# SOLVING EQUATIONS USING NEWTON'S METHOD UNDER WEAK CONDITIONS ON BANACH SPACES WITH A CONVERGENCE STRUCTURE 

IOANNIS K. ARGYROS*


#### Abstract

We provide new semilocal results for Newton's method on Banach spaces with a convergence structure. Using more precise majorizing sequence we show that, under weaker convergence conditions than before, we can obtain finer error bounds on the distances involved and a more precise information on the location of the solution.


MSC 2000. 65J15, 65H10, 65G99, 47H17, 49M15.
Keywords. Newton's method, Banach spaces with a convergence structure, semilocal convergence, Fréchet-derivative, majorant principle, fixed point, Newton-Kantorovich theorem/hypothesis.

## 1. INTRODUCTION

In this study we are concerned with the problem of approximating a locally unique zero $x^{*}$ of the operator

$$
\begin{equation*}
F(x)=A G\left(x_{0}+x\right), \tag{1}
\end{equation*}
$$

where $G$ is an operator Banach space $X$ with a convergence structure (to be precized later) and $A$ is meant to be an approximation of $G^{\prime}\left(x_{0}\right)^{-1} \in L(X, X)$, the space of bounded linear operators from $X$ into $X$.

A large number of problems in applied mathematics and also in engineering are solved by finding the solutions of certain equation. For example, dynamic systems are mathematically modeled by difference or differential equations, and their solutions usually represent the states of the systems. For the sake of simplicity, assume that a time-invariant system is driven by the equation $\dot{x}=$ $\tau(x)$ (for some suitable operator $\tau$ ), where $x$ is the state. Then the equilibrium states are determined by solving equation (1). Similar equations are used in the case of discrete systems. The unknowns of engineering equations can be functions (difference, differential, and integral equations), vectors (systems of linear or nonlinear algebraic equations), or real or complex numbers (single algebraic equations with single unknowns). Except in special cases, the most commonly used solution methods are iterative - when starting from one or

[^0]several initial approximations, a sequence is constructed that converges to a solution of the equation. Iteration methods are also applied for solving optimization problems. In such cases, the iteration sequences converge to an optimal solution of the problem at hand. Since all of these methods have the same recursive structure, they can be introduced and discussed in a general framework.

Using more precise majorizing sequences than before we show that under weaker conditions than before [1]-[3], [5], [6] we can obtain using Newton's method (see (10)), finer error bounds on the distances $\left|x_{n}-x^{*}\right|$ and a more precise information on the location of the solution $x^{*}$.

## 2. PRELIMINARIES

We will need the definitions:
Definition 1. The triple $(X, V, E)$ is a Banach space with a converges structure if
$\left(\mathrm{C}_{1}\right)(X,\|\cdot\|)$ is a real Banach spaces;
$\left(\mathrm{C}_{2}\right)\left(V, C,\|\cdot\|_{V}\right)$ is a real Banach space which is partially ordered by the closed convex cone $C$; the norm $\|\cdot\|_{V}$ is assumed to be monotone on $C$;
$\left(\mathrm{C}_{3}\right) E$ is a closed convex cone in $X \times V$ satisfying $\{0\} \times C \subseteq E \subseteq X \times C$;
$\left(\mathrm{C}_{4}\right)$ the operator $|\cdot|: D_{0} \rightarrow C$ is well defined:

$$
|x|=\inf \{q \in C \mid(x, q) \in E\}
$$

for

$$
x \in D_{0}=\{x \in X \mid \exists q \in C:(x, q) \in E\} ;
$$

and
$\left(\mathrm{C}_{5}\right)$ for all $x \in D_{0} \quad\|x\| \leq\||x|\|_{V}$.
The set

$$
U(a)=\{x \in X \mid(x, a) \in E\}
$$

defines a sort of generalized neighborhood of zero.
Let us given some motivational examples for $X=: \mathbb{R}^{m}$ with the maximumnorm:
(a) $V:=\mathbb{R}, E:=\left\{(x, e) \in \mathbb{R}^{m} \times \mathbb{R} \mid\|x\|_{\infty} \leq e\right\}$
(b) $V:=\mathbb{R}^{m}, E:=\left\{(x, e) \in \mathbb{R}^{m} \times \mathbb{R}^{m}| | x \mid \leq e\right\}$ (componentwise absolute value).
(c) $V:=\mathbb{R}^{m}, E:=\left\{(x, e) \in \mathbb{R}^{m} \times \mathbb{R}^{m} \mid 0 \leq x \leq e\right\}$.

