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TOPOLOGICAL TRANSVERSALITY, PERTURBATION THEOREMS AND SECOND ORDER DIFFERENTIAL EQUATIONS

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- 1. Abstract. The topological transversality theorem for condensing mappings stated in [7] is used to prove some perturbation theorems: a theorem on Y-condensing perturbations of hyperaccretive mappings and a Browder type result on the perturbation of some bijective mappings by Y -Lipschitz mappings. An application concerning the existence and the uniqueness of solution to a boundary value problem for nonlinear second order differtial equations in Banach spaces is finally given.
- 2. Preliminaries. Let I be a real Banach space, I its dual. Denote both the norm in I and its dual norm in I' by [.]. The value of $x^{\mathbb{R}} \in X^{\mathbb{R}}$ at $x \in X$ is denoted by $(x^{\mathbb{R}}, x)$. In case X = R the bilinear functional (.,.) stands for the scalar product.

Let \mathcal{F} be the duality mapping of I, i.e. $\mathcal{F}: I \longrightarrow 2^{I}$, $\mathcal{F}_{x} = \left\{ x^{x} \in X^{x} : (x^{x}, x) = |x|^{2} = |x^{x}|^{2} \right\}$ and let $(.,.)_{+}$ be the semi-inner product on I defined by

 $(x,y)_{+} = |y| \lim_{t \to 0} t^{-1}(|y+tx|-|y|), \text{ the stands}$

or equivalently $(x,y)_{+} = \sup \{(y^{H},x) : y^{H} \in \mathcal{F}y \}$.

A mapping $F: D \to 2^{\mathbb{Z}} \setminus \{\emptyset\}$, $D \subset \mathbb{X}$, is said to be accretive if $(y_1-y_2,x_1-x_2)_+ \geqslant 0$ for all $x_1,x_2 \in \mathbb{D}$, $y_1 \in \mathbb{F}x_1$ and $y_2 \in \mathbb{F}x_2$. An accretive mapping F is said to be hyperaccretive if I+sF is onto \mathbb{X} for some (equivalently for all) s>0. Recall that if F is hyperaccretive then the mapping $R_g=(I+sF)^{-1}:\mathbb{X} \longrightarrow D$ is nonexpansive for each s>0 and $R_gx \longrightarrow x$ as $s \nmid 0$ for all $x \in \overline{D}$ (see [3], pp.126).

Let γ denote α or β . Kuratowski's or the ball measure of noncompactness; for each bounded subset B of a metric space one has

 $\mathcal{A}(B)=\inf\{d>0:B \text{ admits a finite cover by sets of diameter } \leq d\}$ and

 $\beta(B)=\inf\{r>0:B$ can be covered by finitely many balls of radius $r\}$ Clearly, $\beta(B)\leqslant \alpha(B)\leqslant 2\beta(B)$.

A continuous mapping $F: Y \to X$ (Y being a metric space) is called Y-Lipschitz if $Y(F(B)) \leqslant k \ Y(B)$ for some $k \geqslant 0$ and all bounded BCY. We write k-Y-Lipschitz if k is important. F is said to be Y-condensing if Y(F(B)) < Y(B) whenever BCY is bounded and Y(B) > 0.

Let J = [0,1]. Denote by C the real Banach space C(J;X) with the norm $\|u\| = \max\{\|u(t)\|: t \in J\}$ and by C^n $(n \ge 1)$ the space $C^n(J;X)$ endowed with the norm $\|u\|_{n=\max}\{\|u^{(1)}\|: i=0,\ldots,n\}$

We shall denote by V_n and simply by V, the corresponding measure of noncompactness on the space C^n , respectively on C. If $B \subset C$ is bounded and equicontinuous, then

 $\alpha(B) = \sup \{ \alpha(B(t)) : t \in J \},$

where $B(t) = \{u(t): u \in B\}$ (see[3], Proposition 7.3 (a)).

