], \\ 6x - 3, & x \in (1, 10]. \end{cases} \end{aligned}$$

and, respectively

$$\begin{aligned} G_d(f)(x) &= \sup_{y \in Y} \{f(y) - 3d(y, x)\} = \\ &= \begin{cases} 6x + 5, & x \in [-10, -1], \\ -3x + 4, & x \in \left(-1, \frac{-4}{9}\right], \\ 6x, & x \in \left(\frac{-4}{9}, 0\right], \\ -3x, & x \in \left(0, \frac{1}{3}\right], \\ 6x - 3, & x \in \left(\frac{1}{3}, 1\right], \\ -3x - 6, & x \in (1, 10]. \end{cases} \end{aligned}$$

verifies the conditions:

$$\begin{aligned} F_d(f)|_Y &= G_d(f)|_Y = f, \\ \|F_d(f)|_d &= \|G_d(f)|_d = \|f|_d = 3, \end{aligned}$$

and

$$F_d(f)(x) \geq H(x) \geq G_d(f)(x), \quad x \in [-10, 10],$$

where $H \in \mathcal{E}_d(f)$ is an arbitrary extension of f .

Obviously, (X, d) is (d, \bar{d}) -sequentially compact and $\mathcal{E}_d(f)$ is compact in the uniform topology.

Let $F \in d - \text{SLip}_0 X$ such that $F|_Y = f$.

Then

$$\mathcal{E}_d(F|_Y) = \mathcal{E}_d(f).$$

If

$$F(x) \geq F_d(f)(x), \quad \forall x \in [-10, 10]$$

then

$$\|F - F_d(f)\|_\infty = \inf\{\|F - H\|_\infty : H \in \mathcal{E}_d(F|_Y)\}$$

For example, let F be the function

$$F(x) = \begin{cases} F_d(f)(x), & x \in [-1, 1], \\ -4x - 5, & x \in [-10, -1) \\ 7x - 4, & x \in (1, 10). \end{cases}$$

Then

$$\begin{aligned} \|F - F_d(f)\|_\infty &= \max_{x \in [-10, 1]} \{-x - 1\} \vee \max_{x \in [1, 10]} \{x - 1\} = \\ &= 9 \end{aligned}$$

Similarly, if $F(x) \leq G_d(f)(x), \forall x \in [-10, 10]$

then

$$\|F - G_d(f)\|_\infty = \inf\{\|F - H\|_\infty : H \in \mathcal{E}_d(F|_Y)\}.$$

□

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