Case (a) involves classical convergence analysis in a Banach space, (b) allows componentwise analysis and error estimates, and (c) is used for monotone convergence analysis.

The convergence analysis will be based on monotonicity considerations in the space $X \times V$. Let $\left(x_{n}, e_{n}\right)$ be an increasing sequence in $E^{N}$, then

$$
\left(x_{n}, e_{n}\right) \leq\left(x_{n+k}, e_{n+k}\right) \Longrightarrow 0 \leq\left(x_{n+k}-x_{n}, e_{n+k}-e_{n}\right) .
$$

If $e_{n} \rightarrow e$, we obtain: $0 \leq\left(x_{n+k}-x_{n}, e-e_{n}\right)$ and hence by ( $\mathrm{C}_{5}$ )

$$
\left\|x_{n+k}-x_{n}\right\| \leq\left\|e-e_{n}\right\|_{V} \rightarrow 0, \quad \text { as } n \rightarrow \infty .
$$

hence $\left\{x_{n}\right\}(n \geq 0)$ is a Cauchy sequence. When deriving error estimates, we shall as well use sequences $e_{n}=w_{0}-w_{n}$ with a decreasing sequence $\left\{w_{n}\right\}$ ( $n \geq 0$ ) in $C^{N}$ to obtain the estimate

$$
0 \leq\left(x_{n+k}-x_{n}, w_{n}-w_{n+k}\right) \leq\left(x_{n+k}-x_{n}, w_{n}\right) .
$$

If $x_{n} \rightarrow x^{*}$, as $n \rightarrow \infty$, this implies the estimate $\left|x^{*}-x_{n}\right| \leq w_{n}(n \geq 0)$. Moreover, if $(x, e) \in E$, then $x \in D_{0}$ and by $\left(\mathrm{C}_{4}\right)$ we deduce $|x| \leq e$.

Definition 2. An operator $L \in C^{1}\left(V_{1} \rightarrow V\right)$ defined on an open subset $V_{1}$ of an ordered Banach space $V$ is order convex on $[a, b] \subseteq V_{1}$ if

$$
\begin{equation*}
c, d \in[a, b], \quad c \leq d \Rightarrow L^{\prime}(d)-L^{\prime}(c) \in L_{+}(V), \tag{2}
\end{equation*}
$$

where for $m \geq 0$

$$
L_{+}\left(V^{m}\right)=\left\{L \in L\left(V^{m}\right) \mid 0 \leq x_{i} \Rightarrow 0 \leq L\left(x_{1}, x_{2}, \ldots, x_{m}\right)\right\}
$$

and $L(V)$ denotes the space of $m$-linear, symmetric, bounded operators on $V$.
Definition 3. The set of bounds for an operator $H \in L\left(X^{m}\right)$ is defined to be
$B(H)=\left\{L \in L_{+}\left(V^{m}\right) \mid\left(x_{i}, q_{i}\right) \in E \Rightarrow\left(H\left(x_{1}, \ldots, x_{m}\right), L\left(q_{1}, \ldots, q_{m}\right)\right) \in E\right\}$.
Definition 4. Let $H \in L(X)$ and $y \in X$ be given, then

$$
\begin{align*}
H^{*}(y) & =z \Longleftrightarrow z=T^{\infty}(0)=\lim _{n \rightarrow \infty} T^{n}(0), \\
T(x) & =(I-H)(x)+y \Longleftrightarrow z=\sum_{i=0}^{\infty}(I-H)^{i} y, \tag{3}
\end{align*}
$$

if this limit exists.
We will also need the Lemmas [2], [6]:
Lemma 5. Let $L \in L_{+}(V)$ and $a, q \in C$ be given such that:

$$
\begin{equation*}
L(q)+a \leq q \quad \text { and } \quad L^{n}(q) \rightarrow 0 \quad \text { as } \quad n \rightarrow \infty . \tag{4}
\end{equation*}
$$