3. The topological transversality theorem for Y-condensing mappings

Let X be a real Banach space, K a closed convex subset of X and let $U \subset K$ be bounded and open in K. Denote by \overline{U} and \mathcal{U} the closure and the boundary of U in K. Let $\mathcal{H}_{\mathcal{U}}(\overline{U};K)$ be the set of all Y-condensing mappings $F:\overline{U} \to K$ with $x \not\in Fx$ for any $x \in \mathcal{U}$. The elements of $\mathcal{H}_{\mathcal{U}}(\overline{U};K)$ are called admissible. A mapping $F \in \mathcal{H}_{\mathcal{U}}(\overline{U};K)$ is said to be essential if any admissible mapping G which coincides with F on \mathcal{U} , has a fixed point. An admissible mapping which is not essential is called inessential.

Proposition 3.1. The constant mapping $P: \overline{U} \longrightarrow K$, $Px = x_0$ for all $x \in \overline{U}$, where $x_1 \in U$, is essential.

Two admissible mappings P_0 and P_1 are said to be homotopic if there exists $H: JX\overline{U} \to K$ such that $H(s,.) \in \mathcal{A}_{JU}(\overline{U};K)$ for all $s \in J$, $H(0,.) = P_0$, $H(1,.) = P_1$ and $\{H(.,x):x \in \overline{U}\}$ is equicontinuous.

Theorem 3.2. Two homotopic admissible mappings are both essential er both inessential.

The proofs of Proposition 3.1 and Theorem 3.2 can be found in [7]. They reproduce with some specifical changes those of the similar results on completely continuous mappings (see [4]).

4. Perturbation theorems. We will present two applications of Theorem 3.2.

Theorem 4.1. Let I be a real Banach space, $T: D \longrightarrow 2^{\mathbb{Z}} \setminus \{\emptyset\}_0$, DCI, a hyperaccretive mapping, UCI open bounded with UCD and S: U \longrightarrow I Y-condensing. If $x - x_0 \notin s(Sx-Tx-x_0)$ for some $x_0 \in U$ and all $s \in [0,1]$, $x \in \mathcal{J}U$, then there exists $x \in U$ such that $x \in (S-T)x$.

<u>Proof.</u> We shall apply Theorem 3.2. to $P_0, P_1 : \overline{U} \rightarrow X$, $P_0 = X_0$

 $F_1 = (I+T)^{-1}S$. To this end, define $H: J \times \overline{U} \longrightarrow X$, $H(s,x) = R_s((1-s)x_0+sSx)$. Since S is γ -condensing and R_s is nonexpansive, $H(s,\cdot)$ is γ -condensing too. Also, the hypothesis on ∂U guaranties that $x \neq H(s,x)$ for all $s \in J$ and $x \in \partial U$. Hence, $H(s,\cdot) \in \mathcal{H}_{\partial U}(\overline{U}; X)$ for all $s \in J$. It remains only to show that $\{H(\cdot,x): x \in \overline{U}\}$ is equicontinuous at each $s_0 \in J$. For $s_0 = 0$ this follows from

$$|H(s,x) - x_0| \le |R_s((1-s)x_0+sSx) - R_sx_0| +$$

+ $|R_sx_0-x_0| \le s|Sx-x_0| + |R_sx_0-x_0|$,

because $S(\overline{U})$ is bounded and $R_s x_0 \longrightarrow x_0$ as $s \nmid 0$. Now let $s_0 \in]0,1]$. At the beginning we show that $\{(I+(.)T)^{-1}x:x \in B\}$ is equicontinuous at s_0 whenever $B \subset X$ is bounded. Indeed, since

 $\frac{1}{s} (x-R_s x) \in TR_s x \text{ for any } s \in]0,1], \text{ we have}$

$$0 \le (\frac{1}{s}(x-R_sx) - \frac{1}{s_o}(x-R_{s_o}x), R_sx-R_{s_o}x)_+ =$$

$$= ((\frac{1}{s} - \frac{1}{s_0})(x - R_{s_0}x) - \frac{1}{s}(R_sx - R_{s_0}x), R_sx - R_{s_0}x)_{+} =$$

$$= ((\frac{1}{s} - \frac{1}{s_o})(x - R_{s_o}x), R_sx - R_{s_o}x) + -\frac{1}{s} |R_sx - R_{s_o}x|^2.$$

It follows that $|R_s x - R_s x| \le \frac{1}{s_o} |s - s_o| |x - R_s x|$, whence the

equicentinuity of $\{(I+(.)T)^{-1}x:x\in B\}$ at so is immediate because B and $R_{s_0}(B)$ are bounded. Now, from