Then the operator

$$
\begin{equation*}
(I-L)^{*}:[0, a] \rightarrow[0, a] \tag{5}
\end{equation*}
$$

is well defined and continuous.
The following is a generalization of Banach's lemma [2], [5], [6].
Lemma 6. Let $H \in L(X), L \in B(H), y \in D_{0}$ and $q \in C$ be such that

$$
\begin{equation*}
L(q)+|y| \leq q \quad \text { and } \quad L^{n}(q) \rightarrow 0 \quad \text { as } \quad n \rightarrow \infty \tag{6}
\end{equation*}
$$

Then the point $x=(I-H)^{*}(y)$ is well defined, $x \in S$ and

$$
\begin{equation*}
|x| \leq(I-L)^{*}|y| \leq q . \tag{7}
\end{equation*}
$$

Moreover, the sequence

$$
b_{n+1}=L\left(b_{n}\right)+|y|, \quad b_{0}=0
$$

is well defined and

$$
\begin{equation*}
b_{n+1} \leq q, \quad \lim _{n \rightarrow \infty} b_{n}=b=(I-L)^{*}|y| \leq q \tag{8}
\end{equation*}
$$

Lemma 7. Let $H_{1}:[0,1] \rightarrow L\left(X^{m}\right)$ and $H_{2}:[0,1] \rightarrow L_{+}\left(V^{m}\right)$ be continuous operators, then for all $t \in[0,1]$ :

$$
\begin{equation*}
H_{2}(t) \in B\left(H_{1}(t)\right) \Rightarrow \int_{0}^{1} H_{2}(t) \mathrm{d} t \in B\left(\int_{0}^{1} H_{1}(t) \mathrm{d} t\right) \tag{9}
\end{equation*}
$$

which will be used for the remainder of Taylor's formula [1], [2], [5], [6].

## 3. SEMILOCAL CONVERGENCE ANALYSIS

We can show the main semilocal convergence result for Newton's method:

$$
\begin{equation*}
x_{0}=0, \quad x_{n+1}=x_{n}+F^{\prime}\left(x_{n}\right)^{*}\left(-F\left(x_{n}\right)\right) \tag{10}
\end{equation*}
$$

Theorem 8. Assume:
there exists a Banach space $X$ with convergence structure $(X, V, E)$ where $V=\left(V, C,\|\cdot\|_{V}\right)$, operators $F \in C^{\perp}\left(X_{F} \rightarrow X\right)\left(X_{F} \subseteq X\right), L_{0} \in C^{1}\left(V_{L_{0}} \rightarrow V\right)$ $\left(V_{L_{0}} \subseteq V\right), L \in C^{1}\left(V_{L_{0}} \rightarrow V\right)\left(V_{L} \subseteq V\right)$, and a point $a \in C$ such that the following conditions hold:

$$
\begin{gather*}
V_{L_{0}} \subseteq V_{L}  \tag{11}\\
U(a) \subseteq X_{F} \quad \text { and } \quad[0, a] \subseteq V_{L_{0}} \tag{12}
\end{gather*}
$$

$L_{0}$ is order-convex on $[0, a]$ and satisfies

$$
\begin{equation*}
L_{0}^{\prime}(|x|)-L_{0}^{\prime}(0) \leq B\left(F^{\prime}(0)-F^{\prime}(x)\right) \tag{13}
\end{equation*}
$$

for all $x \in U(a)$,
$L$ is order-convex on $[0, a]$ and satisfies

$$
\begin{align*}
L^{\prime}(|x|+|y|)-L^{\prime}(|x|) & \in B\left(F^{\prime}(x)-F^{\prime}(x+y)\right) \text { for all }  \tag{14}\\
x, y & \in U(a) \text { with }|x|+|y| \leq a, \\
L_{0}^{\prime}(0) & \in B\left(I-f^{\prime}(0)\right) \quad \text { and } \quad\left(-F(0), L_{0}(0)\right) \in E,  \tag{15}\\
L_{0}^{\prime}(|x|) & \leq L^{\prime}(|x|) \text { for all } x \in U(a)  \tag{16}\\
L_{0}(\bar{a}) & \leq L(\bar{a}) \text { for all } \bar{a} \in[0, a]  \tag{17}\\
L(a) & \leq a \tag{18}
\end{align*}
$$

and

$$
\begin{equation*}
L^{\prime}(a)^{n} a \rightarrow 0 \quad \text { as } \quad n \rightarrow \infty \tag{19}
\end{equation*}
$$

Then sequence $\left\{x_{n}\right\}(n \geq 0)$ generated by Newton's method (2) is well defined and converges to the unique zero $x^{*}$ of $F$ in $U(a)$.

Define sequences $\left\{\bar{d}_{n}\right\},\left\{d_{n}\right\}(n \geq 0)$ by

$$
\begin{equation*}
\bar{d}_{0}=d_{0}=0, \quad \bar{d}_{n+1}=L\left(\bar{d}_{n}\right)+L_{0}^{\prime}\left(\left|x_{n}\right|\right) c_{n} \tag{20}
\end{equation*}
$$

and

$$
\begin{equation*}
d_{n+1}=L\left(d_{n}\right)+L^{\prime}\left(\left|x_{n}\right|\right) c_{n} \tag{21}
\end{equation*}
$$

where

$$
\begin{equation*}
c_{n}=\left|x_{n+1}-x_{n}\right| \tag{22}
\end{equation*}
$$

Then sequences $\left(x_{n}, \bar{d}_{n}\right) \in(X \times V)^{N},\left(x_{n}, d_{n}\right) \in(X \times V)$ are well defined, monotone and satisfy

$$
\begin{equation*}
\bar{d}_{n} \leq d_{n} \leq b \tag{23}
\end{equation*}
$$

where $b=L^{\infty}(0)$ is the smallest fixed point of $L$ in $[0, a]$.
Proof. First, we observe that the conditions of the Theorem are satisfied if $b$ replaces $a$. For $n=1$ we have to solve

$$
\begin{equation*}
w=\left(I-F^{\prime}(0)\right) w-F(0) \tag{24}
\end{equation*}
$$

By (15), 16) and the order convexity of $L$ we get for $w=b$
$(25) L_{0}^{\prime}(0) b+|-F(0)| \leq L^{\prime}(0) b+L_{0}(0) \leq L(b)-L(0)+L_{0}(0) \leq L(b)=b$.
Hence, $x_{1}$ is well defined, $\left(x_{1}, b\right) \in E$. We also have

$$
\begin{aligned}
x_{1} & =\left(I-F^{\prime}(0)\right) x_{1}+(-F(0)) \Rightarrow \\
\left|x_{1}\right| & \leq L_{0}^{\prime}(0)\left|x_{1}\right|+L_{0}(0)=\bar{d}_{1} \leq L^{\prime}(0)\left|x_{1}\right|+L(0)=d_{1}
\end{aligned}
$$

and by the order convexity of $L$,

$$
d_{1}=L^{\prime}(0)\left|x_{1}\right|+L(0) \leq L^{\prime}(0) b+L(0) \leq L(b)-L(0)+L(0)=L(b)=b
$$

Assume sequences $\left(x_{n}, \bar{d}_{n}\right),\left(x_{n}, d_{n}\right)$ are well defined and monotone up to $n \in N$ with

$$
\begin{equation*}
0 \leq\left(x_{n-1}, \bar{d}_{k-1}\right) \leq\left(x_{k}, d_{k}\right) \quad(k=1, \ldots, n), \bar{d}_{k} \leq d_{k} \leq b \tag{26}
\end{equation*}
$$