 $\|H(s,x)-H(s_0,x)\| \le \|R_s((1-s)x_0+sSx)-R_s\|((1-s)x_0+sSx)\| + \|R_s\|((1-s)x_0+sSx)\| + \|R_s\|(1-s)x_0+sSx\| + \|R_s\|(1-s)x_0+sSx\| + \|R_s\|(1-s)x_0+sSx\| + \|R_s\|(1-s)x_0+sSx\| + \|R_s\|(1-s)x_0$

$$\leq |R_s((1-s)x_0+sSx)-R_s((1-s)x_0+sSx)|+|s-s_0||x_0-Sx||$$

using the boundedness of $S(\overline{U})$ and the equicontinuity just proved for $B = conv(\{x_0\} \cup S(\overline{U}))$, we may infer that $\{H(.,x): x \in \overline{U}\}$ is equicontinuous at s_0 , as desired. Thus, F_0 and F_1 are hometopic and since by Proposition 5.1 F_0 is essential, it fellows by Theorem 5.2 that F_1 is also essential. Consequently, F_1 has a fixed point $x \in U$, that is $x \in (S-T)x$.

Theorem 4.2. Let X be a real Banach space, Y a metric space, T: $Y \longrightarrow X$ and S: $Y \longrightarrow X$ two mappings such that the following conditions are satisfied:

- (i) S is Y-Lipschitz;
- (ii) T maps bounded sets into bounded sets;
- (iii) For each $s \in J$, $T_s = T-sS$ is injective, T_s^{-1} is continuous on its domain and there exists $c_s > 0$ such that

whenever BCY is bounded;

(iv) $\{T_s^{-1}x : s \in J\}$ is bounded for each $x \in X$.

Them, if T is surjective, T-S is surjective too.

Proof. At the beginning we will show that the constant e_s in (1) may be considered independent on s. To this end, let $s_0 \in J$ be arbitrar, $s \in J$ and e_s the greatest constant for which (1) helds. Let BCY be bounded. If $\mathcal{E} > \mathcal{L}(T_s(B))$, then B can be covered by finitely many subsets B_1^1 such that diam $T_s(B_1^1) \leq \mathcal{E}$ and, on the other hand, by (1), $\mathcal{L}(B) < \mathcal{E}/(2e_s)$. Then, S being $\mathcal{L}(S(B)) \leq 2k\mathcal{L}(B) < k\mathcal{E}/e_s$. It follows that B also admits a finite cover by subsets B_1^2 with

diam $S(B_j^2) \le k \epsilon / e_s$. Now, for $y_1, y_2 \in B_1^1 \cap B_j^2$ one has $|T_s, y_1 - T_s, y_2| \le |T_s y_1 - T_s y_2| + |s - s_0| |Sy_1 - Sy_2| \le$

Thus, the sets $T_s(B_i^1 \cap B_j^2)$ represent a finite cover of $T_s(B)$ of diameter $\leqslant \mathcal{E}(1+|s-s_0|k/c_s)$ and so

Letting & d(Ta(B)) we obtain

$$e_{s_{\bullet}} V(B) \le \alpha (T_{s_{\bullet}}(B)) \le \alpha (T_{s}(B)) (1 + |s-s_{\bullet}| k/c_{s}),$$

whence $c_s \le 2c_s(1+|s-s_s|k/c_s)$, that is $c_s \le 2c_s+2k|s-s_s|$, which clearly shows that c_s are upper bounded by a number c>0, as desired.

Next, suppose that for a certain s < 1, T_s is surjective (equivalently, bijective). Define $F_t = (T_s - T_t)T_s^{-1}: X \longrightarrow X$ for $s \le t \le 1$. We have $F_t = (t-s)ST_s^{-1}$ whence, by the continuity of S and T_s^{-1} , F_t is continuous. Now, let k > 0 be such that S is k-y-Lipschitz. If $B \subset X$ is bounded, then by (1) we have

$$Y(P_t(B)) = (t-s) Y(ST_s^{-1}(B)) \le (t-s)k Y(T_s^{-1}(B)) \le (t-s) \frac{k}{e} \cdot Y(B).$$