We must solve

$$
\begin{equation*}
w=\left(I-F^{\prime}\left(x_{n}\right)\right) w+\left(-F\left(x_{n}\right)\right) \tag{27}
\end{equation*}
$$

Using (13), 15) and (16) we get in turn

$$
\begin{align*}
\left|I-F^{\prime}\left(x_{n}\right)\right| & =\left|I-F^{\prime}(0)+F^{\prime}(0)-F^{\prime}\left(x_{n}\right)\right| \\
& \leq\left|I-F^{\prime}(0)\right|+\left|F^{\prime}(0)-F^{\prime}\left(x_{n}\right)\right| \\
& \leq L_{0}^{\prime}(0)+L_{0}^{\prime}\left(\left|x_{n}\right|\right)-L_{0}^{\prime}(0)=L_{0}^{\prime}\left(\left|x_{n}\right|\right) . \tag{28}
\end{align*}
$$

Hence, we conclude $L_{0}^{\prime}\left(\left|x_{n}\right|\right) \in B\left(I-F^{\prime}\left(x_{n}\right)\right)$.
We must solve

$$
\begin{equation*}
L_{0}^{\prime}\left(\left|x_{n}\right|\right) q+\left|-F\left(x_{n}\right)\right| \leq q \tag{29}
\end{equation*}
$$

But

$$
\begin{align*}
\left|-F\left(x_{n}\right)\right| & =\left|-F\left(x_{n}\right)+F\left(x_{n-1}\right)+F^{\prime}\left(x_{n-1}\right)\left(x_{n}-x_{n-1}\right)\right| \\
& \leq \int_{0}^{1}\left[L^{\prime}\left(\left|x_{n-1}\right|+t c_{n-1}\right)-L^{\prime}\left(\left|x_{n-1}\right|\right)\right] c_{n-1} \mathrm{~d} t \\
& =L\left(\left|x_{n-1}\right|+c_{n-1}\right)-L\left(\left|x_{n-1}\right|\right)-L^{\prime}\left(\left|x_{n-1}\right|\right) c_{n-1} \\
& \leq L\left(\bar{d}_{n-1}+\bar{d}_{n}-\bar{d}_{n-1}\right)-L\left(\bar{d}_{n-1}\right)-L_{0}^{\prime}\left(\left|x_{n-1}\right|\right) c_{n-1} \\
& =L\left(\bar{d}_{n}\right)-\bar{d}_{n} \leq L\left(d_{n}\right)-d_{n} \tag{30}
\end{align*}
$$

Set $q=b-\bar{d}_{n}$ to get in turn

$$
\begin{aligned}
L_{0}^{\prime}\left(\left|x_{n}\right|\right) q+\left|-F\left(x_{n}\right)\right|+\bar{d}_{n} & \leq L_{0}^{\prime}\left(\bar{d}_{n}\right)\left(b-\bar{d}_{n}\right)+L\left(d_{n}\right) \\
& \leq L^{\prime}\left(d_{n}\right)\left(b-d_{n}\right)+L\left(d_{n}\right) \\
& \leq L(b)-L\left(d_{n}\right)+L\left(d_{n}\right)=L(b)=b
\end{aligned}
$$

That is $x_{n+1}$ is well defined and

$$
\begin{equation*}
c_{n} \leq b-\bar{d}_{n} \leq b-d_{n} \tag{32}
\end{equation*}
$$

Moreover $\bar{d}_{n+1}, d_{n+1}$ are well defined also and
(33) $\bar{d}_{n+1} \leq L\left(d_{n}\right)+L_{0}^{\prime}\left(\bar{d}_{n}\right)\left(b-\bar{d}_{n}\right) \leq L\left(d_{n}\right)+L^{\prime}\left(d_{n}\right)\left(b-d_{n}\right) \leq L(b)=b$.