This implies that F_t is γ -condensing whenever $s \leqslant t < s + \frac{e}{k}$, $t \leqslant l$. Let $y \in X$ be fixed arbitrary and put $G_t = F_t + y$. Clearly, G_t is γ -condensing for $s \leqslant t < s + \frac{e}{k}$, $t \leqslant l$. We will prove that the set of fixed points of the mappings

 G_t , $s \le t < s + \frac{e}{k}$, $t \le 1$, is bounded. Indeed, if $x \in Fix(G_t)$,

then $x = F_t x + y$ or equivalently, $x = x - T_t T_s^{-1} x + y$. Hence $T_s^{-1} x = T_t^{-1} y$, whence by (iv), the set

 $\left\{T_s^{-1}x:x\in Fix(G_t), s\leq t < s+\frac{c}{k}, t\leq 1\right\}$ is bounded. Since, by

(i) and (ii) T_s maps bounded sets into bounded sets, this implies that $\{x: x \in Fix(G_t), s \le t < s + \frac{e}{t}, t \le l \}$ is also bounded,

as elaimed. Let r>0 be such that |x|< r whenever $x \in Fix(G_t)$, $s \le t < s + \frac{e}{k}$, $t \le 1$ and put $U = \{x \in X : |x| < r\}$. For each $t \le 1$ satisfying $s \le t < s + \frac{e}{k}$, define

 $H: J \times \overline{U} \longrightarrow X$, $H(\lambda, x) = G_{\{1-\lambda\}s+\lambda t} X$.

It is easy to see that $H(0,.)=G_g\equiv y$ and $H(1,.)=G_t$, as mappings from U to X, are homotopic and since $G_g\equiv y$ is essential, because $y\in U$, G_t will be essential too. Thus, there is $x_y\in U$ such that $x_y=G_tx_y$, i.e. $y=T_tT_s^{-1}x_y$. Since y was arbitrary fixed in X, we get that T_t is surjective for any t satisfying $s\leqslant t\leqslant s+\frac{s}{t}$, $t\leqslant 1$. Now it is clear that if $T_0=T$ is surjective, then after a finite number of steps, it follows that $T_1=T_t$ is also surjective.

Remark 4.1. In particular, conditions (i)-(iv) in Theorem 4.2 are satisfied if T and S are Lipschitz and there exists e>C such that $ed(x,y) \le |T_x x - T_y|$ for all $x,y \in Y$ and $s \in J$. Indeed, in this case, conditions (i)-(iii) clearly hold. To prove (iv), let $x \in X$. We fix $s_0 \in J$ such that $T_{s_0}^{-1} x \neq \emptyset$ and we put

 $y_s = T_s^{-1}x$ whenever for some $s \in J$ one has $T_s^{-1}x \neq \emptyset$. Since $0 = |T_sy_s - T_sy_s| > |T_sy_s - T_sy_s| - |T_sy_s - |T_sy_s|$, we get

ed(ys,ys,) < | Tsys-Tsys, | < | Tsys, -Ts, ys, | =

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=| s-s | | Sy | | < | Sy | 1,

for each $s \in J$ with $T_s^{-1}x \neq \emptyset$. Hence $\{T_s^{-1}x : s \in J\}$ is bounded.

In this special case Theorem 4.2 reduces to a result of F.B. Browder [2].

Remark 4.2. An other consequence of Theorem 4.2 is the following hyperaccretivity criterion: If X is a real Banach space and F: X - X is accretive and Y-Lipschitz, then F is hyperaccretive. For the proof it is sufficient to take T = I, the identity of X, and S = -F and to apply Theorem 4.2. This result can also be derived from a more general hyperaccretivity criterion due to V. Barbu [1], Corollary 3.3.2.

Remark 4.5. A topological transversality theorem for <u>multivalue</u> y -condensing mappings T, having Tx closed convex for all x, can be proved similarly. It can be used instead of the degree theory, to prove certain other perturbation theorems as, for instance, some results of J.R.L. Webb [11].

5. Application. We will study the existence, and the uniqueness of the solution to the problem

(2)
$$u^{*}(t)+p(t)u^{*}(t) = f(t,u(t))+g(t), t \in J$$

(3)
$$u(0) = a, u(1) = b$$

in a real Banach space I, where $p \in C(J; \mathbb{R})$, $g \in C(J; \mathbb{X})$, $f \in C(J \times \mathbb{X}; \mathbb{X})$ and $a, b \in \mathbb{X}$. We look for solutions in \mathbb{C}^2 .

Let $C_b^2 = \{ u \in C^2 : u(0) = a, u(1) = b \}$. Clearly, C_b^2 is a closed convex subset of C_b^2 .

Theorem 5.1. Assume

- (a) f is uniformly continuous on J × B fer any bounded B⊂X;
- (b) There exists k≥0 such that
- (4) $\gamma(f(t,B)) \leq k \gamma(B)$, for any bounded BCX;
 - (e) There exists c>0 such that

(5)
$$(f(t,x_1)-f(t,x_2), x_1-x_2)_+ \ge e|x_1-x_2|^2$$

for all x1,x2 EX and teJ.

Then (2)-(5) has exactly one solution $u \in \mathbb{C}^2$.

<u>Proof.</u> We shall apply Theorem 4.2 with C = C(J;X) instead of X and $Y = C_b^2$ to the mappings T = L, $L : C_b^2 \longrightarrow C$, $(Lu)(t) = u^*(t) + p(t)u^*(t)$ and

 $S = F, F : C_b^2 \longrightarrow C, (Fu)(t) = f(t,u(t)).$

- 1) We will prove that F is Y-Lipschitz. At the beginning we show that
- (6) $V(f(J \times B)) \le k V(B)$ for all bounded $B \subset X$. Indeed, for $\varepsilon > 0$ arbitrary fixed, by (a), we have that for each $\overline{t} \in J$ there is a neighbourhood $V(\overline{t}, \varepsilon)$ of \overline{t} such that

 $|f(t,x)-f(\bar{t},x)| < \varepsilon$ for all $t \in V(\bar{t},\varepsilon)$ and $x \in B$. In consequence

γ(f(∇(₹,ε) × B)) ≤ γ(f(₹,B))+2ε,

whence, taking into account (4) and the compactness of J, we get

Y(f(J×B)) ≤ k Y(B)+2 € (2) (2) (2) (2)

New (6) fellows if we take $\varepsilon \rightarrow 0$.

The continuity of F follows by the continuity of f. Now let $D \subset C_b^2$ be bounded. From (6), taking B = D(J), we see that F(D) is bounded. On the other hand, since D is bounded in C2, it fellows that D is equicentinuous. Hence, $c(D) = \sup \{c(D(t)) : t \in J\}$. Also, the equicentinuity of D tegether with the uniform continuity of f, implies that F(D)

$$\mathscr{L}(F(D)) = \sup \{ \mathscr{L}(F(D)(t)) : t \in J \}.$$

Inasmuch as by (4),

is equicontinuous too and so

$$\angle(F(D)(t)) = \angle(f(t,D(t))) \le 2 \ \gamma(f(t,D(t))) \le$$

$$\le 2k \ \gamma(D(t)) \le 2k \ \angle(D(t)) \le 2k \ \angle(D)$$

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whence all the more

 $\gamma(F(D)) \leq 4k \gamma(D)$. Finally, since $\gamma(D) \leq \gamma_2(D)$,

 $\gamma(F(D)) \leq 4k \gamma_2(D)$ for all bounded $D \subset C_b^2$, (8)

which shows that F is Y-Lipschitz.

- 2) Obviously L maps bounded subsets of Cb into bounded sets of C.
- 5) T = L-sF(s ∈ J) is injective. This being clear for s = 0 we may assume s>0. Let $T_su = T_sv$ where $u, v \in C_b^2$. Let $t_s \in J$ such that $|u(t_0)-v(t_0)| = \max\{|u(t)-v(t)|: t \in J\}$. We may suppose that $t_0 \in]0,1[$ because u(0)-v(0) = u(1)-v(1) = 0. Then $(x^{\Xi}, u'(t_a) - v'(t_a)) = 0$ and $(x^{\Xi}, u''(t_a) - v''(t_a)) \le 0$ for every $x^{x} \in \mathcal{F}(u(t_{a})-v(t_{a}))$. Consequently, since

 $u^{*}(t)-v^{*}(t)+p(t)(u^{*}(t)-v^{*}(t)) = s(f(t,u(t))-f(t,v(t))),$ we get

- $0 \geqslant (f(t_0, u(t_0)) f(t_0, v(t_0)), u(t_0) v(t_0))_+, \text{ whence, by (5)}$ $u(t_0) v(t_0) = 0, \text{ that is } u = v.$
- 4) The fellowing step is to prove that for each $s \in J$ there we exists $c_s > 0$ such that

(9)
$$e_s Y_2(T_s^{-1}(B)) \leq Y(B)$$
 for any bounded BCC.