Furthermore the monotonicity of

$$
\left(x_{n}, \bar{d}_{n}\right) \leq\left(x_{n+1}, \bar{d}_{n+1}\right),\left(x_{n}, d_{n}\right) \leq\left(x_{n+1}, d_{n+1}\right)
$$

follows from
(34) $c_{n}+\bar{d}_{n+1} \leq L_{0}^{\prime}\left(\left|\bar{x}_{n}\right|\right) c_{n}+\left|-F\left(x_{n}\right)\right|+\bar{d}_{n} \leq L_{0}^{\prime}\left(\left|x_{n}\right|\right) c_{n}+L\left(\bar{d}_{n}\right)=\bar{d}_{n+1}$
and
(35) $c_{n}+d_{n+1} \leq L^{\prime}\left(\left|x_{n}\right|\right) c_{n}+\left|-F\left(x_{n}\right)\right|+d_{n} \leq L^{\prime}\left(\left|x_{n}\right|\right) c_{n}+L\left(d_{n}\right)=d_{n+1}$.

By the definition of $\left\{\bar{d}_{n}\right\},\left\{d_{n}\right\}$ we get inductively

$$
\begin{equation*}
L^{n}(0) \leq d_{n} \leq b \quad \text { and } \quad L_{0}^{n}(0) \leq \bar{d}_{n} \leq b \tag{36}
\end{equation*}
$$

which together with $L^{n}(0) \rightarrow b$ as $n \rightarrow \infty$ imply $\bar{d}_{n} \rightarrow b^{*}$ and $d_{n} \rightarrow b$ as $n \rightarrow \infty$ for some $b^{*}$ such that $L_{0}^{n}(0) \leq b^{*} \leq b \leq \bar{d}_{n}$, sequence $\left\{x_{n}\right\}$ converges to some $x^{*} \in U\left(b^{*}\right)$, and by (30) $x^{*}$ is a zero of $F$.

To show uniqueness consider the modified Newton's method

$$
\begin{equation*}
y_{n+1}=y_{n}-F\left(y_{n}\right) \tag{37}
\end{equation*}
$$

Then sequence $\left\{y_{n}\right\}$ converges and $\left(x_{n}, L^{*}(0)\right)$ is monotone in $X \times V$. Assume $y^{*} \in U(a)$ is a zero of $F$. Then we can easily get by induction on $n$ that

$$
\begin{equation*}
\left|y^{*}-y_{n}\right| \leq L^{n}(a)-L^{n}(0) \rightarrow 0 \text { as } n \rightarrow \infty . \tag{38}
\end{equation*}
$$

That is $y_{n} \rightarrow y^{*}$ as $n \rightarrow \infty$. However, we have shown $y_{n} \rightarrow x^{*}$ as $n \rightarrow \infty$.
Hence we deduce:

$$
x^{*}=y^{*} .
$$

That completes the proof of the theorem.
Remark 9. As in [1], [2, [5, [6] we note that from the proof of Theorem 8 we have the error bound

$$
\left|x^{*}-x_{n}\right| \leq b^{*}-\bar{d}_{n} \leq q-\bar{d}_{n},
$$

where for $q$ we may use any solution of $L(q) \leq q$. We can obtain better a posteriori error estimates if we use instead the solutions of $R_{n}(q) \leq q$ with monotone operators $R_{n}$.

Under the hypotheses of Theorem 8 define:

$$
R_{n}(q)=\left(I-L_{0}^{\prime}\left(\left|x_{n}\right|\right)\right)^{*} S_{n}(q)+c_{n}
$$

where

$$
S_{n}(q)=L\left(\left|x_{n}\right|+q\right)-L\left(\left|x_{n}\right|\right)-L_{0}^{\prime}\left(\left|x_{n}\right|\right) q .
$$

Operator $S_{n}$ is monotone on interval $I_{n}=\left[0, a-\left|x_{n}\right|\right]$. If there exists a $q_{n} \in C$ such that $\left|x_{n}\right|+q_{n} \leq n$, and

$$
S_{n}\left(q_{n}\right)+L_{0}^{\prime}\left(\left|x_{n}\right|\right)\left(q_{n}-c_{n}\right) \leq q_{n}-c_{n},
$$

then $R_{n}:\left[0, q_{n}\right] \rightarrow\left[0, q_{n}\right]$ is well defined and monotone. A reasonable choice for $q_{n}$ is $a-\bar{d}_{n}$, since

$$
\begin{aligned}
\bar{d}_{n}+c_{n} & \leq \bar{d}_{n+1} \Rightarrow L(a)-L\left(\bar{d}_{n}\right)-L_{0}^{\prime}\left(\left|x_{n}\right|\right) c_{n} \leq a-\bar{d}_{n}-c_{n} \\
& \Rightarrow S_{n}\left(a-\bar{d}_{n}\right)+L_{0}^{\prime}\left(\left|x_{n}\right|\right)\left(a-\bar{d}_{n}-c_{n}\right) \leq a-\bar{d}_{n}-c_{n} .
\end{aligned}
$$

Other ways of choosing a suitable $q_{n}$ are given in the Lemmas that follows:
Lemma 10. Let $q \in I_{n}$ satisfy $R_{n}(q) \leq q$. Then

$$
c_{n} \leq R_{n}(q)=r \leq q
$$

and

$$
R_{n+1}\left(r-c_{n}\right) \leq r-c_{n}
$$

Proof. Element $r-c_{n}$ satisfies

$$
S_{n}(q)+L_{0}^{\prime}\left(\left|x_{n}\right|\right)\left(r-c_{n}\right)=r-c_{n} .
$$

Therefore, we have

$$
S_{n+1}\left(r-c_{n}\right)+\left|-F\left(x_{n+1}\right)\right|+L_{0}^{\prime}\left(\left|x_{n+1}\right|\right)\left(r-c_{n}\right) \leq r-c_{n} .
$$

That completes the proof of the Lemma.
Lemma 11. Assume:

- conditions of Theorem 1 hold;
- there exists a solution $q_{n} \in I_{n}$ of $R_{n}(q) \leq q$.

Then for

$$
a_{n}=q_{n} \quad a_{m+1}=R_{m}\left(a_{m}\right)-c_{m} \quad(m \geq n)
$$

we have

$$
\left|x^{*}-x_{m}\right| \leq a_{m}
$$

Proof. Using induction we immediately have

$$
R_{m}\left(a_{m}\right) \leq a_{m}
$$

That is

$$
a_{m+1}+c_{m} \leq a_{m}
$$

which implies the monotonicity of

$$
\left(x_{m}, a_{n}-a_{m}\right) \text { in } X \times V
$$

That completes the proof of the Lemma.
The properties of $R_{n}$ imply the existence of $R_{n}^{\infty}(0)$ which is a reasonable choice for $q_{n}$ in the Lemma above.

Hence we have:
Lemma 12. Assume conditions of Theorem 1 hold.
Then any solution $q \in I_{n}$ of $R_{n}(q) \leq q$ implies the a posteriori estimate

$$
\left|x^{*}-x_{n}\right| \leq R_{n}^{\infty}(0) \leq q .
$$

As suggested in [1], [2, [5], [6] in precise we may want to use a monotone operator satisfying

$$
P_{n}(q) \leq q \Rightarrow R_{n}(q) \leq q,
$$

where

$$
P_{n}(q)=L\left(\left|x_{n-1}\right|+c_{n-1}+q\right)-L\left(\left|x_{n-1}\right|\right)-L_{0}^{\prime}\left(\left|x_{n-1}\right|\right) c_{n-1}
$$

REmark 13. (a) If $L_{0}=L$ then our Theorem 8 and Lemmas $10-12$ reduce to the corresponding ones in 6. However, if strict inequality holds in (16) or $(17)$, then the error bounds on the distances $\left|x^{*}-x_{n}\right|$ are finer and the information on the location of the solution $x^{*}$ more precise. (since $\bar{d}_{n} \leq d_{n}$ and $\left.b^{*} \leq b\right)$. Note that these improvements are made under the same hypotheses as in [6] (since practically the computation of operator $L$ requires that of $L_{0}$ ).
(b) One hopes that in general we can find conditions weaker than say (18) since the convergence of (20) (and not (21), which depends on (18)) suffices for the existence of $x^{*}\left(\right.$ in $\left.\vec{U}\left(b^{*}\right)\right)$.