Such an inequality clearly holds for s=0 because $T_0=L:C_0^2\to C$ is linear bounded and bijective. Hence we may assume s>0. Let $B\subset C$ be bounded and let $\ell>\kappa(B)$ be arbitraryly fixed. Then B admits a finite cover by subsets Bj of diameter $\ell\in E$. We have only to prove that each set $T_s^{-1}(B_j)$ can be convered by finitely many subsets $B_{j\ell}$ of diam $_2B_{j\ell} < \ell/(2\ell_8)$, ℓ_8 being a constant independent of B,ℓ,j and ℓ (we have denoted by diam $_2$ the diameter with respect to the norm $\|\cdot\|_2$):

4a) Let $g_i \in B_j$ and $u_i = T_0^{-1}g_i$, i=1,2 with $g_1 \neq g_2$.

Consider $t_0 \in]0,1[$ such that $||u_1-u_2|| = |u_1(t_0)-u_2(t_0)|$ (>0).

From

(le)
$$u_1^n(t)-u_2^n(t)+p(t)(u_1^*(t)-u_2^*(t))=s(f(t,u_1(t))-f(t,u_2(t)))+ +g_1(t)-g_2(t)$$

we deduce

$$\begin{split} s(\mathbf{x}^{\Xi}, f(t_0, \mathbf{u}_1(t_0)) - f(t_0, \mathbf{u}_2(t_0))) + (\mathbf{x}^{\Xi}, \mathbf{g}_1(t_0) - \mathbf{g}_2(t_0)) \leqslant 0 \\ \text{for all } \mathbf{x}^{\Xi} \in \mathcal{F}(\mathbf{u}_1(t_0) - \mathbf{u}_2(t_0)). \quad \text{Since } \|\mathbf{g}_1 - \mathbf{g}_2\| \leqslant \varepsilon, \quad \text{by (5) this yields} \end{split}$$

4b) Applying (7) to $D = T_8^{-1}(B_j)$ and taking into account (11)

we may infer that $T_8^{-1}(B_j)$ can be represented as an union of finitely many subsets $B_{j\ell}$ such that diam $F(B_{j\ell}) \le 2k \mathcal{E}/(sc) + \mathcal{E}$.

In the following we shall fix our attention to some subset B_{ij} .

In the following we shall fix our attention to some subset B_{jl} . Suppose that $u_1, u_2 \in B_{jl}$.

Then $|f(t,u_1(t))-f(t,u_2(t))| \le 2k \varepsilon/(sc) + \varepsilon$ for all $t \in J$ and by (10) and (11) we get

where $M_p = \max\{|p(t)|: t \in J\}$.

4e) u_1 and u_2 being as in 4b) denote $v = u_1 - u_2$ and $q = ||v'|| = ||v'|(t_0)||$, where $t_0 \in J$. Let μ be such that $|\mu| \le 1/2$ and $t_0 + \mu \in J$ and put $\delta = |\mu|$. Using Taylor's formula

$$\nabla (t_0 + \mu) = \nabla (t_0) + \mu \nabla' (t_0) + \frac{\mu^2}{2} \nabla'' (t_0 + 0\mu)$$
 for some $\theta \in J$,

by (11) and (12) one deduces

(13)
$$\delta q \leq 2 \mathcal{E} / (sc) + \beta(q) \delta^2 / 2$$
,

where $\beta(q) = M_p q + 2k \varepsilon / c + 2\varepsilon$. It is easy to see that

 $\xi^2/\beta(\xi) > 4 \mathcal{E}/(sc)$ for all $\xi > \mathcal{E}Q$, where Q is some nonnegative constant independent of \mathcal{E} . Assume $q > \mathcal{E}Q$. Then

 $\mathfrak{S}(q) < q^2 \operatorname{se}/(4\varepsilon)$ and by (13) one has

$$q < \frac{2\varepsilon}{se} \cdot \frac{1}{\delta} + \frac{q^2 se}{8\varepsilon} \delta$$

This implies that $4\mathcal{E}/(\sec q) \ge 1/2$ or equivalently, $q \le 8\mathcal{E}/(\sec q)$. Indeed, if $4\mathcal{E}/(\sec q) < 1/2$, choosing $\delta = 4\mathcal{E}/(\sec q)$ in (14), one obtains q < q/2+q/2, a contradiction. Thus, if $q > \mathcal{E}Q$ then $q \le 8\mathcal{E}/(\sec q)$. Therefore,

(15) || ui-ui|| < mar | 50 | 8 5 // and

By (11), (12) and (15), $\dim_2 B_{j\ell} \leq \mathcal{E}/(2c_g)$, where $1/(2c_g) = \max\{Q,8/(se), M_{p}\max\{Q,8/(se)\} + 4k/e+2\}, \text{ as desired.}$

- 5) For each $s \in J$, T_s^{-1} is continuous. To show this, let $g_n \xrightarrow{C} g^{\mathbb{Z}}$ as $n \to \infty$ and $u_n = T_s^{-1} g_n$. Since $f(\{g_n : n \geqslant 1\}) = 0$, by (9) the sequence (u_n) contains a subsequence which converges is C^2 to some $u^{\mathbb{Z}}$. By $g_n = T_s u_n$ and the continuity of T_s , we obtain $g^{\mathbb{Z}} = T_s u_n^{\mathbb{Z}}$, i.e. $u^{\mathbb{Z}} = T_s^{-1} g^{\mathbb{Z}}$, whence it follows that even the entire sequence (u_n) converges to $T_s^{-1} g^{\mathbb{Z}}$.
- 6) Condition (iv) in Theorem 4.2 is satisfied if for each $g \in C$ the set of all solutions $u \in C_b^2$ to

(16)
$$u^{n}+p(t)u^{n} = sf(t,u)+g(t)$$

for $s \in J$, is bounded in C^2 . Let $u_s \in C_b^2$ a solution to (16) and $u_o \in C_b^2$ the solution to (16) in case s = 0. Denote $v_s = u_s - u_o$. Then

$$v_8^n + p(t)v_8^t = sf(t, u_0(t) + v_8)$$
.

Thus, were have to prove the a priori boundedness of the set of all solutions $v \in \mathbb{C}^2$ satisfying

(17)
$$v''+p(t)v' = sf(t,u_0(t)+v)$$

and v(0) = v(1) = 0, for $s \in J$. But this follows by Lemmas 4 and 5 in [8] because, by (5) we have

$$(f(t,u_0(t)+x),x)_+ \ge -(-f(t,u_0(t)),x)_+ + e|x|^2 \ge$$

> elx|2-||f(.,uo(.))|||x|>0,

for |x|>||f(.,uo(.))||/c, which means that condition (iii) of

Thus, all the assumptions of Theorem 4.2 are satisfied. Therefore, since L is surjective, L-F is surjective too (even bijective), which shows that (2),(3) has exactly one solution $u \in \mathbb{C}^2$ for each $g \in \mathbb{C}$.

Remark 5.1. The existence of solutions to (2),(5) also follows from our paper [8], by using directly the topological transversality theorem and the a priori bounds technique, but under the additional assumption that k in (4) be sufficiently small. Thus, the advantage of using the perturbation Theorem 4.2 in case of equation (2), consists in the fact that k in (4) may be arbitrar.

Remark 5.2. Conditions (a) and (b) in Theorem 5.1 are, in particular, satisfied if f is completely continuous or if $f = f_1 + f_2$ where f_1 is completely continuous and f_2 is Lipschits.

Remark 5.3. In particular, if $X = \mathbb{R}^n$ the assumptions of . Theorem 5.1 reduce to: $f: J \times \mathbb{R}^n \longrightarrow \mathbb{R}^n$ continuous and $(f(t,x_1)-f(t,x_2),x_1-x_2) \geqslant e\|x_1-x_2\|^2$ for all $x_1,x_2 \in \mathbb{R}^n, t \in J$. In this case the existence and the uniqueness of solution to (2), (3) follows from [5], Theorem II 3.3, Theorem V 2.2.

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This paper is in final form and no version of it will be submitted for publication elsewhere.

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