As an example we consider the case of a Banach space with a real norm denoted by $\|\cdot\|$. To check the conditions of the theorem, assume $F^{\prime}(0)=I$ and that the Fréchet-derivative $F^{\prime}$ of operator $F$ can be estimated by some monotone operator $\ell:[0, a] \rightarrow R$ such that

$$
\left\|F^{\prime}(x)-F^{\prime}(y)\right\| \leq \ell(\|x-y\|)\|x-y\| \text { for all } x, y \in U(a) .
$$

Moreover define

$$
L(q)=\|F(0)\|+\int_{0}^{q} \mathrm{~d} s \int_{0}^{s} \mathrm{~d} t \ell(t) .
$$

Set $\ell(t) \leq \ell(a)=\ell_{1} \geq 0$. Then crucial convergence condition (18) holds if

$$
\|F(0)\|+\frac{1}{2} \ell_{1} a^{2} \leq a
$$

or if

$$
\begin{equation*}
h_{K}=2 \ell_{1}\|F(0)\| \leq 1, \tag{39}
\end{equation*}
$$

which is the famous Newton-Kantorovich condition that guarantees the semilocal convergence of Newton's method to $x^{*}$ [3], [4], [8].

To show that sequence (20) converges under weaker conditions than (39) in this case, assume there exists a monotone operator $p:[0, a] \rightarrow R$ such that

$$
\left\|F^{\prime}(x)-F^{\prime}(0)\right\| \leq p_{1}(\|x\|)\|x\| \text { for all } x \in U(a)
$$

Set $p(t) \leq p(a)=p_{1}$, and define

$$
L_{0}(q)=\|F(0)\|+\int_{0}^{q} \mathrm{~d} s \int_{0}^{s} \mathrm{~d} t p(t)
$$

Then it can easily be seen that sequence 20 converges, provided that

$$
\begin{equation*}
h_{A}=\left(p_{1}+\frac{\ell_{1}}{2}\right)\|F(0)\| \leq 1 \tag{40}
\end{equation*}
$$

which is weaker than 39 . Note also that

$$
p_{1} \leq \ell_{1}
$$

holds in general and that $\frac{\ell_{1}}{p_{1}}$ can be arbitrarily large [3].
Hence, the above justify the claims made at the introduction and in the Remark above.

## REFERENCES

[1] Argyros, I. K., Newton methods on Banach spaces with on convergence structure and applications, computers and Mathematics with Applications, 40, 1, pp. 37-48, 2000.
[2] Argyros, I. K., Advances in the efficiency of computational methods and applications, World Scientific Publ. Co. River Edge, New Jersey, 2000.
[3] Argyros, I. K., An improved error analysis for Newton-like methods under generalized conditions, J. Comput. Appl. Math. 157, 1, pp. 169-185, 2003.
[4] Kantorovich, L. V., and Akilov, G. P., Functional Analysis in normed spaces, Pergamon Press, Oxford, 1982.
[5] Meyer, P. W., Newton's method in generalized Banach spaces, Numer. Funct. Anal. and Optimiz. 9, pp. 249-259, 1987.
[6] Meyer, P. W., A unifying theorem on Newton's method, Numer. Funct. Anal. and Optimiz., 13, (5 and 6), pp. 463-473, 1992.
[7] VANDERGRAFT, J. A., Newton's method for convex operators in partially ordered spaces, SIAM J. Numer. Anal. 4, pp. 406-432, 1967.
[8] Yamamoto, J., A unified derivation of several error bounds for Newton's process, J. Comput. Appl. Math. 12 and 13, pp. 179-191, 1985.

Received by the editors: February 3, 2005.


[^0]:    *Department of Mathematical Sciences, Cameron University, Lawton, OK 73505, USA, e-mail: ioannisa@cameron.edu.

